

datasheet

PRELIMINARY SPECIFICATION

1/4" color CMOS QXGA (5 megapixel) image sensor
with OmniBSI™ technology

OV5640

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color CMOS QSXGA (5 megapixel) image sensor with OmniBSI™ technology

datasheet (CSP3)
PRELIMINARY SPECIFICATION

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color CMOS QXGA (5 megapixel) image sensor with OmniBSI™ technology

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applications

- cellular phones
- toys
- PC multimedia
- digital still cameras

ordering information

- **OV05640-A71A** (color, lead-free)
71-pin CSP3

features

- 1.4 μm x 1.4 μm pixel with OmniBSI technology for high performance (high sensitivity, low crosstalk, low noise, improved quantum efficiency)
- optical size of 1/4"
- automatic image control functions: automatic exposure control (AEC), automatic white balance (AWB), automatic band filter (ABF), automatic 50/60 Hz luminance detection, and automatic black level calibration (ABLC)
- programmable controls for frame rate, AEC/AGC 16-zone size/position/weight control, mirror and flip, cropping, windowing, and panning
- image quality controls: color saturation, hue, gamma, sharpness (edge enhancement), lens correction, defective pixel canceling, and noise canceling
- support for output formats: RAW RGB, RGB565/555/444, CCIR656, YUV422/420, YCbCr422, and compression
- support for video or snapshot operations
- support for LED and flash strobe mode
- support for internal and external frame synchronization for frame exposure mode
- support for horizontal and vertical sub-sampling, binning
- support for minimizing artifacts on binned image
- support for data compression output
- support for anti-shake
- standard serial SCCB interface
- digital video port (DVP) parallel output interface and dual lane MIPI output interface
- embedded 1.5V regulator for core power
- programmable I/O drive capability, I/O tri-state configurability
- support for black sun cancellation
- support for images sizes: 5 megapixel, and any arbitrary size scaling down from 5 megapixel
- support for auto focus control (AFC) with embedded AF VCM driver
- embedded microcontroller
- suitable for module size of 8.5 x 8.5 x <6mm with both CSP and RW packaging

key specifications

- **active array size:** 2592 x 1944
- **power supply:**
 - core: 1.5V \pm 5% (with embedded 1.5V regulator)
 - analog: 2.6 ~ 3.0V (2.8V typical)
 - I/O: 1.8V / 2.8V
- **power requirements:**
 - active: TBD
 - standby: TBD
- **temperature range:**
 - operating: -30°C to 70°C (see [table 8-1](#))
 - stable image: 0°C to 50°C (see [table 8-1](#))
- **output formats:** 8-/10-bit RGB RAW output
- **lens size:** 1/4"
- **lens chief ray angle:** 24° (see [figure 10-2](#))
- **input clock frequency:** 6~27 MHz
- **S/N ratio:** TBD
- **dynamic range:** TBD
- **maximum image transfer rate:**
 - QSXGA (2592x1944): 15 fps
 - 1080p: 30 fps
 - 1280x960: 45 fps
 - 720p: 60 fps
 - VGA (640x480): 90 fps
 - QVGA (320x240): 120 fps
- **sensitivity:** TBD
- **shutter:** rolling shutter / frame exposure
- **maximum exposure interval:** 1964 x t_{ROW}
- **pixel size:** 1.4 μm x 1.4 μm
- **well capacity:** TBD
- **dark current:** TBD
- **fixed pattern noise (FPN):** TBD
- **image area:** 3673.6 μm x 2738.4 μm
- **package dimensions:** 5985 μm x 5835 μm

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1 signal descriptions

table 1-1 lists the signal descriptions and their corresponding pin numbers for the OV5640 image sensor. The package information is shown in **section 9**.

table 1-1 signal descriptions (sheet 1 of 3)

pin number	signal name	pin type	description
A2	VCMSINK	I/O	analog I/O
A3	AVDD	power	power for analog circuit
A4	AGND	ground	ground for analog circuit
A6	DGND	ground	ground for digital circuit
A7	NC	—	no connect
A8	NC	—	no connect
A9	NC	—	no connect
A10	AGND	ground	ground for analog circuit
A11	NC	—	no connect
B1	DGND	ground	ground for digital circuit
B2	VCMSINK	I/O	analog I/O
B3	VCMGND	I/O	analog I/O
B4	VCMGND	I/O	analog I/O
B5	DVDD	power	power for digital circuit
B6	NC	—	no connect
B7	NC	—	no connect
B8	NC	—	no connect
B9	DVDD	power	power for digital circuit
B10	AVDD	power	power for analog circuit
B11	VN	reference	internal analog reference
C1	DVDD	power	power for digital circuit
C2	DGND	ground	ground for digital circuit
C3	NC	—	no connect
C10	VH	reference	internal analog reference
C11	AVDD	power	power for analog circuit
D1	PWDN	input	power down (active high with internal pull-down resistor)

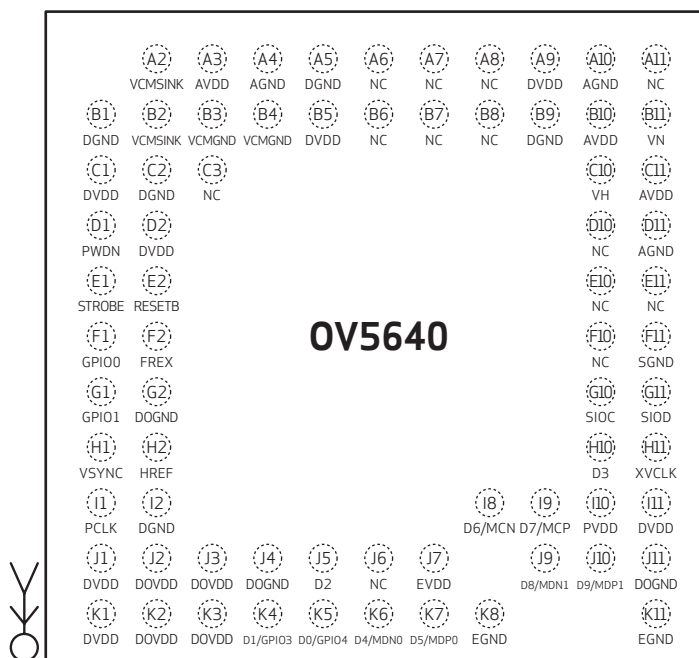
table 1-1 signal descriptions (sheet 2 of 3)

pin number	signal name	pin type	description
D2	DVDD	power	power for digital circuit
D10	NC	–	no connect
D11	AGND	ground	ground for analog circuit
E1	STROBE	I/O	strobe output
E2	RESETB	input	reset (active low with internal pull-up resistor)
E10	NC	–	no connect
E11	NC	–	no connect
F1	GPIO0	I/O	GPIO port 0
F2	FREX	I/O	frame exposure / mechanical shutter
F10	NC	–	no connect
F11	SGND	ground	ground for sensor circuit
G1	GPIO1	I/O	GPIO port 1
G2	DOGND	ground	ground for I/O circuit
G10	SIOC	input	SCCB input clock
G11	SIOD	I/O	SCCB data
H1	VSYNC	I/O	DVP VSYNC output
H2	HREF	I/O	DVP HREF output
H10	D3	I/O	DVP data output port 3
H11	XVCLK	input	system input clock
I1	PCLK	I/O	DVP PCLK output
I2	DGND	ground	ground for digital circuit
I8	D6/MCN	I/O	DVP data output port 6/ MIPI TX clock lane negative output
I9	D7/MCP	I/O	DVP data output port 7/ MIPI TX clock lane positive output
I10	PVDD	power	power for PLL circuit
I11	DVDD	power	power for digital circuit
J1	DVDD	power	power for digital circuit
J2	DOVDD	power	power for I/O circuit
J3	DOVDD	power	power for I/O circuit
J4	DOGND	ground	ground for I/O circuit
J5	D2	I/O	DVP data output port 2

table 1-1 signal descriptions (sheet 3 of 3)

pin number	signal name	pin type	description
J6	NC	–	no connect
J7	EVDD	reference	power for MIPI TX circuit
J9	D8/MDN1	I/O	DVP data output port 8/ MIPI TX second data lane negative output
J10	D9/MDP1	I/O	DVP data output port 9/ MIPI TX second data lane positive output
J11	DOGND	ground	ground for I/O circuit
K1	DVDD	power	power for digital circuit
K2	DOVDD	power	power for I/O circuit
K3	DOVDD	power	power for I/O circuit
K4	D1/GPIO3	I/O	DVP data output port 1/ GPIO port 3
K5	D0/GPIO2	I/O	DVP data output port 0/ GPIO port 2
K6	D4/MDN0	I/O	DVP data output port 4/ MIPI TX first data lane negative output
K7	D5/MDP0	I/O	DVP data output port 5/ MIPI TX first data lane positive output
K8	EGND	ground	ground for MIPI TX circuit
K11	EGND	ground	ground for MIPI TX circuit

figure 1-1 pin diagram



5640 CSP D5 1 1

2 system level description

2.1 overview

The OV5640 (color) image sensor is a low voltage, high-performance, 1/4-inch 5 megapixel CMOS image sensor that provides the full functionality of a single chip 5 megapixel (2592x1944) camera using OmniBSI™ technology in a small footprint package. It provides full-frame, sub-sampled, windowed or arbitrarily scaled 8-bit/10-bit images in various formats via the control of the Serial Camera Control Bus (SCCB) interface.

The OV5640 has an image array capable of operating at up to 15 frames per second (fps) in 5 megapixel resolution with complete user control over image quality, formatting and output data transfer. All required image processing functions, including exposure control, gamma, white balance, color saturation, hue control, defective pixel canceling, noise canceling, etc., are programmable through the SCCB interface or embedded microcontroller. The OV5640 also includes a compression engine for increased processing power. In addition, Omnivision image sensors use proprietary sensor technology to improve image quality by reducing or eliminating common lighting/electrical sources of image contamination, such as fixed pattern noise, smearing, etc., to produce a clean, fully stable, color image.

The OV5640 has an embedded microcontroller, which can be combined with an internal autofocus engine and programmable general purpose I/O modules (GPIO) for external autofocus control. It also provides an anti-shake function with an internal anti-shake engine. For identification and storage purposes, the OV5640 also includes a one-time programmable (OTP) memory.

The OV5640 supports both a digital video parallel port and a serial MIPI port.

2.2 architecture

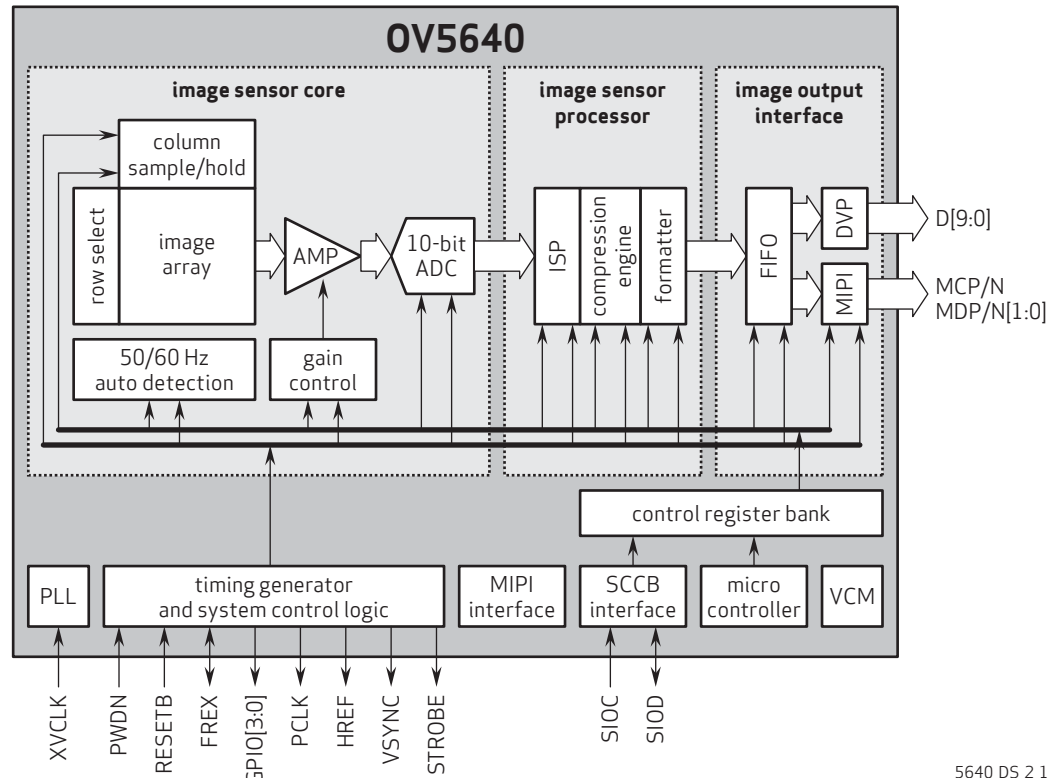
The OV5640 sensor core generates streaming pixel data at a constant frame rate, indicated by HREF and VSYNC.

figure 2-1 shows the functional block diagram of the OV5640 image sensor.

The timing generator outputs signals to access the rows of the image array, precharging and sampling the rows of the array in series. In the time between pre-charging and sampling a row, the charge in the pixels decreases with the time exposed to the incident light. This is known as exposure time.

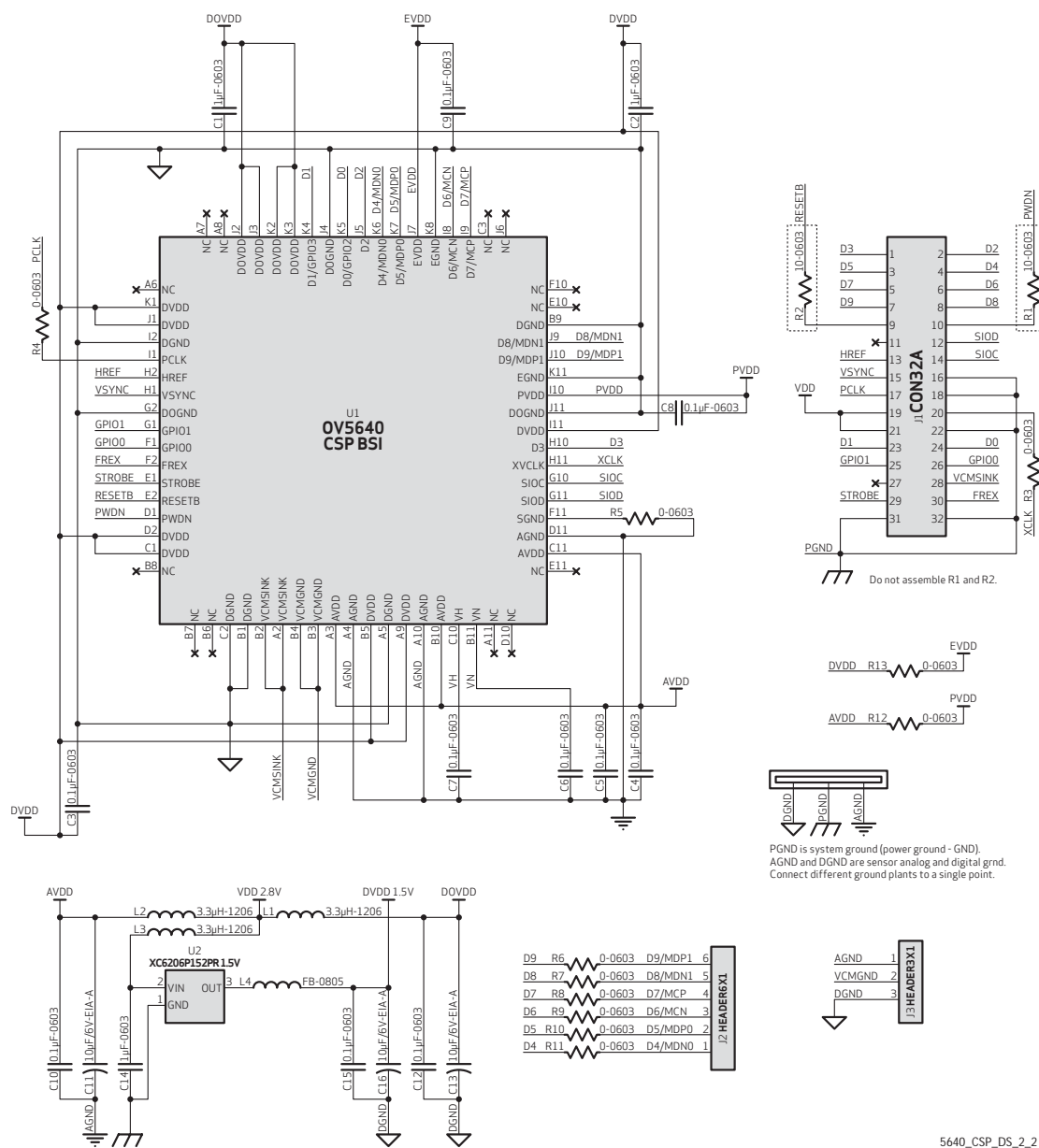
The exposure time is controlled by adjusting the time interval between precharging and sampling. After the data of the pixels in the row has been sampled, it is processed through analog circuitry to correct the offset and multiply the data with corresponding gain. Following analog processing is the ADC which outputs 10-bit data for each pixel in the array.

figure 2-1 OV5640 block diagram



5640_DS_2_1

figure 2-2 reference design schematic



2.3 format and frame rate

table 2-1 format and frame rate

format	resolution	frame rate	scaling method	pixel clock
5 Mpixel	2592x1944	15 fps	full resolution (dummy 16 pixel horizontal, 8 lines) 2608x1952 with dummy	96/192 MHz
1280x960	1280x960	45 fps	subsampling in vertical and horizontal 1296x968 supports 2x2 binning	96/192 MHz
1080p	1920x1080	30 fps	cropping from full resolution 1936x1088 with dummy pixels	96/192 MHz
720p	1280x720	60 fps	cropping 2592x1944 to 2560x1440 subsampling in vertical and horizontal 1296x728 with dummy supports 2x2 binning	96/192 MHz
VGA	640x480	90 fps	subsampling from 1280x960 648x484 with dummy supports 2x2 binning	48/96 MHz
QVGA	320x240	120 fps	subsampling from 1280x960 324x242 with dummy supports 2x2 binning	24/48 MHz

2.4 I/O control

The OV5640 I/O pad direction and driving capability can be easily adjusted. **table 2-2** lists the driving capability and direction control registers of the I/O pads.

table 2-2 driving capability and direction control for I/O pads (sheet 1 of 2)

function	register	default value	R/W	description
output drive capability control	0x302C	0x02	RW	Bit[7:6]: output drive capability 00: 1x 01: 2x 10: 3x 11: 4x
D[9:0] I/O control	0x3017[3:0], 0x3018[7:2]	0x00	RW	input/output control for the D[9:0] pins 0: input 1: output D9 share with MD2P pin for MIPI D8 share with MD2N pin for MIPI D7 share with MCP pin for MIPI D6 share with MCN pin for MIPI D5 share with MD1P pin for MIPI D4 share with MD1N pin for MIPI
D[9:0] output select	0x301D[3:0], 0x301E[7:2]	0x00	RW	output selection for the D[9:0] pins 0: normal data path 1: register-controlled value
D[9:0] output value	0x301A[3:0], 0x301B[7:2]	0x00	RW	D[9:0] output value
D[9:0] input value	0x3051[3:0], 0x3052[7:2]	–	R	D[9:0] input value
VSYNC I/O control	0x3017	0x00	RW	Bit[6]: input/output control for the VSYNC pin 0: input 1: output
VSYNC output select	0x301D	0x00	RW	Bit[6]: output selection for the VSYNC pin 0: normal data path 1: register-controlled value
VSYNC output value	0x301A	0x00	RW	Bit[6]: VSYNC output value
VSYNC input value	0x3051	–	R	Bit[6]: VSYNC input value
HREF I/O control	0x3017	0x00	RW	Bit[5]: input/output control for the HREF pin 0: input 1: output

table 2-2 driving capability and direction control for I/O pads (sheet 2 of 2)

function	register	default value	R/W	description	
HREF output select	0x301D	0x00	RW	Bit[5]:	output selection for the HREF pin 0: normal data path 1: register-controlled value
HREF output value	0x301A	0x00	RW	Bit[5]:	HREF output value
HREF input value	0x3051	—	R	Bit[5]:	HREF input value
PCLK I/O control	0x3017	0x00	RW	Bit[4]:	input/output control for the PCLK pin 0: input 1: output
PCLK output select	0x301D	0x00	RW	Bit[4]:	output selection for the PCLK pin 0: normal data path 1: register-controlled value
PCLK output value	0x301A	0x00	RW	Bit[4]:	PCLK output value
PCLK input value	0x3051	—	R	Bit[4]:	PCLK input value

2.5 system clock control

The OV5640 PLL allows for an input clock frequency ranging from 6~27 MHz and has a maximum VCO frequency of 800 MHz. MipiClk is for the MIPI and SysClk is for the internal clock of the Image Signal Processing (ISP) block. The PLL can be bypassed by setting register 0x3039[7] to 1.

2.6 SCCB interface

The Serial Camera Control Bus (SCCB) interface controls the image sensor operation. Refer to the OmniVision Technologies Serial Camera Control Bus (SCCB) Specification for detailed usage of the serial control port.

Group write is supported in order to update a group of registers in the same frame. These registers are guaranteed to be written prior to the internal latch at the frame boundary.

The OV5640 supports up to four groups. These groups share 1 KB RAM and the size of each group is programmable by adjusting the start address. The group hold start addresses range from 0x40 to 0x7F, where the unit is 16 bytes.

table 2-3 group sharing registers

address	register name	default value	R/W	description
0x3200	GROUP ADDR0	0x40	RW	Start Address for Group0 {group_addr0[7:0], 4'h0}
0x3201	GROUP ADDR1	0x4A	RW	Start Address for Group1 {group_addr1[7:0], 4'h0}
0x3202	GROUP ADDR2	0x54	RW	Start Address for Group2 {group_addr2[7:0], 4'h0}
0x3203	GROUP ADDR3	0x5E	RW	Start Address for Group3 {group_addr3[7:0], 4'h0}

The group write function is controlled by register **0x3212**.

table 2-4 group write register

address	register name	default value	R/W	description
0x3212	SRM GROUP ACCESS	–	W	SRM Group Access
				Bit[7]: Group launch enable Bit[6]: Test mode access group Bit[5]: Group launch Bit[4]: Group hold end Bit[3:0]: Group id 0xx: Group for register access 011: Group to hold register address of embedded line SOF 100: Group to hold register address of embedded line EOF 101: Test mode for store register value to memory 110: Test mode for restore register value from memory 111: Group for write mask address
0x3213	SRM GROUP STATUS	–	R	SRM Group Status Bit[7]: Store default Bit[6]: Restore Bit[5]: Group hold Bit[4]: Group launch Bit[3]: Group write Bit[2:0]: Group select

The SCCB will enter group write mode after writing to register **0x3212** with a valid group ID. The subsequent registers will be held to the buffer specified by the group_id instead of writing to the registers. Make sure the number of registers does not exceed the capacity of the group. Setting group_hold_end to 1 will exit the group write mode. After that, setting both group_launch and group_launch_en to 1 will write the buffered values to the real registers. Multiple groups of registers can be prepared before writing to the real registers but be sure the correct group_id is specified when the group write is launched.

The following is an example demonstrating the group write operation:

```

78 3212 00 Enable group0
78 3600 00 Write registers to be held in group0
78 3601 01
78 3212 10 End group0

```

78 3212 01 Enable group1
 78 3602 02 Write registers to be held in group1
 78 3603 03
 78 3212 11 End group1

..... Other direct register access

78 3212 02 Enable group2
 78 3604 04 Write registers to be held in group2
 78 3605 05
 78 3212 12 End group2

78 3212 A0 Launch group0

..... Other direct register access

78 3212 03 Enable group3
 78 3606 06 Write registers to be held in group3
 78 3607 07
 78 3212 13 End group3

78 3212 A1 Launch group1
 78 3212 A2 Launch group2
 78 3212 A3 Launch group3

2.7 power up sequence

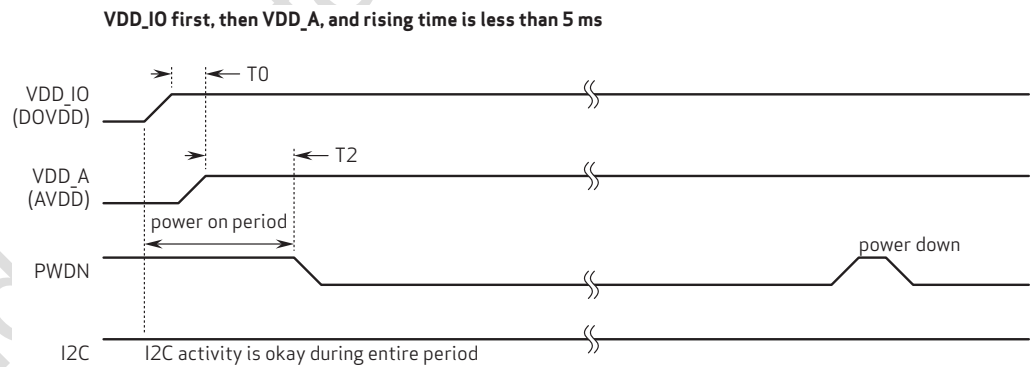
Based on the system power configuration (1.8V or 2.8V for I/O power, using external DVDD or internal DVDD, requiring access to the I2C during power up period or not), the power up sequence will differ. If 1.8V is used for I/O power, using the internal DVDD is preferred. If 2.8V is used for I/O power, due to a high voltage drop at the internal DVDD regulator, there is a potential heat issue. Hence, for a 2.8V power system, OmniVision recommends using an external DVDD source. Due to the higher power down current when using an external DVDD source, OmniVision strongly recommends cutting off all powers, including the external DVDD, when the sensor is not in use in the case of 2.8V I/O and external DVDD.

2.7.1 power up with internal DVDD

For powering up with the internal DVDD and I2C access during the power ON period, the following conditions must occur:

1. if V_{DD-IO} and V_{DD-A} are turned ON at the same time, make sure V_{DD-IO} becomes stable before V_{DD-A} becomes stable
2. PWDN is active high with an asynchronized design (does not need clock)
3. PWDN must go high if I2C is accessed during the power up period
4. for PWDN to go low, power must first become stable ($AVDD$ to PWDN ≥ 1 ms)
5. RESETB is active low with an asynchronized design
6. state of RESETB does not matter during power up period once DOVDD is up

figure 2-3 power up timing with internal DVDD and I2C access during power up period



note $T0 \geq 0$ ms: delay from VDD_IO stable to VDD_A stable
 $T2 \geq 1$ ms: delay from VDD_A stable to sensor power up stable

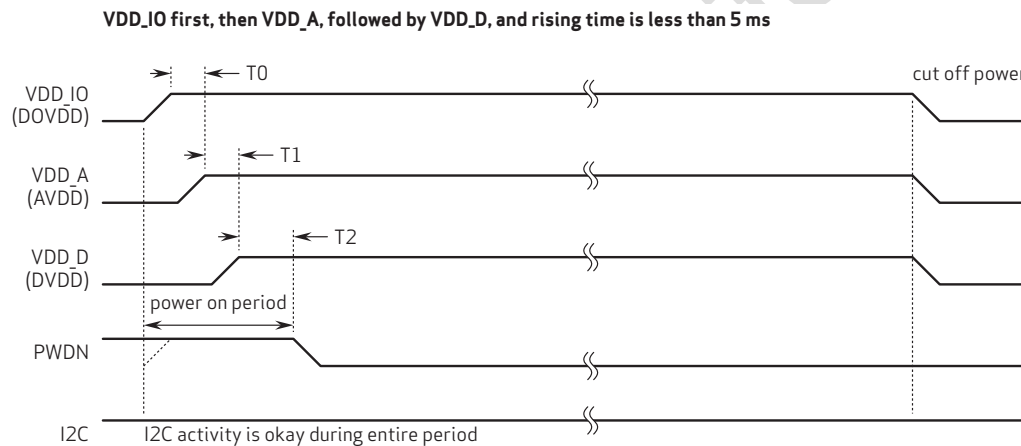
5640_DS_2_3

2.7.2 power up with external DVDD source

For powering up with an external DVDD source and I2C access during the power ON period, the following conditions must occur:

1. if V_{DD_IO} and V_{DD_A} are turned ON at the same time, make sure V_{DD_IO} becomes stable before V_{DD_A} becomes stable
2. if V_{DD_A} and V_{DD_D} are turned ON at the same time, make sure V_{DD_A} becomes stable before V_{DD_D} becomes stable
3. PWDN is active high with an asynchronized design (does not need clock)
4. for PWDN to go low, power must first become stable ($DVDD$ to $PWDN \geq 1$ ms)
5. all powers are cut off when the camera is not in use (power down mode is not recommended)
6. RESETB is active low with an asynchronized design
7. state of RESETB does not matter during power up period once $DOVDD$ is up

figure 2-4 power up timing with external DVDD source and I2C access during power up period



note $T_0 \geq 0$ ms: delay from V_{DD_IO} stable to V_{DD_A} stable
 $T_1 \geq 0$ ms: delay from V_{DD_A} stable to V_{DD_D} stable
 $T_2 \geq 1$ ms: delay from V_{DD_D} stable to sensor power up stable

5640_DS_2_4

2.8 reset

The OV5640 sensor includes a **RESETB** pin that forces a complete hardware reset when it is pulled low (GND). The OV5640 clears all registers and resets them to their default values when a hardware reset occurs. A reset can also be initiated through the SCCB interface by setting register **0x3008**[7] to high.

2.9 standby and sleep

Two suspend modes are available for the OV5640:

- hardware standby
- SCCB software sleep

To initiate hardware standby mode, the **PWDN** pin must be tied to high. When this occurs, the OV5640 internal device clock is halted and all internal counters are reset and registers are maintained.

Executing a software power down through the SCCB interface suspends internal circuit activity but does not halt the device clock. All register content is maintained in standby mode.

The OV5640 sensor has an image array of 2624 columns by 1964 rows (5,153,536 pixels). **figure 3-1** shows a cross-section of the image sensor array.

The sensor array design is based on a field integration readout system with line-by-line transfer and an electronic shutter with a synchronous pixel readout scheme.

3.2 binning

Binning mode is usually used for subsampling. During subsampling, information is periodically dropped when data is output. When the binning function is ON, voltage levels of adjacent pixels are averaged before being sent to the ADC. If the binning function is OFF, the pixels, which are not output, are merely skipped. The OV5640 supports 2x2, 1x2, and 2x1 binning.

figure 3-2 illustrates 2x2 binning, where the voltage levels of four (2x2) adjacent same-color pixels are averaged before entering the ADC.

In OV5640, vertical binning will automatically turn on when in vertical-subsampled formats.

figure 3-2 example of 2x2 binning

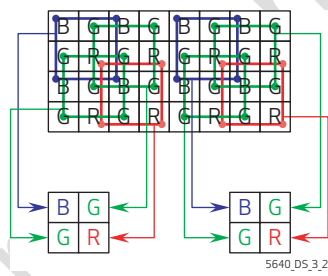
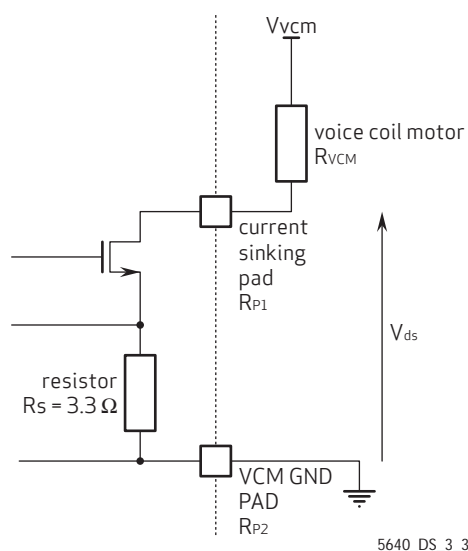


table 3-1 binning-related registers

address	register name	default value	R/W	description	
0x3621	TIMING TC REG21	0x00	RW	Bit[0]:	Horizontal binning enable

3.3 VCM driver

figure 3-3 VCM block diagram



The maximum SINK current can be estimated as:

- $ISINK = (V_{vcm} - V_{ds}) / (R_s + R_{vcm} + R_{p1} + R_{p2})$
- V_{ds} is the transistor headroom
- R_{p1} and R_{p2} are the resistance in the current path
- R_{VCM} is the resistance of the voice coil motor.

The OV5640 VCM driver is a single 10-bit DAC with 100 mA output current sink capability. It is designed for linear control of the VCM. The DAC is controlled via the SCCB interface with clock rates up to 400 Hz. The OV5640 VCM driver provides three types of output current control modes that allow users to adjust transient response of the sinking current.

3.3.1 output current control mode

The OV5640 VCM driver uses 4 bits (S_3 , S_2 , S_1 , and S_0) to control the output current response.

1. $S[3:0] = X000$: Directly jump mode: code directly jumps to target code. Output current transient response time (see [table 3-2](#).)
2. $S[3:0] = 0001$ to 0111 : Single step mode: code increases/decreases by a single step. Single step time durations are 50μs, 100μs, 200μs, 400μs, 800μs, 1600μs, and 3200μs, which are controlled by S_2 , S_1 , and S_0 (see [table 3-4](#).)
3. $S[3:0] = 1001$ to 1111 : Multi-code steps mode: Code increases/decreases in multi-code steps. If the target code and the current code have a difference larger than 128, the 64-code step is applied first. When the difference in between target and current codes is no more than 128 but larger than 16, the 16-code step is used. When the difference is less than 16, it will directly jump to the target code. Single step time options are 50μs, 100μs, 200μs, 400μs, 800μs, 1600μs, and 3200μs, which are controlled by S_2 , S_1 , and S_0 , (see [table 3-5](#).)

table 3-2 VCM driver control

function	register	description
current transient response control	0x3602	Bit[3:0]: Current transient response control x000: mode 0 0001~0111: mode 1 1001~1111: mode 2
10-bit DAC code	0x3603[5:0], 0x3602[7:4]	0x3603[5:0]: D[9:4] 0x3602[7:4]: D[3:0]
clock divider	0x3605[3:0], 0x3606[7:0]	divide external clock to obtain a 20 KHz clock for VCM control block VCM control clock = external clock / Rdiv[11:0]

table 3-3 VCM control registers

address	register name	default value	R/W	description
0x3603	VCM[15:8]	0x01	RW	Bit[7]: PD Bit[5:0]: D[9:4]
0x3602	VCM[7:0]	0x50	RW	Bit[7:4]: D[3:0] Bit[3]: S3 Bit[2:0]: S[2:0]
0x3605	SLEW[11:8]	0x46	RW	Bit[3:0]: Rdiv[11:8]
0x3604	SLEW[7:0]	0x05	RW	Bit[7:0]: Rdiv[7:0]
0x3606	VCM CURRENT	0x00	RW	Bit[2:0]: VCM output current control 000: $0.71 * I_d$ 001: $0.77 * I_d$ 010: $0.83 * I_d$ 011: $0.91 * I_d$ 100: $1.00 * I_d$ 101: $1.11 * I_d$ 110: $1.25 * I_d$ 111: $1.43 * I_d$

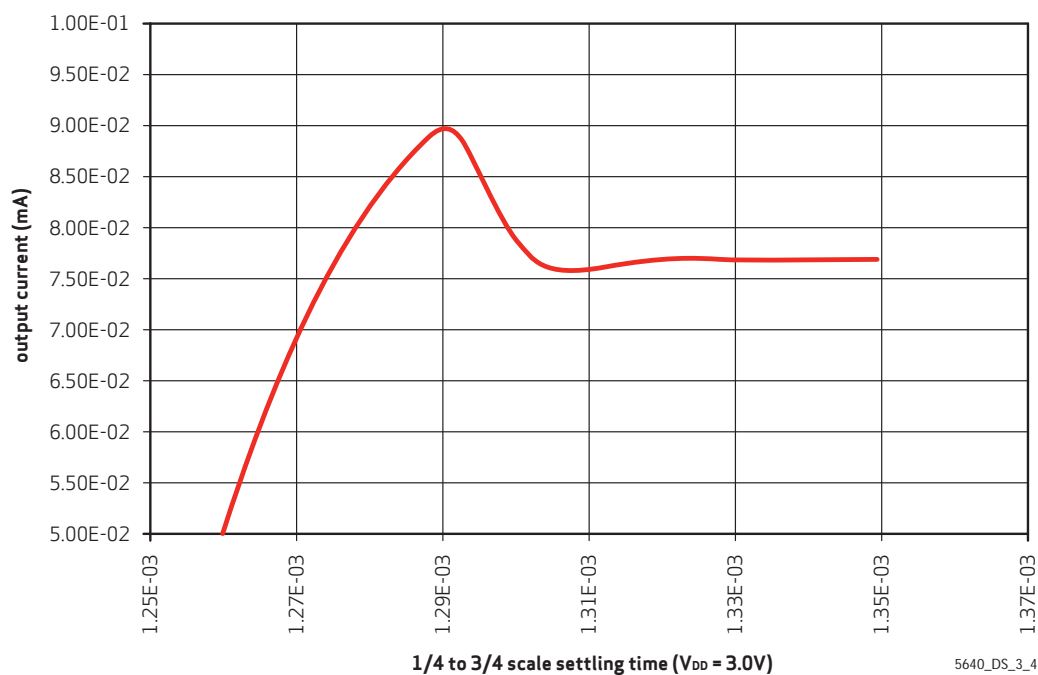
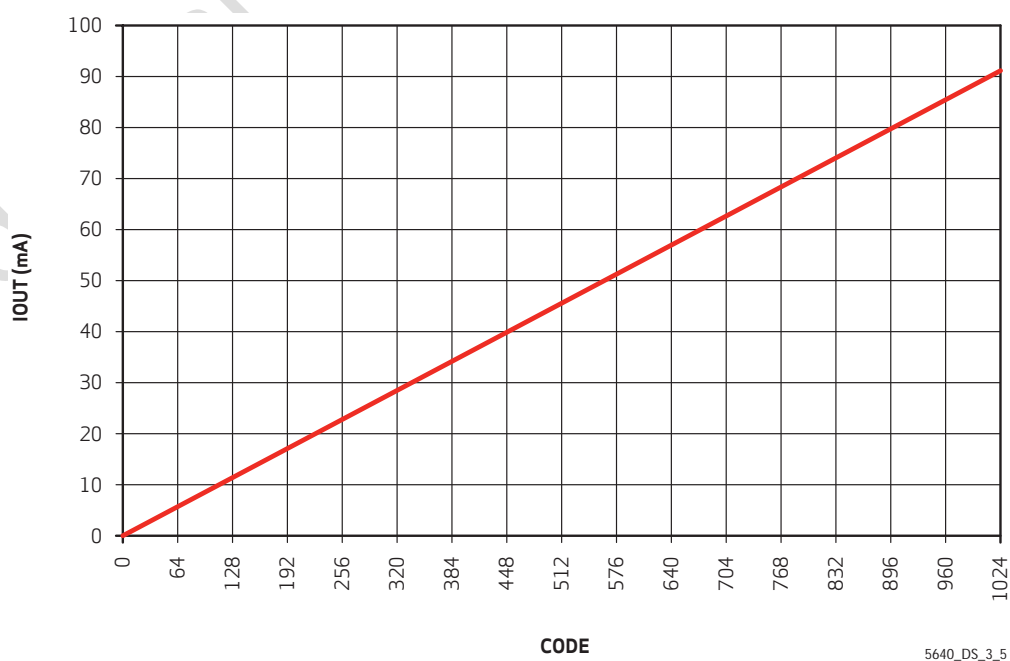
table 3-4 single step mode

mode	S3	S2	S1	S0	single step transition time	full scale transition time (1023 steps)
single step mode	0	0	0	1	50 μ s	51.15ms
	0	0	1	0	100 μ s	102.3ms
	0	0	1	1	200 μ s	204.6ms
	0	1	0	0	400 μ s	409.2ms
	0	1	0	1	800 μ s	818.4ms
	0	1	1	0	1600 μ s	1.637s
	0	1	1	1	3200 μ s	3.274s

table 3-5 multi-code step mode

mode	S3	S2	S1	S0	single step transition time	full scale transition time (22 steps) ^a
single step mode	1	0	0	1	50 μ s	1.1ms
	1	0	1	0	100 μ s	2.2ms
	1	0	1	1	200 μ s	4.4ms
	1	1	0	0	400 μ s	8.8ms
	1	1	0	1	800 μ s	17.6ms
	1	1	1	0	1600 μ s	35.2ms
	1	1	1	1	3200 μ s	70.4ms

a. a full scale transition includes fourteen 64-code steps, seven 16-code steps and one directly jump step.

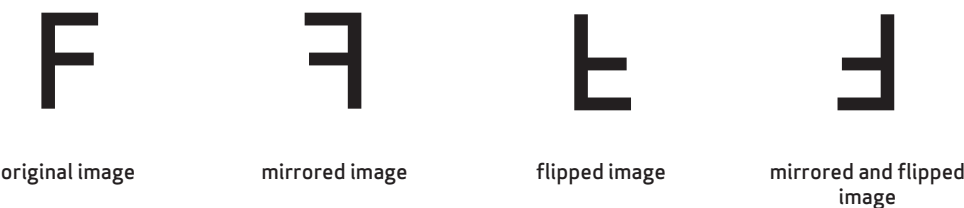
figure 3-4 1/4 to 3/4 scale settling time (directly jump mode, VDD = 3.0V)**figure 3-5** sink current vs. code (VDD = 3.0V, reg 0x30A5 = 0x05, VCM resistance = 23ohms)

4 image sensor core digital functions

4.1 mirror and flip

The OV5640 provides Mirror and Flip readout modes, which respectively reverse the sensor data readout order horizontally and vertically (see **figure 4-1**). In flip, the OV5640 does not need additional settings because the ISP block will auto-detect whether the pixel is in the red line or blue line and make the necessary adjustments.

figure 4-1 mirror and flip samples



5640_DS_4_1

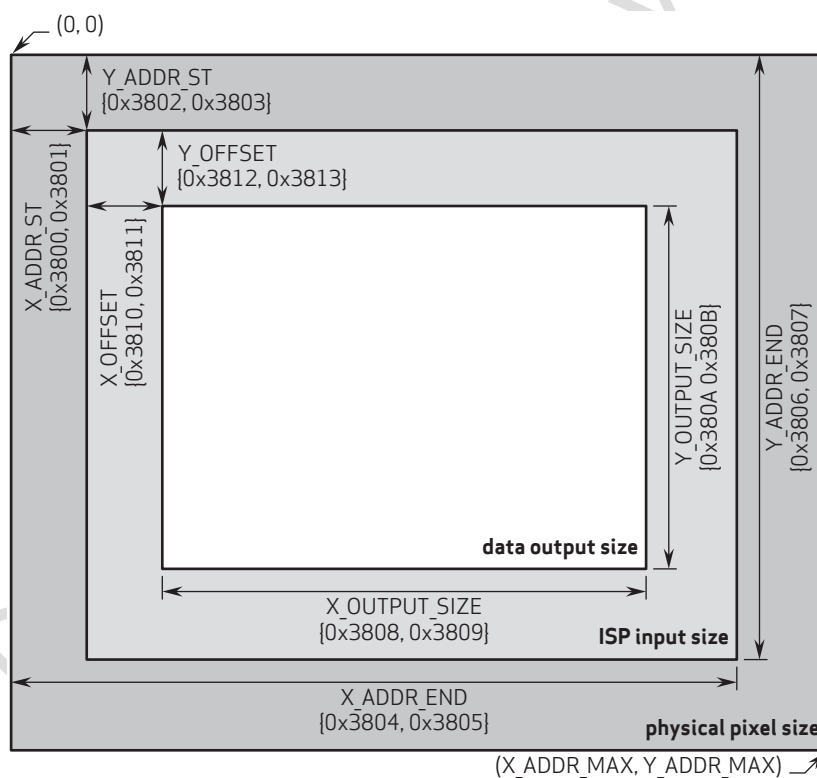
table 4-1 mirror and flip registers

address	register name	default value	R/W	description
0x3820	TIMING TC REG20	0x40	RW	Timing control Bit[2]: ISP vflip Bit[1]: Sensor vflip
0x3821	TIMING TC REG21	0x00	RW	Timing Control Bit[2]: ISP mirror Bit[1]: Sensor mirror

4.2 image windowing

The OV5640 uses registers 0x3800 ~ 0x3814 for image windowing. **figure 4-2** illustrates how the registers define the windowing size. Physical pixel size is the total pixel array size we have in the sensor. The ISP input size is the total pixel data read from pixel array. Typically, the larger ISP input size is, the less maximum frame rate can be reached. The data output size is the image output size of OV5640. This size is windowed from ISP input size and is defined by x_offset and y_offset as **figure 4-2** shows.

figure 4-2 image windowing



5640_DS_4_2

figure 4-3 shows the windowing configuration when scaling function is enabled. The pre-scaling image size is the ISP input size subtracted by two times of offsets for both horizontal and vertical.

figure 4-3 image windowing configuration

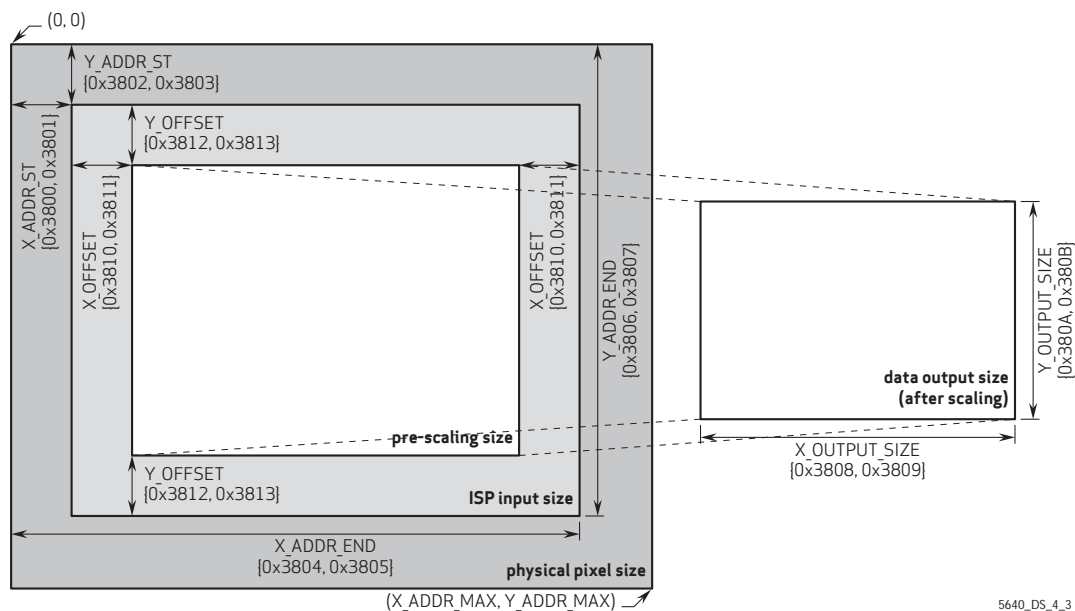


table 4-2 image windowing registers (sheet 1 of 2)

address	register name	default value	R/W	description
0x3800	TIMING HS	0x00	RW	Bit[3:0]: X address start high byte[11:8] high byte
0x3801	TIMING HS	0x00	RW	Bit[7:0]: X address start low byte[7:0] low byte
0x3802	TIMING VS	0x00	RW	Bit[2:0]: Y address start high byte[10:8] high byte
0x3803	TIMING VS	0x00	RW	Bit[7:0]: Y address start low byte[7:0] low byte
0x3804	TIMING HW	0x0A	RW	Bit[3:0]: X address end high byte[11:8] high byte
0x3805	TIMING HW	0x3F	RW	Bit[7:0]: X address end low byte[7:0] low byte
0x3806	TIMING VH	0x07	RW	Bit[2:0]: Y address end high byte[10:8] high byte
0x3807	TIMING VH	0x9F	RW	Bit[7:0]: Y address end low byte[7:0] low byte
0x3808	TIMING DVPHO	0x0A	RW	Bit[3:0]: DVP output horizontal width[11:8] high byte

table 4-2 image windowing registers (sheet 2 of 2)

address	register name	default value	R/W	description
0x3809	TIMING DVPHO	0x20	RW	Bit[7:0]: DVP output horizontal width[7:0] low byte
0x380A	TIMING DVPVO	0x07	RW	Bit[2:0]: DVP output vertical height[10:8] high byte
0x380B	TIMING DVPVO	0x98	RW	Bit[7:0]: DVP output vertical height[7:0] low byte
0x380C	TIMING HTS	0x0B	RW	Bit[3:0]: Total horizontal size[11:8] high byte
0x380D	TIMING HTS	0x1C	RW	Bit[7:0]: Total horizontal size[7:0] low byte
0x380E	TIMING VTS	0x07	RW	Bit[7:0]: Total vertical size[15:8] high byte
0x380F	TIMING VTS	0xB0	RW	Bit[7:0]: Total vertical size[7:0] low byte
0x3810	TIMING HOFFSET	0x00	RW	Bit[3:0]: ISP horizontal offset[11:8] high byte
0x3811	TIMING_HOFFSET	0x10	RW	Bit[7:0]: ISP horizontal offset[7:0] low byte
0x3812	TIMING VOFFSET	0x00	RW	Bit[2:0]: ISP vertical offset[10:8] high byte
0x3813	TIMING VOFFSET	0x04	RW	Bit[7:0]: ISP vertical offset[7:0] low byte

4.3 test pattern

For testing purposes, the OV5640 offers one type of test pattern, color bar.

figure 4-4 test pattern

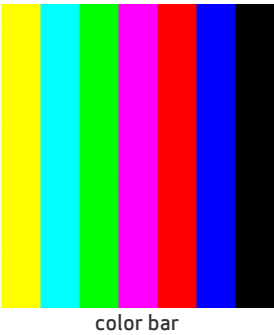


table 4-3 test pattern selection control

address	register name	default value	R/W	description
0x503D	PRE ISP TEST SETTING 1	0x00	RW	Bit[7]: Color bar enable 0: Test disable 1: Color bar enable Bit[3:2]: Color bar style 00: Standard eight color bar 01: Gradual change at vertical mode 1 10: Gradual change at horizontal 11: Gradual change at vertical mode 2

4.4 50/60Hz detection

4.4.1 overview

When the integration time is not an integer multiple of the period of light intensity, the image will flicker. The function of the detector is to detect whether the sensor is under a 50 Hz or 60 Hz light source so that the basic step of integration time can be determined. Contact your local OmniVision FAE for auto detection settings.

4.5 AEC/AGC algorithms

4.5.1 overview

The Auto Exposure Control (AEC) and Auto Gain Control (AGC) allows the image sensor to adjust the image brightness to a desired range by setting the proper exposure time and gain applied to the image. Besides automatic control, exposure time and gain can be set manually from external control. The related registers are listed in [table 4-4](#).

table 4-4 AEC/AGC control functions

address	register name	default value	R/W	description
0x3500	AEC PK EXPOSURE	0x00	RW	Exposure Output Bit[3:0]: Exposure [19:16]
0x3501	AEC PK EXPOSURE	0x02	RW	Exposure Output Bit[7:0]: Exposure [15:8]
0x3502	AEC PK EXPOSURE	0x00	RW	Exposure Output Bit[7:0]: Exposure [7:0]
0x3503	AEC PK MANUAL	0x00	RW	AEC Manual Mode Control Bit[1]: AGC manual 0: Auto enable 1: Manual enable Bit[0]: AEC manual 0: Auto enable 1: Manual enable
0x350A	AEC PK REAL GAIN	0x00	RW	Real Gain Bit[1:0]: Real gain[9:8]
0x350B	AEC PK REAL GAIN	0x10	RW	Real Gain Bit[7:0]: Real gain[7:0]
0x350C	AEC PK VTS	0x00	RW	AEC VTS Output Bit[7:0]: VTS[15:8] high bits
0x350D	AEC PK VTS	0x00	RW	AEC VTS Output Bit[7:0]: VTS[7:0] low bits

4.5.2 average-based algorithm

The average-based AEC controls image luminance using registers (0x3A0F), (0x3A10), (0x3A1B), and (0x3A1E). In average-based mode, the value of register (0x3A0F) indicates the high threshold value, and the value of register (0x3A10) indicates the low threshold value. The value of register (0x3A1B) indicates the high threshold value for image change from stable state to unstable state and the value of register (0x3A1E) indicates the low threshold value for image change from stable state to unstable state. When the target image luminance average value AVG READOUT (0x56A1) is within the range specified by registers (0x3A1B) and (0x3A1E), the AEC keeps the image exposure and gain. When register AVG READOUT (0x56A1) is greater than the value in register (0x3A1B), the AEC will decrease the image exposure and gain until it falls into the range of {0x3A10, 0x3A0F}. When register AVG READOUT (0x56A1) is less than

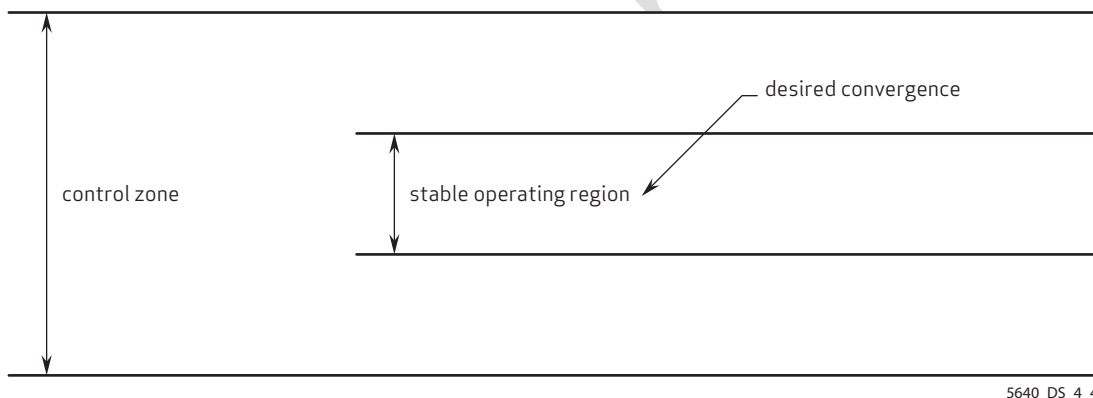
the value in register (0x3A1E), the AEC will increase the image exposure and gain until it falls into the range of {0x3A10, 0x3A0F}. Accordingly, the value in register (0x3A0F) should be greater than the value in register (0x3A10). The gap between the values of registers (0x3A1B) and (0x3A1E) controls the image stability.

The AEC function supports both manual and auto speed selections in order to bring the image exposure into the range set by the values in registers (0x3A0F) and (0x3A10). For manual mode, the speed supports both normal and fast speed selection. AEC set to normal mode will allow for the slowest step increment or decrement in the image exposure to maintain the specified range. AEC set to fast mode will provide for an approximate ten-step increment or decrement in the image exposure to maintain the specified range. For auto mode, the speed step will automatically be adjusted according to the difference between the target and present values. The auto ratio of steps can be set by register bits AVG READOUT (0x56A1); thus, the AEC speed can be adjusted automatically by the image average value or controlled manually.

Register (0x3A11) and register (0x3A1F) controls the fast AEC range in manual speed selection mode. If the target image AVG READOUT (0x56A1) is greater than (0x3A11), AEC will decrease by half. If register AVG READOUT (0x56A1) is less than (0x3A1F), AEC will double.

As shown in desired convergence, the AEC/AGC convergence uses two regions, the inner stable operating region and the outer control zone, which defines the convergence step size of fast and slow conditions.

figure 4-5 desired convergence



5640_DS_4_4

As for auto mode, the AEC will automatically calculate the steps needed based on the difference between target and current values. So, the outer control zone is meaningless for this mode.

table 4-5 AEC/AGC control functions

address	register name	default value	R/W	description
0x3A0F	AEC CTRL0F	0x78	RW	Stable Range High Limit (enter) Bit[7:0]: WPT
0x3A10	AEC CTRL10	0x68	RW	Stable Range Low Limit (enter) Bit[7:0]: BPT
0x3A11	AEC CTRL11	0xD0	RW	Step Manual Mode, Fast Zone High Limit Bit[7:0]: vpt_high
0x3A1B	AEC CTRL1B	0x78	RW	Stable Range High Limit (go out) Bit[7:0]: WPT2
0x3A1E	AEC CTRL1E	0x68	RW	Stable Range Low Limit (go out) Bit[7:0]: BPT2
0x3A1F	AEC CTRL1F	0x40	RW	Step Manual Mode, Fast Zone Low Limit Bit[7:0]: vpt_low

For the average-based AEC/AGC algorithm, the measured window is horizontally and vertically adjustable and divided by sixteen (4x4) zones (see **figure 4-6**). Each zone (or block) is 1/16th of the image and has a 4-bit weight in calculating the average luminance (YAVG). The 4-bit weight could be $n/16$ where n is from 0 to 15. The final YAVG is the weighted average of the sixteen zones.

4.5.2.1 average luminance (YAVG)

Auto exposure time calculation is based on a frame brightness average value. By properly setting x_start , x_end , y_start , and y_end as shown in **figure 4-6**, a 4x4 grid average window is defined. It will automatically divide each zone into 4x4 zones. The average value is the weighted average of the 16 sections. **table 4-6** lists the corresponding registers.

figure 4-6 average-based window definition

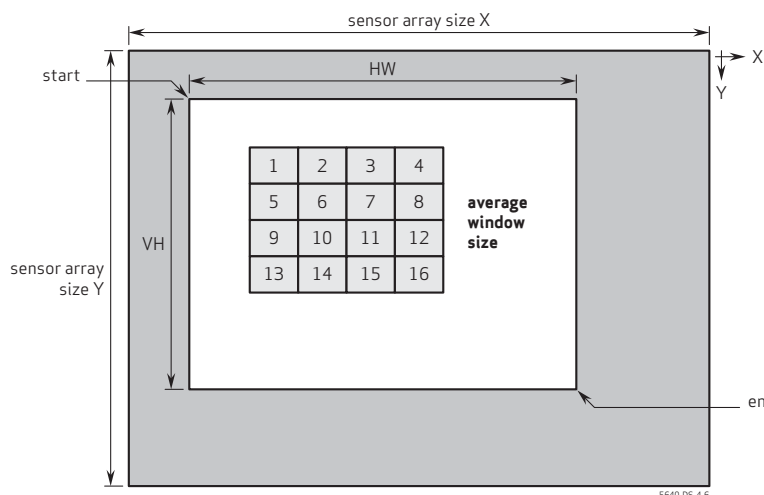


table 4-6 timing control functions (sheet 1 of 2)

address	register name	default value	R/W	description
0x3810	TIMING HOFFSET	0x00	RW	Bit[3:0]: ISP horizontal offset[11:8] high byte
0x3811	TIMING_HOFFSET	0x04	RW	Bit[7:0]: ISP Horizontal offset[7:0] low byte
0x3812	TIMING VOFFSET	0x11	RW	Bit[3:0]: ISP vertical offset[11:8] high byte
0x3813	TIMING VOFFSET	0x11	RW	Bit[7:0]: ISP vertical offset[7:0] low byte
0x3808	TIMING DVPHO	0x07	RW	Bit[3:0]: DVP output horizontal width[11:8] high byte
0x3809	TIMING DVPHO	0x98	RW	Bit[7:0]: DVP output horizontal width[7:0] low byte
0x380A	TIMING DVPVO	0x0B	RW	Bit[3:0]: DVP output vertical height[11:8] high byte
0x380B	TIMING DVPVO	0x1C	RW	Bit[7:0]: DVP output vertical height[7:0] low byte
0x501D	ISP MISC	0x00	RW	Bit[4]: Average size manual enable
0x5680	X START	0x00	RW	Bit[3:0]: x start[11:8] Horizontal start position for average window high byte, valid when 0x501D[4]=1
0x5681	X START	0x00	RW	Bit[7:0]: x start[7:0] Horizontal start position for average window low byte, valid when 0x501D[4]=1

table 4-6 timing control functions (sheet 2 of 2)

address	register name	default value	R/W	description
0x5682	Y START	0x00	RW	Bit[2:0]: y start[10:8] Vertical start position for average window low byte, valid when 0x501D[4]=1
0x5683	Y START	0x00	RW	Bit[7:0]: y start[7:0] Vertical start position for average window low byte, valid when 0x501D[4]=1
0x5684	X WINDOW	0x10	RW	Bit[3:0]: Window X [11:8] Horizontal end position for average window high byte, valid when 0x501D[4]=1
0x5685	X WINDOW	0xA0	RW	Bit[7:0]: Window X [7:0] Horizontal end position for average window low byte, valid when 0x501D[4]=1.
0x5686	Y WINDOW	0x0C	RW	Bit[2:0]: Window Y [10:8] Vertical end position for average window high byte, valid when 0x501D[4]=1
0x5687	Y WINDOW	0x78	RW	Bit[7:0]: Window Y [7:0] Vertical end position for average window low byte, valid when 0x501D[4]=1
0x5688	WEIGHT00	0x11	RW	Bit[7:4]: Window 01 weight Bit[3:0]: Window 00 weight
0x5689	WEIGHT01	0x11	RW	Bit[7:4]: Window 03 weight Bit[3:0]: Window 02 weight
0x568A	WEIGHT02	0x11	RW	Bit[7:4]: Window 11 weight Bit[3:0]: Window 10 weight
0x568B	WEIGHT03	0x11	RW	Bit[7:4]: Window 13 weight Bit[3:0]: Window 12 weight
0x568C	WEIGHT04	0x11	RW	Bit[7:4]: Window 21 weight Bit[3:0]: Window 20 weight
0x568D	WEIGHT05	0x11	RW	Bit[7:4]: Window 23 weight Bit[3:0]: Window 22 weight
0x568E	WEIGHT06	0x11	RW	Bit[7:4]: Window 31 weight Bit[3:0]: Window 30 weight
0x568F	WEIGHT07	0x11	RW	Bit[7:4]: Window 33 weight Bit[3:0]: Window 32 weight

4.6 AEC/AGC steps

The AEC and AGC work together to obtain adequate exposure/gain based on the current environmental illumination. In order to achieve the best SNR, extending the exposure time is always preferred rather than raising the gain when the current illumination is getting brighter. Vice versa, under dark conditions, the action to decrease the gain is always taken prior to shortening the exposure time.

4.6.1 auto exposure control (AEC)

The function of the AEC is to calculate the integration time of the next frame and send the information to the timing control block. Based on the statistics of previous frames, the AEC is able to determine whether the integration time should increase, decrease, fast increase, fast decrease, or remain the same.

In extremely bright situations, the LAEC activates, allowing integration time to be less than one row. In extremely dark situations, the night mode activates, allowing integration time to be larger than one frame.

To avoid image flickering under a periodic light source, the integration time can be adjusted in steps of integer multiples of the period of the light source. This new AEC step system is called the banding filter, suggesting that the exposure time is not continuous but falls in some steps.

4.6.1.1 LAEC

If the integration time is only one row period but the image is too bright, AEC will enter LAEC mode. Within LAEC, the integration time can be further decreased to the minimum of 1/16 row. LAEC ON/OFF can be set in register bit 0x3A00[6].

4.6.1.2 banding mode ON with AEC

In Banding ON mode, the exposure time will fall in steps of integer multiples of the period of light intensity. This design is to reject image flickering when the light source is not steady but periodical.

For a given light flickering frequency, the band step can be expressed in units of row period.

Band Step = 'period of light intensity' × 'frame rate' × 'rows per frame'.

The band steps for 50Hz and 60Hz light sources can be set in registers {0x3A08[1:0], 0x3A09[7:0]} and {0x3A0A[1:0], 0x3A0B[7:0]}, respectively.

When auto-banding is ON, if the next integration time is less than the minimum band step, banding will automatically turn OFF. It will turn ON again when the next integration time becomes larger than the minimum band. If auto banding is disabled, the minimum integration time is one band step. Auto banding can be set in register bit 0x3A00[5].

4.6.1.3 banding mode OFF with AEC

When banding mode is OFF, integration time increases/decreases as normal. It is not necessarily multiples of band steps.

4.6.1.4 night mode

The OV5640 supports long integration time such as 1 frame, 2 frames, 3 frames, 4 frames, 5 frames, 6 frames, 7 frames, and 8 frames in dark conditions. This is achieved by slowing down the original frame rate and waiting for exposure. Night mode ceiling can be set in register bits {0x3A02[7:0], 0x3A03[7:0], 0x3A14[7:0], 0x3A15[7:0]}. Night mode can be disabled by setting register bit 0x3A00[2] to 0. Also, when in night mode, the increase and decrease

step can be based on band or frames, depending on register 0x3A05[6]. The minimum increase/decrease step can be one band. The step can be based both on bands and frames.

4.6.2 manual exposure control

To manually change exposure value, you must first set both 0x3503[0], where 0x3503[0] enables manual exposure control. In auto exposure mode, the extra exposure values (larger than 1 frame) in registers 0x350C/0x350D automatically change. In manual exposure mode, these registers will not automatically change. The manually set exposure in registers 0x3500~0x3502 must be less than the maximum exposure value in {0x380E, 0x380F} + {0x350C, 0x350D}. The exposure value in registers 0x3500~0x3502 is in units of line*16 - the low 4 bits (0x3502[3:0]) is the fraction of line, the maximum value in {0x380E + 0x380F} + {0x350C, 0x350D} is in unit of line. If the manually set exposure value is less than one pre-defined frame period (e.g., 1/15 second in 15fps), there is no need to change 0x380E/0x380F. If the exposure value needs to be set beyond the pre-defined frame period; in other words, if the frame period needs to be extended to extend exposure time, then the maximum frame value in 0x380E/0x380F needs to be set first, then the exposure can be set in registers 0x3500~0x3502 accordingly.

4.6.3 auto gain control (AGC)

Unlike prolonging integration time, increasing gain will amplify both signal and noise. Thus, AGC usually starts after AEC is full. However, in cases where adjacent AEC step changes are too large ($>1/16$), AGC steps should be inserted in between; otherwise, the integration time will keep switching between two adjacent steps and the image flickers.

4.6.3.1 integration time between 1~16 rows

When integration time is less than 16 rows, the changes between adjacent AEC steps are larger than $1/16$, which may possibly make the image oscillate between two AEC levels; thus, some AGC steps are added in between.

4.6.3.2 gain insertion between AEC banding steps

When banding mode is ON, the integration time changes in step of the period of light intensity. For the first 16 band steps, since the exposure time change between adjacent steps is larger than $1/16$, AGC steps are inserted to ensure image stability.

4.6.3.3 gain insertion between night mode steps

Between night mode steps (e.g., integration time = 1 frame and 2 frames), AGC steps are inserted to ensure no adjacent step change is larger than $1/16$.

4.6.3.4 when AEC reaches maximum

When AEC reaches its maximum step while the image is still too dark, the gain starts to increase until the new frame average falls into the stable range or AGC reaches its maximum step. The AGC ceiling can be set in {0x3A18[9:8], 0x3A19[7:0]}.

4.6.4 manual gain control

To manually change gain, first set register bit 0x3503[1] to enable manual control, then change the values in 0x350A/0x350B for the manual gain. The OV5640 has a maximum of 64x gain.

4.7 black level calibration (BLC)

The pixel array contains several optically shielded (black) lines. These lines are used as reference for black level calibration. There are three main functions of the BLC:

- Combining two ADC data paths into one data path
- Adjusting all normal pixel values based on the values of the black levels
- Applying multiplication to all pixel values based on digital gain

Black level adjustments can be made with registers 0x4000 through 0x4013.

table 4-7 BLC control functions

address	register name	default value	R/W	description
0x4000	BLC CTRL00	0x89	RW	BLC Control 00 Bit[0]: BLC enable
0x4002	BLC CTRL02	0x45	RW	Bit[7]: Format change enable BLC update when format changes
0x4003	BLC CTRL03	0x08	RW	Bit[7]: BLC redo enable Write 1 into it will trigger a BLC redo N frames begin, N is 0x4003[5:0] Bit[6]: BLC freeze Bit[5:0]: Manual frame number
0x4005	BLC CTRL05	0x18	RW	Bit[1]: BLC always update 0: Normal freeze 1: BLC always update;
0x4009	BLACK LEVEL	0x10	RW	Bit[7:0]: BLC black level target at 10-bit range

4.8 light frequency selection

The OV5640 can detect the light flickering frequency. When this function is enabled, the sensor can detect the light frequency and select the corresponding banding filter value. To remove banding, the banding filter should be turned on and the banding filter value should be set to the appropriate value.

table 4-8 light frequency registers

address	register name	default value	R/W	description
0x3C01	5060HZ_CTRL1	0x00	RW	Bit[7]: Band manual enable 0: Auto 1: Manual
0x3C00	5060HZ_CTRL2	0x00	RW	Bit[2]: Band value manual setting 0: 60 Hz light 1: 50 Hz light
0x3C0C	5060HZ_CTRL3	—	R	Bit[0]: Band50/60 0: 60 Hz light 1: 50 Hz light

4.9 digital gain

The OV5640 supports 1/2/4 digital gain. Normally, the gain is controlled automatically by the automatic gain control (AGC) block.

4.10 strobe flash and frame exposure

4.10.1 strobe flash control

The strobe signal is programmable. It supports both LED and Xenon modes. The polarity of the pulse can be changed. The strobe signal is enabled (turned high/low depending on the pulse's polarity) by requesting the signal via the SCCB interface. Flash modules are triggered by the rising edge by default or by the falling edge if the signal polarity is changed. It supports the following flashlight modes (see [table 4-9](#)).

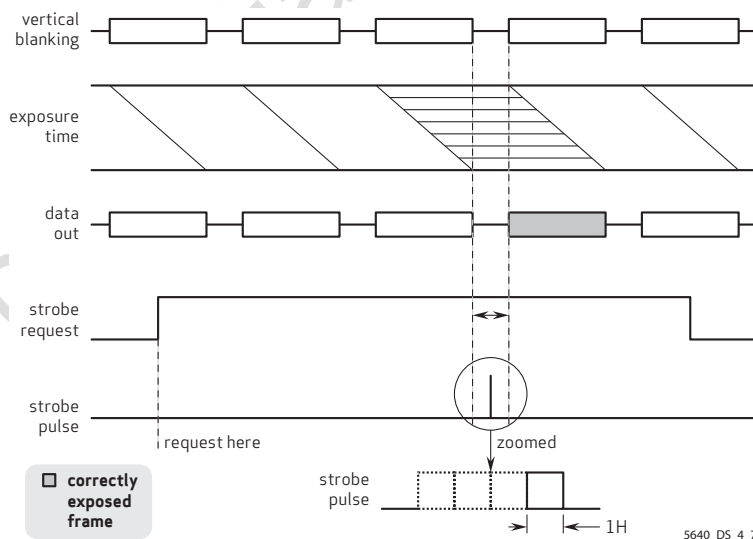
table 4-9 flashlight modes

mode	output	AEC / AGC	AWB
xenon	one-pulse	no	no
LED 1	pulse	no	no
LED 2	pulse	no	yes
LED 3	continuous	yes	yes

4.10.1.1 xenon flash control

After a strobe request is submitted, the strobe pulse will be activated at the beginning of the third frame (see [figure 4-7](#)). The third frame will be correctly exposed. The pulse width can be changed in Xenon mode between 1H and 4H, depending on register 0x3B00[3:2], where H is one row period.

figure 4-7 xenon flash mode



4.10.1.2 LED 1 & 2 mode

Two frames after the strobe request is submitted, the third frame is correctly exposed. The strobe pulse will be activated only one time if the strobe end request is set correctly (see **figure 4-8**). If end request is not sent, the strobe signal is activated intermittently until the strobe end request is set (see **figure 4-9**). The number of skipped frames is programmable using registers {0x3A1C, 0x3A1D}.

figure 4-8 LED 1 & 2 mode - one pulse output

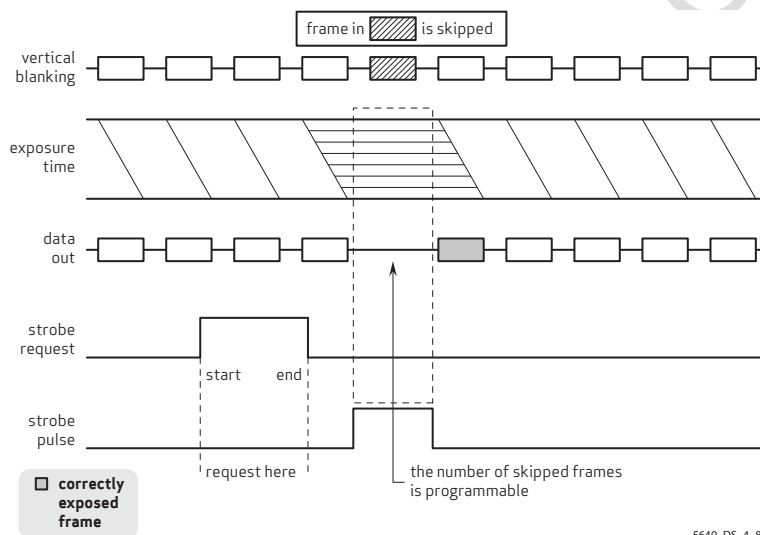
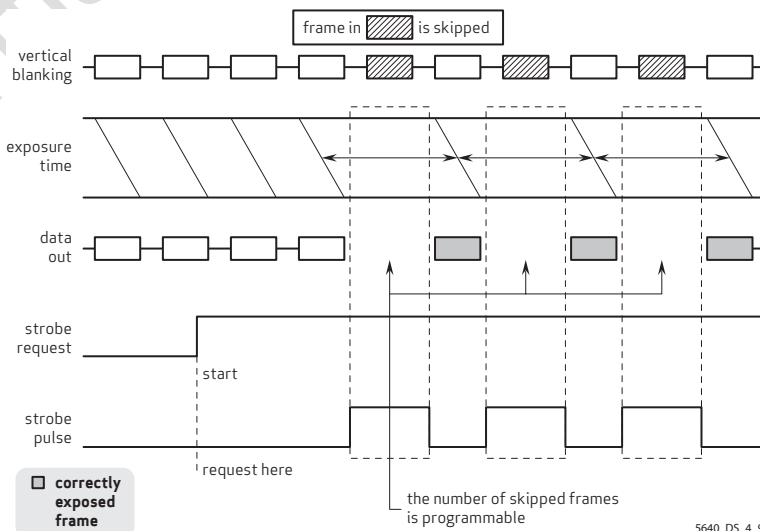


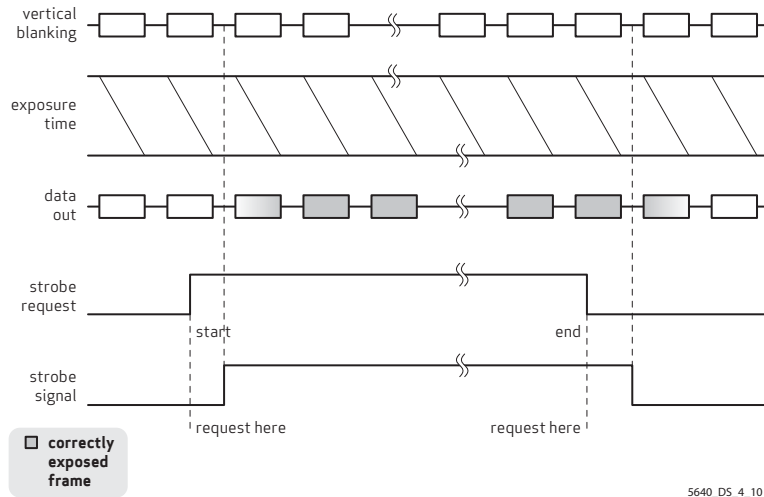
figure 4-9 LED 1 & 2 mode - multiple pulse output



4.10.1.3 LED 3 mode

In LED 3 mode, the strobe signal stays active until the strobe end request is sent (see **figure 4-10**).

figure 4-10 LED 3 mode



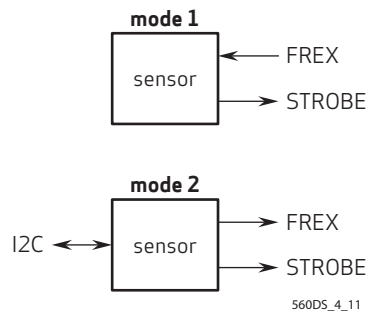
4.10.2 frame exposure (FREX) mode

In FREX mode, whole frame pixels start integration at the same time, rather than integrating row by row. After the user-defined exposure time (registers {0x3B04, 0x3B05}), the shutter closes, preventing further integration and the image begins to read out. After the readout finishes, the shutter opens again and the sensor resumes normal mode, waiting for the next FREX request.

The OV5640 supports two modes of FREX (see **figure 4-11**):

- mode 1 - frame exposure and shutter control requests come from the external system via the FREX pin. The sensor will send a strobe output signal to control the flash light.
- mode 2 - frame exposure request comes from the external system via the I2C register 0x3B08[0]. The sensor will output two signals, shutter control signal through the FREX pin and strobe signal through the STROBE pin.

figure 4-11 FREX modes



In mode 1, the FREX pin is configured as an input while it is configured as an output in mode 2. In both mode 1 and mode 2, the strobe output is irrelevant with the rolling strobe function. When in rolling shutter mode, the strobe function and this FREX/shutter control function do not work at the same time.

4.10.3 FREX strobe flash control

See **table 4-10** for FREX strobe control functions.

table 4-10 FREX strobe control functions (sheet 1 of 2)

address	register name	default value	R/W	description
0x3B00	STROBE CTRL	0x00	RW	Strobe Control Bit[7]: Strobe request ON/OFF 0: OFF/BLC 1: ON Bit[6]: Strobe pulse reverse Bit[3:2]: width_in_xenon Bit[1:0]: Strobe mode 00: Xenon 01: LED 1 10: LED 2 11: LED 3
0x3B01	FREX EXPOSURE 02	0x00	RW	Bit[7:0]: FREX exposure time[23:16]
0x3B02	FREX SHUTTER DELAY 01	0x08	RW	Bit[4:0]: Shutter delay time[12:8]
0x3B03	FREX SHUTTER DELAY 00	0x00	RW	Bit[7:0]: Shutter delay time[7:0] Unit: 64x sclk cycle
0x3B04	FREX EXPOSURE 01	0x04	RW	Bit[7:0]: FREX exposure time [15:8]
0x3B05	FREX EXPOSURE 00	0x00	RW	Bit[7:0]: FREX exposure time [7:0] Unit: Tline
0x3B06	FREX CTRL 07	0x04	RW	Bit[7:4]: FREX frame delay Bit[3:0]: FREX STROBE width[3:0]
0x3B07	FREX MODE	0x08	RW	Bit[7:0]: FREX mode selection 00: FREX STROBE mode0 01: FREX STROBE mode1 1x: Rolling STROBE
0x3B08	FREX REQUEST	0x00	RW	FREX Request
0x3B09	FREX HREF DELAY	0x02	RW	FREX HREF Delay

table 4-10 FREX strobe control functions (sheet 2 of 2)

address	register name	default value	R/W	description
0x3B0A	FREX RST LENGTH	0x04	RW	Bit[2:0]: FREX precharge length 000: 1/16 Tline 001: 1/8 Tline 010: 1/4 Tline 011: 1/2 Tline 100: 1 Tline 101: 2 Tline 110: 4 Tline 111: 8 Tline
0x3B0B	STROBE WIDTH	0x00	RW	Bit[7:0]: STROBE width[19:12]
0x3B0C	STROBE WIDTH	0x3D	RW	Bit[7:0]: STROBE width[11:4]

4.11 one time programmable (OTP) memory

The OV5640 supports a maximum of 256 bits of one-time programmable (OTP) memory to store chip identification and manufacturing information.

table 4-11 OTP control functions

address	register name	default value	R/W	description
0x3D20	OTP PROGRAM CTRL	0x00	RW	Bit[7]: OTP program busy Bit[1]: OTP program speed 0: Fast 1: Slow Bit[0]: OTP program enable
0x3D21	OTP READ CTRL	0x00	RW	Bit[7]: OTP read busy Bit[1]: OTP read speed 0: Fast 1: Slow Bit[0]: OTP read enable
0x3D00	OTP DATA00	0x00	RW	OTP Dump/Load Data00
0x3D01	OTP DATA01	0x00	RW	OTP Dump/Load Data01
0x3D02	OTP DATA02	0x00	RW	OTP Dump/Load Data02
0x3D03	OTP DATA03	0x00	RW	OTP Dump/Load Data03
0x3D04	OTP DATA04	0x00	RW	OTP Dump/Load Data04
0x3D05	OTP DATA05	0x00	RW	OTP Dump/Load Data05
0x3D06	OTP DATA06	0x00	RW	OTP Dump/Load Data06

table 4-11 OTP control functions

address	register name	default value	R/W	description
0x3D07	OTP DATA07	0x00	RW	OTP Dump/Load Data07
0x3D08	OTP DATA08	0x00	RW	OTP Dump/Load Data08
0x3D09	OTP DATA09	0x00	RW	OTP Dump/Load Data09
0x3D0A	OTP DATA0A	0x00	RW	OTP Dump/Load Data0a
0x3D0B	OTP DATA0B	0x00	RW	OTP Dump/Load Data0b
0x3D0C	OTP DATA0C	0x00	RW	OTP Dump/Load Data0c
0x3D0D	OTP DATA0D	0x00	RW	OTP Dump/Load Data0d
0x3D0E	OTP DATA0E	0x00	RW	OTP Dump/Load Data0e
0x3D0F	OTP DATA0F	0x00	RW	OTP Dump/Load Data0f
0x3D10	OTP DATA10	0x00	RW	OTP Dump/Load Data10
0x3D11	OTP DATA11	0x00	RW	OTP Dump/Load Data11
0x3D12	OTP DATA12	0x00	RW	OTP Dump/Load Data12
0x3D13	OTP DATA13	0x00	RW	OTP Dump/Load Data13
0x3D14	OTP DATA14	0x00	RW	OTP Dump/Load Data14
0x3D15	OTP DATA15	0x00	RW	OTP Dump/Load Data15
0x3D16	OTP DATA16	0x00	RW	OTP Dump/Load Data16
0x3D17	OTP DATA17	0x00	RW	OTP Dump/Load Data17
0x3D18	OTP DATA18	0x00	RW	OTP Dump/Load Data18
0x3D19	OTP DATA19	0x00	RW	OTP Dump/Load Data19
0x3D1A	OTP DATA1A	0x00	RW	OTP Dump/Load Data1a
0x3D1B	OTP DATA1B	0x00	RW	OTP Dump/Load Data1b
0x3D1C	OTP DATA1C	0x00	RW	OTP Dump/Load Data1c
0x3D1F	OTP DATA1D	0x00	RW	OTP Dump/Load Data1d
0x3D1E	OTP DATA1E	0x00	RW	OTP Dump/Load Data1e
0x3D1F	OTP DATA1F	0x00	RW	OTP Dump/Load Data1f

5 image sensor processor digital functions

5.1 ISP general controls

The ISP module provides lens correction, gamma, de-noise, sharpen, auto focus, etc. These functions are enabled by registers 0x5000 ~ 0x5005.

table 5-1 ISP general control registers (sheet 1 of 3)

address	register name	default value	R/W	description
0x5000	ISP CONTROL 00	0x06	RW	ISP Control 00
				Bit[7]: LENC correction enable 0: Disable 1: Enable
				Bit[5]: RAW gamma enable 0: Disable 1: Enable
				Bit[2]: Black pixel cancellation enable 0: Disable 1: Enable
				Bit[1]: White pixel cancellation enable 0: Disable 1: Enable
0x5001	ISP CONTROL 01	0x01	RW	Bit[0]: Color interpolation (CIP) enable 0: Disable 1: Enable
				ISP Control 01
				Bit[7]: Special Digital Effects (SDE) enable 0: Disable 1: Enable
				Bit[5]: Scaling enable 0: Disable 1: Enable
				Bit[2]: UV average enable 0: Disable 1: Enable
				Bit[1]: Color matrix enable 0: Disable 1: Enable
				Bit[0]: Auto white balance (AWB) enable 0: Disable 1: Enable

table 5-1 ISP general control registers (sheet 2 of 3)

address	register name	default value	R/W	description
0x5003	ISP CONTROL 03	0x08	RW	ISP Control 03
				Bit[2]: Bin enable 0: Disable 1: Enable
				Bit[1]: Draw window for AFC enable 0: Disable 1: Enable
				Bit[0]: Solarize enable 0: Disable 1: Enable
0x5005	ISP CONTROL 05	0x36	RW	ISP Control 05
				Bit[6]: AWB bias manual enable 0: Disable 1: Enable
				Bit[5]: AWB bias on enable 0: Disable 1: Enable
				Bit[4]: AWB bias plus enable 0: Disable 1: Enable
				Bit[2]: LENC bias on enable 0: Disable 1: Enable
				Bit[1]: GMA bias on enable 0: Disable 1: Enable
0x501E	ISP MISC	0x00	RW	Bit[0]: LENC bias manual enable 0: Disable 1: Enable
				Bit[6]: Scale ratio manual enable

table 5-1 ISP general control registers (sheet 3 of 3)

address	register name	default value	R/W	description
0x5020	DITHER CTRL 0	0x00	RW	RGB Dither Control
				Bit[6]: Dither register control selection enable
				0: From register control
				1: From system control
				Bit[5:4]: R channel register control when 0x501E[6] = 0
0x5020	DITHER CTRL 0	0x00	RW	00: Not allowed
				01: RGB444
				10: RGB565/555
				11: Not allowed
				Bit[3:2]: G channel register control when 0x501E[6] = 0
0x5020	DITHER CTRL 0	0x00	RW	00: Not allowed
				01: RGB444
				10: RGB565/555
				11: Not allowed
				Bit[1:0]: B channel register control when 0x501E[6] = 0
0x5020	DITHER CTRL 0	0x00	RW	00: Not allowed
				01: RGB444
				10: RGB565/555
				11: Not allowed

5.2 lens correction (LENC)

The main purpose of the LENC is to compensate for lens imperfection. According to the area where each pixel is located, the module calculates a gain for the pixel, correcting each pixel with its gain calculated to compensate for the light distribution due to lens curvature. The LENC correcting curve automatic calculation according sensor gain is also added so that the LENC can adapt with the sensor gain. Also, the LENC supports the subsample function in both horizontal and vertical directions. Contact your local OmniVision FAE for lens correction settings (registers 0x5800~0x5849).

table 5-2 LENC control registers (sheet 1 of 2)

address	register name	default value	R/W	description	
0x5000	ISP CONTROL 00	0x06	RW	Bit[7]:	LENC correction enable 0: Disable 1: Enable
0x5842	BR HSCALE	0x01	RW	Bit[2:0]:	br h scale[10:8] Reciprocal of horizontal step for BR channel. BR channel in whole image is divided into 5x5 blocks. The step is used to point to the border of the adjacent block
0x5843	BR HSCAL	0x2B	RW	Bit[7:0]:	br h scale[7:0] Reciprocal of horizontal step for BR channel. BR channel in whole image is divided into 5x5 blocks. The step is used to point to the border of the adjacent block
0x5844	BR VSCALE	0x01	RW	Bit[2:0]:	br v scale[10:8] Reciprocal of vertical step for BR channel. BR channel in whole image is divided into 5x5 blocks. The step is used to point to the border of the adjacent block
0x5845	BR VSCALE	0x8D	RW	Bit[7:0]:	br v scale[7:0] Reciprocal of vertical step for BR channel. BR channel in whole image is divided into 5x5 blocks. The step is used to point to the border of the adjacent block
0x5846	G HSCALE	0x01	RW	Bit[2:0]:	g h scale[10:8] Reciprocal of horizontal step for G channel. G channel in whole image is divided into 6x6 blocks. The step is used to point to the border of the adjacent block

table 5-2 LENC control registers (sheet 2 of 2)

address	register name	default value	R/W	description
0x5847	G HSCAL	0x8F	RW	Bit[7:0]: g h scale[7:0] Reciprocal of horizontal step for G channel. G channel in whole image is divided into 6x6 blocks. The step is used to point to the border of the adjacent block
0x5848	G VSCALE	0x01	RW	Bit[2:0]: g v scale[10:8] Reciprocal of vertical step for G channel. G channel in whole image is divided into 6x6 blocks. The step is used to point to the border of the adjacent block
0x5849	G VSCALE	0x09	RW	Bit[7:0]: g v scale[7:0] Reciprocal of vertical step for G channel. G channel in whole image is divided into 6x6 blocks. The step is used to point to the border of the adjacent block

5.3 auto white balance (AWB)

The main function of Auto White Balance (AWB) is the process of removing unrealistic color casts so that objects which appear white in person are rendered white in the image or video. Thus, the AWB makes sure that the white color is always a white color in different color temperatures. It supports manual white balance and auto white balance. For auto white balance, simple AWB and advanced AWB methods are supplied. Advance AWB takes into account the *color temperature* of a light source. For advanced AWB settings, contact your local OmniVision FAE.

table 5-3 AWB control registers (sheet 1 of 2)

address	register name	default value	R/W	description
0x5001	ISP CONTROL 01	0x01	RW	Bit[0]: Auto white balance enable 0: Disable 1: Enable
0x5181	AWB CONTROL 01	0x58	RW	Bit[7:6]: Step local Bit[5:4]: Step fast Bit[3]: Slop 8x Bit[2]: Slop 4x Bit[1]: One zone Bit[0]: AVG all
0x5182	AWB CONTROL 02	0x11	RW	Bit[7:4]: Maximum local counter Bit[3:0]: Maximum fast counter
0x5183	AWB CONTROL 03	0x90	RW	Bit[7]: AWB simple enable 0: AWB advance 1: AWB simple Bit[6]: YUV enable 1: Simple YUV enable Bit[5]: AWB preset Bit[4]: AWB simf Bit[3:2]: AWB win
0x5184	AWB CONTROL 04	0x25	RW	Bit[7:6]: Counter area selection Bit[5]: G enable Bit[4:2]: Counter limit control Bit[1:0]: Counter threshold
0x5185	AWB CONTROL 05	0x24	RW	Bit[7:4]: Stable range unstable Threshold for unstable to stable change Bit[3:0]: Stable range stable Threshold for stable to un-stable change
0x5186~ 0x5190	AWB CONTROL	–	–	Advanced AWB Control Registers
0x5191	AWB CONTROL 17	0xFF	RW	Bit[7:0]: AWB top limit
0x5192	AWB CONTROL 18	0x00	RW	Bit[7:0]: AWB bottom limit
0x5193	AWB CONTROL 19	0xF0	RW	Bit[7:0]: Red limit

table 5-3 AWB control registers (sheet 2 of 2)

address	register name	default value	R/W	description	
0x5194	AWB CONTROL 20	0xF0	RW	Bit[7:0]:	Green limit
0x5195	AWB CONTROL 21	0xF0	RW	Bit[7:0]:	Blue limit
0x5196	AWB CONTROL 22	0x03	RW	Bit[5]: Bit[3:2]: 00: AWB simple from after AWB gain 01: AWB simple from after RAW GMA 10: AWB simple from after AWB gain 11: AWB simple from after RAW GMA Bit[1]: Bit[0]:	AWB freeze AWB simple selection Fast enable AWB bias stat
0x5197	AWB CONTROL 23	0x02	RW	Bit[7:0]:	Local limit
0x519E	AWB CONTROL 30	0x00	RW	Bit[3]: Bit[2]:	Local limit select Simple stable select
0x519F	AWB CURRENT R GAIN	—	R	Bit[3:0]:	Current R setting[11:8]
0x51A0	AWB CURRENT R GAIN	—	R	Bit[7:0]:	Current R setting[7:0]
0x51A1	AWB CURRENT G GAIN	—	R	Bit[3:0]:	Current G setting[11:8]
0x51A2	AWB CURRENT G GAIN	—	R	Bit[7:0]:	Current G setting[7:0]
0x51A3	AWB CURRENT B GAIN	—	R	Bit[3:0]:	Current B setting[11:8]
0x51A4	AWB CURRENT B GAIN	—	R	Bit[7:0]:	Current B setting[7:0]
0x51A5	AWB AVERAGE B	—	R	Bit[7:0]:	Average r[9:2]
0x51A6	AWB AVERAGE B	—	R	Bit[7:0]:	Average g[9:2]
0x51A7	AWB AVERAGE B	—	R	Bit[7:0]:	Average b[9:2]
0x51D0	AWB CONTROL74	—	R	Bit[5]: Bit[4]: Bit[3]: Bit[2:1]:	R large G large B large Current type

5.4 raw gamma

The main purpose of the Gamma (GMA) function is to compensate for the non-linear characteristics of the sensor. GMA converts the pixel values according to the Gamma curve to compensate the sensor output under different light strengths. The non-linear gamma curve is approximately constructed with different linear functions. Raw gamma compensates the image in the RAW domain.

table 5-4 raw gamma control registers

address	register name	default value	R/W	description
0x5000	ISP CONTROL 00	0x06	RW	Bit[5]: Raw gamma enable 0: Disable GMA 1: Enable GMA
0x5001	ISP CONTROL 01	0x01	RW	Bit[7]: Special digital effect enable 0: Disable 1: Enable
0x5481	GAMMA YST00	0x26	RW	Bit[7:0]: Y yst 00
0x5482	GAMMA YST01	0x35	RW	Bit[7:0]: Y yst 01
0x5483	GAMMA YST02	0x48	RW	Bit[7:0]: Y yst 02
0x5484	GAMMA YST03	0x57	RW	Bit[7:0]: Y yst 03
0x5485	GAMMA YST04	0x63	RW	Bit[7:0]: Y yst 04
0x5486	GAMMA YST05	0x6E	RW	Bit[7:0]: Y yst 05
0x5487	GAMMA YST06	0x77	RW	Bit[7:0]: Y yst 06
0x5488	GAMMA YST07	0x80	RW	Bit[7:0]: Y yst 07
0x5489	GAMMA YST08	0x88	RW	Bit[7:0]: Y yst 08
0x548A	GAMMA YST09	0x96	RW	Bit[7:0]: Y yst 09
0x548B	GAMMA YST0A	0xA3	RW	Bit[7:0]: Y yst 0A
0x548C	GAMMA YST0B	0xAF	RW	Bit[7:0]: Y yst 0B
0x548D	GAMMA YST0C	0xC5	RW	Bit[7:0]: Y yst 0C
0x548E	GAMMA YST0D	0xD7	RW	Bit[7:0]: Y yst 0D
0x548F	GAMMA YST0E	0xE8	RW	Bit[7:0]: Y yst 0E
0x5490	GAMMA YST0F	0x0F	RW	Bit[7:0]: Y yst 0F

5.5 defect pixel cancellation (DPC)

Due to processes and other reasons, pixel defects in the sensor array will occur. Thus, these bad or wounded pixels will generate wrong color values. The main purpose of Defect Pixel Cancellation (DPC) function is to remove the effect caused by these bad or wounded pixels. Also, some special functions are available for those pixels located at the image boundary. To remove the defect pixel effect correctly, the proper threshold should first be determined.

table 5-5 DPC control registers

address	register name	default value	R/W	description
0x5000	ISP CONTROL 00	0x06	RW	Bit[2]: Black pixel cancellation enable 0: Disable 1: Enable Bit[1]: White pixel cancellation enable 0: Disable 1: Enable

5.6 color interpolation (CIP)

The CIP functions include de-noising of raw images, RAW to RGB interpolation, and edge enhancement. In sensor RAW format, each pixel will be either R, G or B. CIP will calculate the other two color values using the neighboring pixel of the same color. Thus, we can get the full RGB information for each pixel. For edge enhancement, the OV5640 provides both manual and auto modes.

table 5-6 CIP control registers

address	register name	default value	R/W	description
0x5000	ISP CONTROL 00	0x06	RW	Bit[0]: Color interpolation enable 0: Disable 1: Enable
0x5301	CIP SHARPENMT THRESHOLD 2	0x48	RW	Color Interpolation Sharpen MT Threshold 2
0x5302	CIP SHARPENMT OFFSET1	0x18	RW	CIP Sharpen MT Offset1 (Y edge mt manual setting when 0x5308[6]=1)
0x5303	CIP SHARPENMT OFFSET2	0x0E	RW	CIP Sharpen MT Offset2
0x5304	CIP DNS THRESHOLD 1	0x08	RW	CIP DNS Threshold 1
0x5305	CIP DNS THRESHOLD 2	0x48	RW	CIP DNS Threshold 2
0x5306	CIP DNS OFFSET1	0x09	RW	CIP DNS Offset1 (DNS threshold manual setting when 0x5308[4]=1)
0x5307	CIP DNS OFFSET2	0x16	RW	CIP DNS Offset2
0x5308	CIP CTRL	0x25	RW	Bit[6]: CIP edge MT manual enable Bit[4]: CIP DNS manual enable Bit[2:0]: CIP threshold for BR sharpen
0x5309	CIP SHARPENTH THRESHOLD 1	0x08	RW	CIP Sharpen TH Threshold 1
0x530A	CIP SHARPENTH THRESHOLD 2	0x48	RW	CIP Sharpen TH Threshold 2
0x530B	CIP SHARPENTH OFFSET1	0x04	RW	CIP Sharpen TH Offset1 (Sharpen threshold manual setting when 0x5308[6]=1)
0x530C	CIP SHARPENTH OFFSET2	0x06	RW	CIP Sharpen TH Offset2
0x530D	CIP EDGE MT AUTO	–	R	CIP Edge MT Auto Read
0x530E	CIP DNS THRESHOLD AUTO	–	R	CIP DNS Threshold Auto Read
0x530F	CIP SHARPEN THRESHOLD AUTO	–	R	CIP Sharpen Threshold Auto Read

5.7 color matrix (CMX)

The main purpose of the Color Matrix (CMX) function is to cancel out crosstalk and convert color space. Given the color correction matrix, CCM, and RGB to YUV conversion matrix, RGB2YUV, the combined matrix is:

$$\text{CMX} = \begin{bmatrix} \text{cmx00} & \text{cmx01} & \text{cmx02} \\ \text{cmx10} & \text{cmx11} & \text{cmx12} \\ \text{cmx20} & \text{cmx21} & \text{cmx22} \end{bmatrix} = \text{RGB2YUV} \times \text{CCM} \times \begin{bmatrix} 1 & -0.25 & 0.75 \\ 1 & -0.25 & -0.25 \\ 1 & 0.75 & -0.25 \end{bmatrix}$$

$$\text{where } \begin{bmatrix} R \\ G \\ B \end{bmatrix} = \text{CCM} \begin{bmatrix} R_0 \\ G_0 \\ B_0 \end{bmatrix}$$

The CMX is then normalized by $2^{0x5394[3:0]}$.

table 5-7 CMX control registers

address	register name	default value	R/W	description
0x5001	ISP CONTROL 01	0x01	RW	Bit[1]: Color matrix enable 0: Disable 1: Enable
0x5382	CMX2	0x64	RW	Bit[7:0]: CMX2 for Y
0x5383	CMX3	0x08	RW	Bit[7:0]: CMX3 for Y
0x5384	CMX4	0x30	RW	Bit[7:0]: CMX4 for U
0x5385	CMX5	0x90	RW	Bit[7:0]: CMX5 for U
0x5386	CMX6	0xC0	RW	Bit[7:0]: CMX6 for U
0x5387	CMX7	0xA0	RW	Bit[7:0]: CMX7 for V
0x5388	CMX8	0x98	RW	Bit[7:0]: CMX8 for V
0x5389	CMX9	0x08	RW	Bit[7:0]: CMX9 for V
0x538A	CMXSIGN	0x01	RW	Cmxsign Bit[0]: CMX9 sign
0x538B	CMXSIGN	0x98	RW	Cmxsign Bit[7]: CMX8 sign Bit[6]: CMX7 sign Bit[5]: CMX6 sign Bit[4]: CMX5 sign Bit[3]: CMX4 sign Bit[2]: CMX3 sign Bit[1]: CMX2 sign Bit[0]: CMX1 sign

5.8 UV average

The main function of the UV average is to average the U/V channel value using special filters.

table 5-8 UV average register

address	register name	default value	R/W	description
0x5001	ISP CONTROL 01	0x4F	RW	Bit[2]: UV average enable 0: Disable 1: Enable

5.9 scaling

The main purpose of the scaling function is to zoom out the image. According to the new width and new height of the new image, the module uses the values of several pixels to generate the values of one pixel. The values of some pixels are divided and used in two or more adjacent pixels. The scaling function supports up to 32x scale.

table 5-9 UV average register

address	register name	default value	R/W	description
0x5001	ISP CONTROL 01	0x01	RW	Bit[5]: Scale enable 0: Disable 1: Enable
0x5601	SCALE CTRL 1	0x00	RW	Bit[6:4]: HDIV RW DCW scale times 000: DCW 1 time 001: DCW 2 time 010: DCW 4 time 100: DCW 8 time 101: DCW 16 time Others: DCW 16 time Bit[2:0]: VDIV RW DCW scale times 000: DCW 1 time 001: DCW 2 time 010: DCW 4 time 100: DCW 8 time 101: DCW 16 time Others: DCW 16 time
0x5602	SCALE CTRL 2	0x02	RW	XSC High Bits
0x5603	SCALE CTRL 3	0x00	RW	XSC Low Bits
0x5604	SCALE CTRL 4	0x02	RW	YSC High Bits
0x5605	SCALE CTRL 5	0x00	RW	YSC Low Bits
0x5606	SCALE CTRL 6	0x00	RW	Bit[3:0]: Voffset

5.10 UV adjust

The main function of the UV adjust is to adjust the U/V channel value according to sensor gain. It supports both manual and auto modes.

The UV adjust function is integrated in SDE. The main function of the UV adjust is to adjust the U/V channel value according to sensor gain. It supports both manual and auto modes

5.10.1 manual mode

By setting SDE CTRL 0 [1] (0x5580) to 1 and SDE CTRL 8 0x5588[6] to 1, UV adjust is controlled only by register SAT U (0x5583[7:0]) and SAT V (0x5584[7:0]) for U and V gains.

5.10.2 auto mode

When the UV adjust is set for auto mode (0x5580[1]=1 and 0x5588[6]=0), the UV adjust curve parameters (see **figure 5-1**) should be entered into the corresponding registers. The UV adjust parameters, UV adj th1, UV adj th2, and offset low, offset high should be entered into the registers to set the curve. To get these values, first set the values of UV adj th1, UV adj th2, offset low and offset high. Then, calculate the values of a and k as follows:

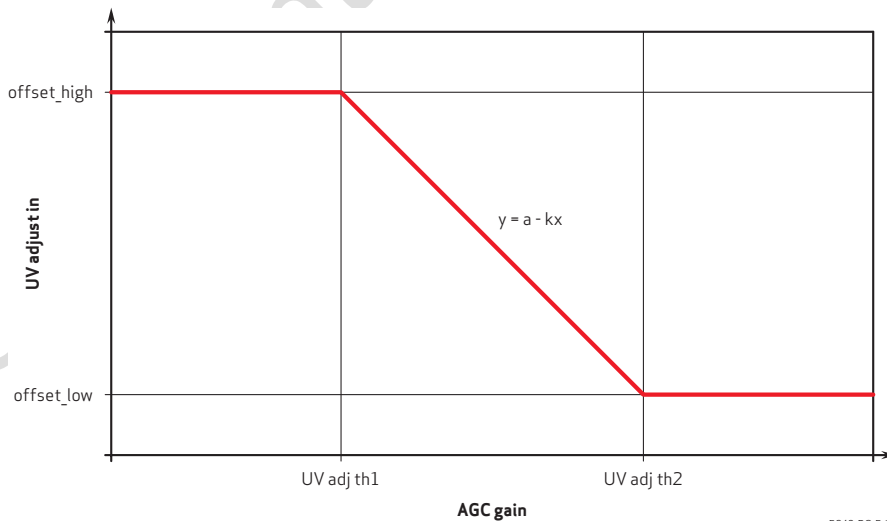
$$k = (\text{offset high} - \text{offset low}) / (\text{UV adj th2} - \text{UV adj th1})$$

$$a = \text{offset high} + (\text{offset high} - \text{offset low}) / (\text{UV adj th2} - \text{UV adj th1})$$

Registers to be changed:

- UV adj th1[8:0] = registers 0x5589[7:0]
- UV adj th2[8:0] = registers {0x558A[0], 0x558B[7:0]}
- offset high = register 0x5583[7:0] (when 0x5580[1]=1 and 0x5588[6]=0)
- offset low = register 0x5584[7:0] (when 0x5580[1]=1 and 0x5588[6]=0)

figure 5-1 UV adjust graph



5.11 special digital effects (SDE)

The Special Digital Effects (SDE) functions include hue/saturation control, brightness, contrast, etc. SDE also supports negative, black/white, sepia, greenish, blueish, redish, solarize and other image effects.

table 5-10 SDE control registers

address	register name	default value	R/W	description
0x5001	ISP CONTROL 01	0x01	RW	Bit[7]: Special digital effect enable 0: Disable 1: Enable
0x5581	SDE CTRL1	0x80	RW	Bit[7:0]: Hue cos coefficient
0x5582	SDE CTRL2	0x00	RW	Bit[7:0]: Hue sin coefficient
0x5583	SDE CTRL3	0x40	RW	Bit[7:0]: Saturation U when 0x5580[1]=1 and 0x5588[6]=1, max value for UV adjust when 0x5580[1]=1 and 0x5588[6]=0; or fixed U when 0x5580[3]=1
0x5584	SDE CTRL4	0x40	RW	Bit[7:0]: Saturation V when 0x5580[1]=1 and 0x5588[6]=1, min value for UV adjust when 0x5580[1]=1 and 0x5588[6]=0; or Vreg when 0x5580[4]=1
0x5585	SDE CTRL5	0x00	RW	Bit[7:0]: Yoffset for contrast when 0x5044[3]=1; or fixed Y when 0x5580[7]=1
0x5586	SDE CTRL6	0x20	RW	Bit[7:0]: Y gain for contrast
0x5587	SDE CTRL7	0x00	RW	Bit[7:0]: Y bright for contrast
0x5588	SDE CTRL8	0x01	RW	Bit[6]: UV adjust manual enable Bit[5]: Sign5 for hue V, cos Bit[4]: Sign4 for hue U, cos Bit[3]: Sign3 Y bright sign for contrast 0: Keep Y bright sign 1: Negative Y bright sign Bit[2]: Sign2 Y offset sign for contrast when 0x5044[3]=1 0: Keep Y offset sign 1: Negative Y offset sign Bit[1]: Sign1 for hue V, sin Bit[0]: Sign0 for hue U, sin
0x5589	SDE CTRL9	0x01	RW	Bit[7:0]: UV adjust threshold 1 Valid when 0x5580[1]=1
0x558A	SDE CTRL10	0x01	RW	Bit[0]: UV adjust threshold 2[8] Valid when 0x5580[1]=1
0x558B	SDE CTRL11	0xFF	RW	Bit[7:0]: UV adjust threshold 2[7:0] Valid when 0x5580[1]=1
0x558C	SDE CTRL12	—	R	Bit[7:0]: UV adjust value read out

5.12 ISP format

table 5-11 ISP format control registers

address	register name	default value	R/W	description
0x501F	FORMAT MUX CONTROL	0x00	RW	Format MUX Control Bit[2:0]: Format selection 000: ISP YUV422 001: ISP RGB 010: ISP dither 011: ISP RAW (DPC) 100: SNR RAW 101: ISP RAW (CIP)

5.13 draw window

The draw window module is used to display a window on top of live video. It is usually used by autofocus to display a focus window.

table 5-12 draw window registers (sheet 1 of 2)

address	register name	default value	R/W	description
0x5003	ISP CONTROL 03	0x08	RW	Bit[1]: Draw window for AFC enable 0: Disable 1: Enable
0x501F	FORMAT MUX CONTROL	0x00	RW	Bit[2:0]: Format select 000: ISP YUV422 001: ISP RGB 010: ISP dither 011: ISP RAW (DPC) 100: SNR RAW 101: ISP RAW (CIP)
0x5027	DRAW WINDOW CONTROL 00	0x02	RW	Bit[0]: Draw window control 0: No fixed Y 1: Fixed Y
0x5028	DRAW WINDOW LEFT POSITION CONTROL	0x04	RW	Bit[3:0]: Draw window left[11:8] high byte
0x5029	DRAW WINDOW LEFT POSITION CONTROL	0x90	RW	Bit[7:0]: Draw window left[7:0] low byte
0x502A	DRAW WINDOW RIGHT POSITION CONTROL	0x05	RW	Bit[3:0]: Draw window right[11:8] high byte
0x502B	DRAW WINDOW RIGHT POSITION CONTROL	0x90	RW	Bit[7:0]: Draw window right[7:0] low byte

table 5-12 draw window registers (sheet 2 of 2)

address	register name	default value	R/W	description
0x502C	DRAW WINDOW TOP POSITION CONTROL	0x03	RW	Bit[2:0]: Draw window top[10:8] high byte
0x502D	DRAW WINDOW TOP POSITION CONTROL	0x6C	RW	Bit[7:0]: Draw window top[7:0] low byte
0x502E	DRAW WINDOW BOTTOM POSITION CONTROL	0x04	RW	Bit[2:0]: Draw window bottom[10:8] high byte
0x502F	DRAW WINDOW BOTTOM POSITION CONTROL	0x2C	RW	Bit[7:0]: Draw window bottom[7:0] low byte
0x5030	DRAW WINDOW HORIZONTAL BOUNDARY WIDTH CONTROL	0x00	RW	Bit[3:0]: Draw window horizontal boundary width[11:8] high byte
0x5031	DRAW WINDOW HORIZONTAL BOUNDARY WIDTH CONTROL	0x14	RW	Bit[7:0]: Draw window horizontal boundary width[7:0] low byte
0x5032	DRAW WINDOW VERTICAL BOUNDARY WIDTH CONTROL	0x00	RW	Bit[2:0]: Draw window vertical boundary width[10:8] high byte
0x5033	DRAW WINDOW VERTICAL BOUNDARY WIDTH CONTROL	0x14	RW	Bit[7:0]: Draw window vertical boundary width[7:0] low byte
0x5034	DRAW WINDOW Y CONTROL	0x80	RW	Bit[7:0]: Fixed Y for draw window
0x5035	DRAW WINDOW U CONTROL	0x2A	RW	Bit[7:0]: Fixed U for draw window
0x5036	DRAW WINDOW V CONTROL	0x14	RW	Bit[7:0]: Fixed V for draw window

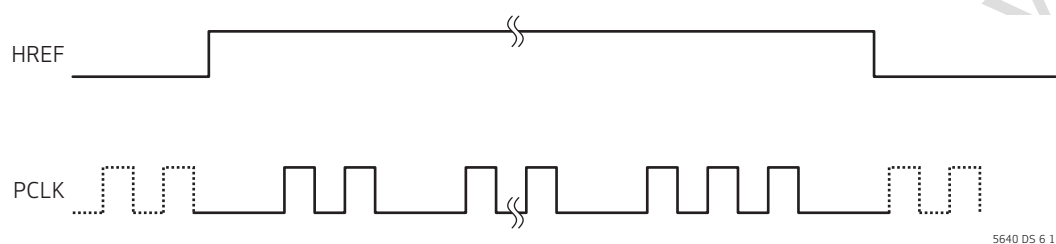
6 image sensor output interface digital functions

6.1 compression engine

6.1.1 compression mode 1 timing

The whole frame has only one line. PCLK will be gated when there is no valid image data transmitted.

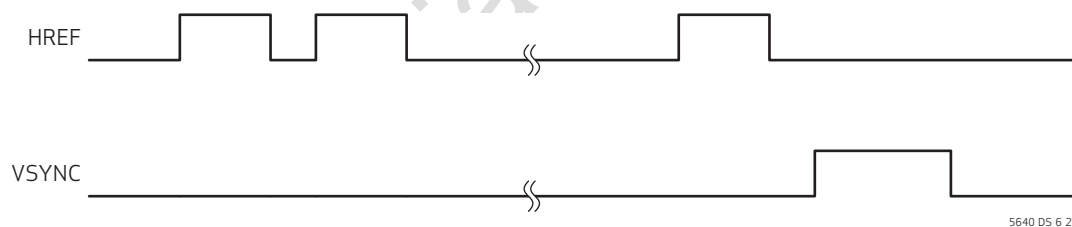
figure 6-1 compression mode 1 timing



6.1.2 compression mode 2 timing

Compression data is transmitted with programmable line width. PCLK is free running. The last line may contain dummy data to match the width. By default, the line number varies from frame to frame. The user can set register 4600[5] (0x4600) to ensure every frame has a fixed line number (programmable).

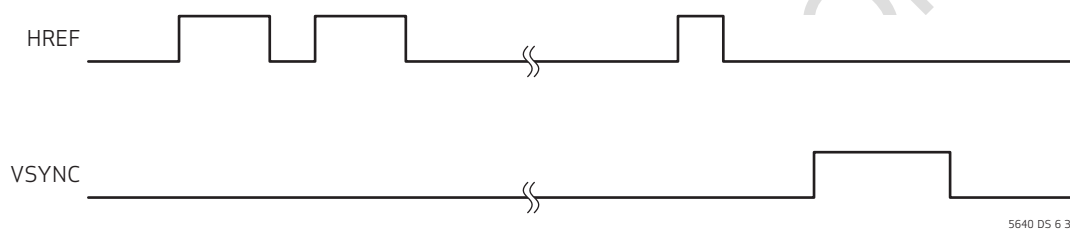
figure 6-2 compression mode 2 timing



6.1.3 compression mode 3 timing

Compression data is transmitted with programmable width. The last line width maybe different from the other line (there is no dummy data). In each frame, the line number may be different.

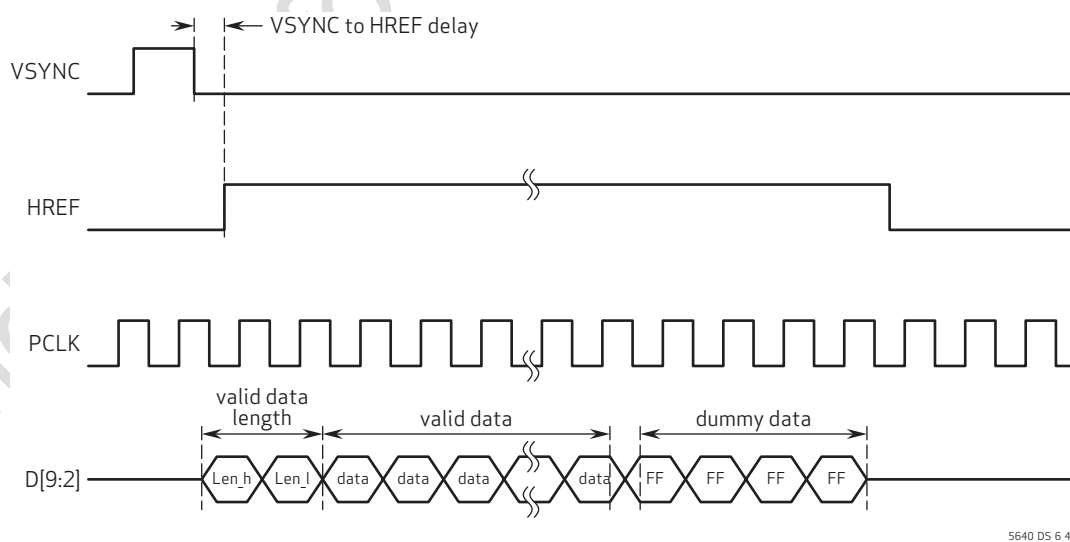
figure 6-3 compression mode 3 timing



6.1.4 compression mode 4 timing

The width and height are fixed in each frame. The first two bytes are valid data length in every line, followed by valid image data. Dummy data (0xFF) may be used as padding at each line end if the current valid image data is less than the line width.

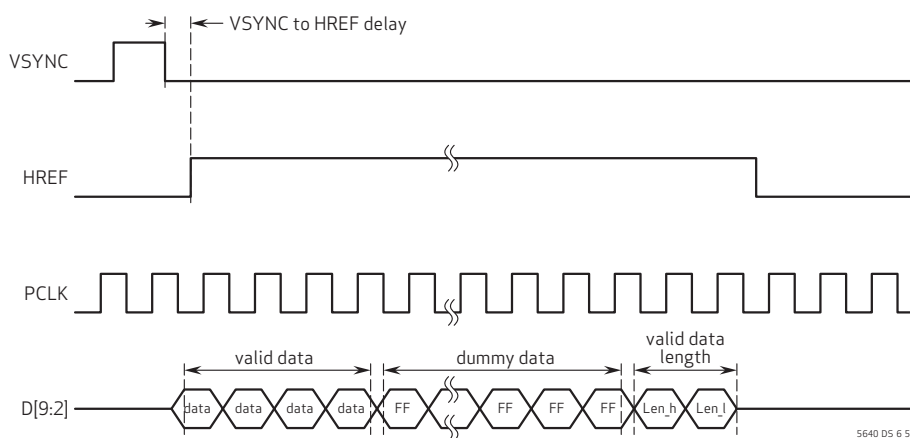
figure 6-4 compression mode 4 timing



6.1.5 compression mode 5 timing

The width and height are fixed in each frame. Every line begins with valid image data. Dummy data may be used as padding at each line end if the current valid image data is less than the line width. The last two bytes of every line is valid data length.

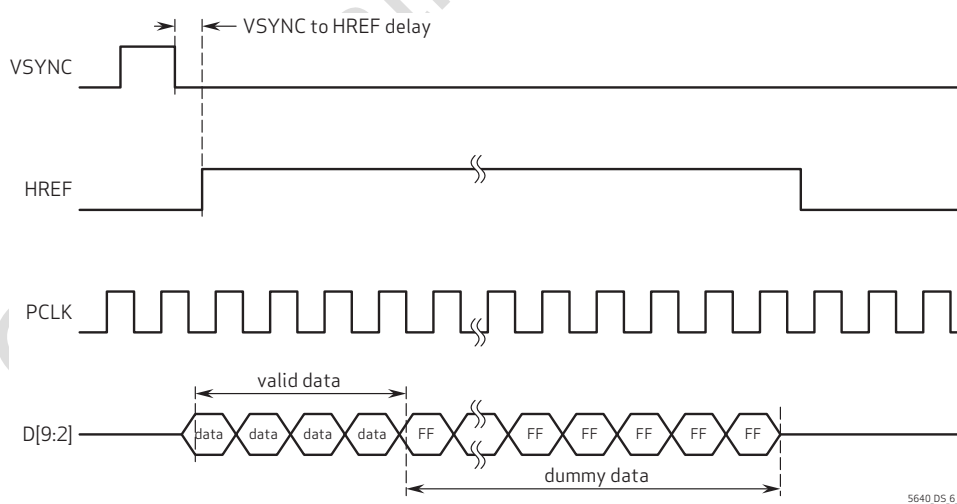
figure 6-5 compression mode 5 timing



6.1.6 compression mode 6 timing

The width and height are fixed in each frame. Every line begins with valid image data. Dummy data may be used as padding at each line end if the current valid image data less than the line width.

figure 6-6 compression mode 6 timing



6.1.7 compression mode control

table 6-1 compression control registers (sheet 1 of 2)

address	register name	default value	R/W	description	
0x3821	COMPRESSION ENABLE	0x00	RW	Bit[5]:	JPEG enable
0x4600	VFIFO CTRL00	0x80	RW	Bit[5]:	JPEG output fixed height enable 0: In JPEG mode2 JPEG height is different in each frame 1: In JPEG mode2 JPEG height is fixed in each frame
0x4602	VFIFO HSIZE	0x04	RW	JPEG Output Width High Byte	
0x4603	VFIFO HSIZE	0x00	RW	JPEG Output Width Low Byte	
0x4604	VFIFO VSIZE	0x03	RW	JPEG Output Height High Byte	
0x4605	VFIFO HSIZE	0x00	RW	JPEG Output Height Low Byte	
0x460C	VFIFO CTRL0C	0x20	RW	Bit[7:4]:	JPEG dummy data pad speed
0x460D	VFIFO CTRL0D	0x00	RW	JPEG PAD Dummy Data	
0x4713	JPG MODE SELECT	0x02	RW	Bit[2:0]:	JPEG mode select 001: JPEG mode 1 010: JPEG mode 2 011: JPEG mode 3 100: JPEG mode 4 101: JPEG mode 5 110: JPEG mode 6
0x471F	DVP HREF CTRL	0x40	RW	HREF Minimum Blanking in JPEG Mode23	
0x4723	DVP CTRL23	0x00	RW	DVP JPEG Mode456 Skip Line Number	
0x4400	JPEG CTRL00	0x81	RW	Bit[7]:	input_format 0: YUV420 1: YUV422
				Bit[6:0]:	JFIFO read speed control
0x4401	JPEG CTRL01	0x01	RW	Bit[7:4]:	SFIFO output buffer speed control
				Bit[3]:	Read SRAM enable when blanking 0: Disable 1: Enable
				Bit[2]:	Read SRAM at first blanking 0: Disable 1: Enable
				Bit[1:0]:	SFIFO read speed control

table 6-1 compression control registers (sheet 2 of 2)

address	register name	default value	R/W	description
0x4404	JPEG CTRL04	0x24	RW	Bit[7]: jfifo_pwrn Bit[6]: SFIFO pwrn Bit[5]: Header output enable Bit[4]: Enable gated clock 0: Disable gated clock 1: Enable gated clock Bit[3]: Substitute 0xFF to 0xFE in QT Bit[2:0]: Quantization rounding Bias: set value = Bias/8
0x4417	JFIFO OVERFLOW	–	R	Bit[0]: JFIFO overflow indicator

6.2 system control

System control registers include clock, reset control, and PLL configure. Individual modules can be reset or clock gated by setting the appropriate registers.

table 6-2 system control registers (sheet 1 of 3)

address	register name	default value	R/W	description
0x3000	SYSTEM RESET00	0x30	RW	Reset for Individual Block (0: enable block; 1: reset block) Bit[7]: Reset BIST Bit[6]: Reset MCU program memory Bit[5]: Reset MCU Bit[4]: Reset OTP Bit[3]: Reset STB Bit[2]: Reset d5060 Bit[1]: Reset timing control Bit[0]: Reset array control
0x3001	SYSTEM RESET01	0x08	RW	Reset for Individual Block (0: enable block; 1: reset block) Bit[7]: Reset AWB registers Bit[6]: Reset AFC Bit[5]: Reset ISP Bit[4]: Reset FC Bit[3]: Reset S2P Bit[2]: Reset BLC Bit[1]: Reset AEC registers Bit[0]: Reset AEC

table 6-2 system control registers (sheet 2 of 3)

address	register name	default value	R/W	description
0x3002	SYSTEM RESET02	0x1C	RW	Reset for Individual Block (0: enable block; 1: reset block) Bit[7]: Reset VFIFO Bit[5]: Reset format Bit[4]: Reset JFIFO Bit[3]: Reset SFIFO Bit[2]: Reset JPG Bit[1]: Reset format MUX Bit[0]: Reset average
0x3003	SYSTEM RESET03	0x00	RW	Reset for Individual Block (0: enable block; 1: reset block) Bit[5]: Reset digital gain compensation Bit[4]: Reset SYNC FIFO Bit[3]: Reset PSRAM Bit[2]: Reset ISP FC Bit[1]: Reset MIPI Bit[0]: Reset DVP
0x3004	CLOCK ENABLE00	0xCF	RW	Clock Enable Control (0: disable clock; 1: enable clock) Bit[7]: Enable BIST clock Bit[6]: Enable MCU program memory clock Bit[5]: Enable MCU clock Bit[4]: Enable OTP clock Bit[3]: Enable STROBE clock Bit[2]: Enable D5060 clock Bit[1]: Enable timing control clock Bit[0]: Enable array control clock
0x3005	CLOCK ENABLE01	0xF7	RW	Clock Enable Control (0: disable clock; 1: enable clock) Bit[7]: Enable AWB register clock Bit[6]: Enable AFC clock Bit[5]: Enable ISP clock Bit[4]: Enable FC clock Bit[3]: Enable S2P clock Bit[2]: Enable BLC clock Bit[1]: Enable AEC register clock Bit[0]: Enable AEC clock
0x3006	CLOCK ENABLE02	0xE3	RW	Clock Enable Control (0: disable clock; 1: enable clock) Bit[7]: Enable PSRAM clock Bit[6]: Enable FMT clock Bit[5]: Enable JPEG 2x clock Bit[3]: Enable JPEG clock Bit[1]: Enable format MUX clock Bit[0]: Enable average clock

table 6-2 system control registers (sheet 3 of 3)

address	register name	default value	R/W	description
0x3007	CLOCK ENABLE03	0xFF	RW	Clock Enable Control (0: disable clock; 1: enable clock) Bit[7]: Enable digital gain compensation clock Bit[6]: Enable SYNC FIFO clock Bit[5]: Enable ISPFC SCLK clock Bit[4]: Enable MIPI PCLK clock Bit[3]: Enable MIPI clock Bit[2]: Enable DVP PCLK clock Bit[1]: Enable VFIFO PCLK clock Bit[0]: Enable VFIFO SCLK clock
0x3008	SYSTEM CTROL0	0x02	RW	System Control Bit[7]: Software reset Bit[6]: Software power down
0x3034	SC PLL CONTRL0	0x1A	RW	Bit[6:4]: PLL charge pump control Bit[3:0]: MIPI bit mode 0x8: 8-bit mode 0xA: 10-bit mode
0x3035	SC PLL CONTRL1	0x11	RW	Bit[7:4]: System clock divider Slow down all clocks Bit[3:0]: Scale divider for MIPI MIPI PCLK/SERCLK can be slowed down
0x3036	SC PLL CONTRL2	0x69	RW	Bit[7:0]: PLL multiplier (4~252) Can be any integer for 4~127 and only even integer for 128~252
0x3037	SC PLL CONTRL3	0x03	RW	Bit[4]: PLL root divider 0: Bypass 1: Divided by 2 Bit[3:0]: PLL pre-divider 1, 2, 3, 4, 6, 8
0x3039	SC PLL CONTRL5	0x00	RW	Bit[7]: PLL bypass

6.3 microcontroller unit (MCU)

The MCU firmware can be downloaded by writing to registers starting from 0x8000. A total of 6 KB of program memory can be used for program storage. Before downloading the firmware, the user must enable the MCU clock by setting register 0x3000[5] to 1'b1. After downloading the firmware, set register 0x3000[5] to 1'b0 to enable the MCU. The MCU interrupts are triggered by several internal signals for firmware development.

table 6-3 MCU control registers (sheet 1 of 2)

address	register name	default value	R/W	description
0x3F00	MC CTRL 00	0x00	RW	Bit[0]: MCU soft reset 1: Reset MCU
0x3F01	MC INTERRUPT MASK0	0x00	RW	Mask0 for Interrupt (0: disable interrupt bit; 1: enable interrupt bit) Bit[7]: JFIFO over flow Bit[6]: JFIFO end of image Bit[5]: ISP end of frame Bit[4]: ISP start of frame Bit[3]: AFC done Bit[2]: AWB done Bit[1]: VFIFO full Bit[0]: VFIFO empty
0x3F02	MC INTERRUPT MASK1	0x00	RW	Mask1 for Interrupt (0: disable interrupt bit; 1: enable interrupt bit) Bit[7]: AEC done Bit[6]: ISP average done Bit[5]: AEC trigger Bit[4]: JPG over size Bit[3]: SRM operation start Bit[2]: SRM operation done Bit[1]: DVP frame counter change Bit[0]: BLC start of frame
0x3F03	MC READ INTERRUPT ADDRESS	0x70	RW	Bit[7:0]: Set high byte for SCCB address that will trigger interrupt when read
0x3F04	MC READ INTERRUPT ADDRESS	0x00	RW	Bit[7:0]: Set low byte for SCCB address that will trigger interrupt when read
0x3F05	MC WRITE INTERRUPT ADDRESS	0x70	RW	Bit[7:0]: Set high byte for SCCB address that will trigger interrupt when written
0x3F06	MC WRITE INTERRUPT ADDRESS	0x04	RW	Bit[7:0]: Set low byte for SCCB address that will trigger interrupt when written

table 6-3 MCU control registers (sheet 2 of 2)

address	register name	default value	R/W	description
0x3F0C	MC INTERRUPT0 STATUS	0x00	RW	Interrupt0 Status Indicator Bit[5]: ISP EOF Bit[4]: ISP SOF Bit[2]: AWB done Bit[1]: VFIFO full Bit[0]: VFIFO empty
0x3F0D	MC INTERRUPT1 STATUS	0x00	RW	Interrupt1 Status Indicator Bit[7]: AEC done Bit[6]: Average done Bit[5]: AEC trigger Bit[3]: MIPI turn around Bit[2]: MIPI low power contention detect Bit[0]: BLC SOF

6.4 frame control (FC)

Frame control (FC) is used to mask some specified frame by setting the appropriate registers.

table 6-4 FC control registers

address	register name	default value	R/W	description
0x4201	FRAME CONTROL 00	0x00	RW	Control Passed Frame Number When both ON and OFF numbers are set to 0x00, frame control is in bypass mode Bit[3:0]: Frame ON number
0x4202	FRAME CONTROL 01	0x00	RW	Control Masked Frame Number When both ON and OFF numbers are set to 0x00, frame control is in bypass mode Bit[3:0]: Frame OFF number

6.5 format description

Format control converts the internal data format into the desired output format including YUV, RGB, or RAW.

table 6-5 FORMAT control registers (sheet 1 of 5)

address	register name	default value	R/W	description
0x4300	FORMAT CONTROL 00	0xF8	RW	<p>Format Control 00</p> <p>Bit[7:4]: Output format of formatter module</p> <p>0x0: RAW</p> <p>Bit[3:0]: Output sequence</p> <p>0x0: BGBG... / GRGR...</p> <p>0x1: GBGB... / RGRG...</p> <p>0x2: GRGR... / BGBG...</p> <p>0x3: RGRG... / GBGB...</p> <p>0x4~0xF: Not allowed</p> <p>0x1: Y8</p> <p>Bit[3:0]: Does not matter</p> <p>0x2: YUV444/RGB888 (not available for full resolution)</p> <p>Bit[3:0]: Output sequence</p> <p>0x0: YUVYUV..., or GBRGBR...</p> <p>0x1: YVUYVU..., or GRBGRB...</p> <p>0x2: UYVUYV..., or BGRBGR...</p> <p>0x3: VYUYVU..., or RBRBGR...</p> <p>0x4: UYVUYV..., or BRBGRB...</p> <p>0x5: VUYVUY..., or RBGRBG...</p> <p>0x6~0xE: Not allowed</p> <p>0xF: UYVUYV..., or BGRBGR...</p> <p>0x3: YUV422</p> <p>Bit[3:0]: Output sequence</p> <p>0x0: YUYV...</p> <p>0x1: YVYU...</p> <p>0x2: UYVY...</p> <p>0x3: VYUY...</p> <p>0x4~0xE: Not allowed</p> <p>0xF: UYVY...</p> <p>0x4: YUV420</p> <p>Bit[3:0]: Output sequence</p> <p>0x0: YYYY... / YUYV...</p> <p>0x1: YYYY... / YVYU...</p> <p>0x2: YYYY... / UYVY...</p> <p>0x3: YYYY... / VYUY...</p> <p>0x4: YUYV... / YYYY...</p>

table 6-5 FORMAT control registers (sheet 2 of 5)

address	register name	default value	R/W	description
				0x5: YVYU... / YYYY... 0x6: UYVY... / YYYY... 0x7: VYUY... / YYYY... 0x8~0xE: Not allowed 0xF: YYYY... / UYVY... 0x5: YUV420 (for MIPI only) Bit[3:0]: Output sequence 0x0~0xD: Not allowed 0xE: VYVYVY... / UYUYUY... 0xF: UYUYUY... / VYVYVY... 0x6: RGB565 Bit[3:0]: Output sequence 0x0: {b[4:0],g[5:3]}, {g[2:0],r[4:0]} 0x1: {r[4:0],g[5:3]}, {g[2:0],b[4:0]} 0x2: {g[4:0],r[5:3]}, {r[2:0],b[4:0]} 0x3: {b[4:0],r[5:3]}, {r[2:0],g[4:0]} 0x4: {g[4:0],b[5:3]}, {b[2:0],r[4:0]} 0x5: {r[4:0],b[5:3]}, {b[2:0],g[4:0]} 0x6~0xE: Not allowed 0xF: {g[2:0],b[4:0]}, {r[4:0],g[5:3]} 0x7: RGB555 format 1 Bit[3:0]: Output sequence 0x0: {b[4:0],g[4:2]}, {g[1:0],1'b0,r[4:0]} 0x1: {r[4:0],g[4:2]}, {g[1:0],1'b0,b[4:0]} 0x2: {g[4:0],r[4:2]}, {r[1:0],1'b0,b[4:0]} 0x3: {b[4:0],r[4:2]}, {r[1:0],1'b0,g[4:0]} 0x4: {r[4:0],b[4:2]}, {b[1:0],1'b0,g[4:0]} 0x5: {g[4:0],b[4:2]}, {b[1:0],1'b0,r[4:0]} 0x6~0xE: Not allowed 0xF: {g[1:0],1'b0,b[4:0]}, {r[4:0],g[4:2]} 0x8: RGB555 format 2 Bit[3:0]: Output sequence 0x0: {1'b0,b[4:0],g[4:3]}, {g[2:0],r[4:0]}

table 6-5 FORMAT control registers (sheet 3 of 5)

address	register name	default value	R/W	description
0x1:				{1'b0,r[4:0],g[4:2]}, {g[2:0],b[4:0]}
0x2:				{1'b0,g[4:0],r[4:2]}, {r[2:0],b[4:0]}
0x3:				{1'b0,b[4:0],r[4:2]}, {r[2:0],g[4:0]}
0x4:				{1'b0,r[4:0],b[4:2]}, {b[2:0],g[4:0]}
0x5:				{1'b0,g[4:0],b[4:2]}, {b[2:0],r[4:0]}
0x6:				{b[4:0],1'b0,g[4:3]}, {g[2:0],r[4:0]}
0x7:				{r[4:0],1'b0,g[4:2]}, {g[2:0],b[4:0]}
0x8:				{g[4:0],1'b0,r[4:2]}, {r[2:0],b[4:0]}
0x9:				{b[4:0],1'b0,r[4:2]}, {r[2:0],g[4:0]}
0xA:				{r[4:0],1'b0,b[4:2]}, {b[2:0],g[4:0]}
0xB:				{g[4:0],1'b0,b[4:2]}, {b[2:0],r[4:0]}
0xC~0xF:				Not allowed
0x9:	RGB444 format 1			
Bit[3:0]:	Output sequence			
0x0:				{1'b0,b[3:0],2'h0,g[3]}, {g[2:0],1'b0,r[3:0]}
0x1:				{1'b0,r[3:0],2'h0,g[3]}, {g[2:0],1'b0,b[3:0]}
0x2:				{1'b0,g[3:0],2'h0,r[3]}, {r[2:0],1'b0,b[3:0]}
0x3:				{1'b0,b[3:0],2'h0,r[3]}, {r[2:0],1'b0,g[3:0]}
0x4:				{1'b0,r[3:0],2'h0,b[3]}, {b[2:0],1'b0,g[3:0]}
0x5:				{1'b0,g[3:0],2'h0,b[3]}, {b[2:0],1'h0,r[3:0]}
0x6:				{b[3:0],1'b0,g[3:1]}, {g[0],2'h0,r[3:0],1'b0}
0x7:				{r[3:0],1'b0,g[3:1]}, {g[0],2'h0,b[3:0],1'b0}
0x8:				{g[3:0],1'b0,r[3:1]}, {r[0],2'h0,b[3:0],1'b0}
0x9:				{b[3:0],1'b0,r[3:1]}, {r[0],2'h0,g[3:0],1'b0}
0xA:				{r[3:0],1'b0,b[3:1]}, {b[0],2'h0,g[3:0],1'b0}
0xB:				{g[3:0],1'b0,b[3:1]}, {b[0],2'h0,r[3:0],1'b0}
0xC~0xE:				Not allowed

table 6-5 FORMAT control registers (sheet 4 of 5)

address	register name	default value	R/W	description
				0xF: {g[0],2'h2,b[3:0],1'b1}, {r[3:0],1'b1,g[3:1]}
				0xA: RGB444 format 2
				Bit[3:0]: Output sequence
				0x0: {4'b0,b[3:0]}, {g[3:0],r[3:0]}
				0x1: {4'b0,r[3:0]}, {g[3:0],b[3:0]}
				0x2: {4'b0,b[3:0]}, {r[3:0],g[3:0]}
				0x3: {4'b0,r[3:0]}, {b[3:0],g[3:0]}
				0x4: {4'b0,g[3:0]}, {b[3:0],r[3:0]}
				0x5: {4'b0,g[3:0]}, {r[3:0],b[3:0]}
				0x6: {b[3:0],g[3:0],2'h0}, {r[3:0],b[3:0],2'h0,g[3:0],r[3:0],2'h0}
				0x7: {r[3:0],g[3:0],2'h0}, {b[3:0],r[3:0],2'h0,g[3:0],b[3:0],2'h0}
				0x8: {b[3:0],r[3:0],2'h0}, {g[3:0],b[3:0],2'h0,r[3:0],g[3:0],2'h0}
				0x9: {r[3:0],b[3:0],2'h0}, {g[3:0],r[3:0],2'h0,b[3:0],g[3:0],2'h0}
				0xA: {g[3:0],b[3:0],2'h0}, {r[3:0],g[3:0],2'h0,b[3:0],r[3:0],2'h0}
				0xB: {g[3:0],r[3:0],2'h0}, {b[3:0],g[3:0],2'h0,r[3:0],b[3:0],2'h0}
				0xC~0xF: Not allowed
				0xB~0xE: Not allowed
				0xF: Bypass formatter module (not recommended)
				Bit[3:0]: Output format
				0x8: Raw
				0x9: YUV422
				0xA: YUV444
				0xE: VYYY.../UYUYUY
				0xF: UYYY.../YYVYYY

table 6-5 FORMAT control registers (sheet 5 of 5)

address	register name	default value	R/W	description	
0x4301	FORMAT CONTROL 01	0x00	RW	Format Control 01 Bit[1:0]: YUV422 UV control 00: U/V generated from average 01: U/V generated from first pixel 10: Not valid 11: U/V generated from second pixel	
0x4302	YMAX VALUE	0x03	RW	Bit[1:0]:	Y max clip value[9:8]
0x4303	YMAX VALUE	0xFF	RW	Bit[7:0]:	Y max clip value[7:0]
0x4304	YMIN VALUE	0x00	RW	Bit[1:0]:	Y min clip value[9:8]
0x4305	YMIN VALUE	0x00	RW	Bit[7:0]:	Y min clip value[7:0]
0x4306	UMAX VALUE	0x03	RW	Bit[1:0]:	U max clip value[9:8]
0x4307	UMAX VALUE	0xFF	RW	Bit[7:0]:	U max clip value[7:0]
0x4308	UMIN VALUE	0x00	RW	Bit[1:0]:	U min clip value[9:8]
0x4309	UMIN VALUE	0x00	RW	Bit[7:0]:	U min clip value[7:0]
0x430A	VMAX VALUE	0x03	RW	Bit[1:0]:	V max clip value[9:8]
0x430B	VMAX VALUE	0xFF	RW	Bit[7:0]:	V max clip value[7:0]
0x430C	VMIN VALUE	0x00	RW	Bit[1:0]:	V min clip value[9:8]
0x430D	VMIN VALUE	0x00	RW	Bit[7:0]:	V min clip value[7:0]

6.6 digital video port (DVP)

6.6.1 overview

The Digital Video Port (DVP) provides 10-bit parallel data output in all formats supported and extended features including compression mode, HSYNC mode, CCIR656 mode, and test pattern output. The DVP is also used to receive the video data from an external camera, which will be sent out through the OV5640 MIPI interface.

table 6-6 DVP control registers (sheet 1 of 3)

address	register name	default value	R/W	description
0x4709	DVP VYSNC WIDTH0	0x02	RW	VSYNC Width Line Unit
0x470A	DVP VYSNC WIDTH1	0x00	RW	Bit[7:0]: VSYNC width PCLK unit[15:8]
0x470B	DVP VYSNC WIDTH2	0x01	RW	Bit[7:0]: VSYNC width PCLK unit[7:0]
0x4711	PAD LEFT CTRL	0x00	RW	HSYNC Mode Left Padding Pixel Counter Add padding data at start of a line
0x4712	PAD RIGHT CTRL	0x00	RW	HSYNC Mode Right Padding Pixel Counter Add padding data at end of a line
0x4713	JPG MODE SELECT	0x02	RW	Bit[2:0]: JPEG mode select 001: JPEG mode 1 010: JPEG mode 2 011: JPEG mode 3 100: JPEG mode 4 101: JPEG mode 5 110: JPEG mode 6
0x4715	656 DUMMY LINE	0x00	RW	Bit[3:0]: CCIR656 dummy line number Control dummy line number at beginning of the frame
0x4719	CCIR656 CTRL	0x00	RW	Bit[1:0]: CCIR656 EAV/SAV option
0x471B	HSYNC CTRL00	0x02	RW	Bit[0]: HSYNC mode enable

table 6-6 DVP control registers (sheet 2 of 3)

address	register name	default value	R/W	description
0x471D	DVP VSYNC CTRL	0x01	RW	Bit[1:0]: vsync_mode 00: VSYNC positive edge trigger by end of field, negative edge trigger by start of frame 01: VSYNC positive edge trigger by end of frame, the width define by register 10: VSYNC positive edge trigger by start of field, the width define by register
0x471F	DVP HREF CTRL	0x40	RW	HREF Minimum Blanking in JPEG Mode23
0x4721	VERTICAL START OFFSET	0x00	RW	Bit[3:0]: Vertical start delay between video output and video input
0x4722	VERTICAL END OFFSET	0x00	RW	Bit[3:0]: Vertical end delay between video output and video input
0x4723	DVP CTRL23	0x00	RW	DVP JPEG Mode456 Skip Line Number
0x4730	CCIR656 CTRL00	0x00	RW	Bit[7]: SYNC code selection 0: Automatically generate SYNC code 1: SYNC code from register setting 0x4732~4735 Bit[6]: f value in CCIR656 SYNC code when fixed f value Bit[5]: Fixed f value Bit[4:3]: Blank toggle data options 00: Toggle data is 1'h040/1'h200 01: Use register setting 0x4736~0x4738 10: Blanking data always keep 0 Bit[1]: Clip data disable Bit[0]: CCIR656 mode enable
0x4731	CCIR656 CTRL01	0x00	RW	Bit[0]: Blanking toggle data order option
0x4732	CCIR656 FS	0x01	RW	CCIR656 Sync Code Frame Start
0x4733	CCIR656 FE	0x0F	RW	CCIR656 Sync Code Frame End
0x4734	CCIR656 LS	0x00	RW	CCIR656 Sync Code Line Start

table 6-6 DVP control registers (sheet 3 of 3)

address	register name	default value	R/W	description
0x4735	CCIR656 LE	0x00	RW	CCIR656 Sync Code line End
0x4736	CCIR656 CTRL6	0x00	RW	Bit[3:2]: Toggle data0[9:8] Bit[1:0]: Toggle data1[9:8]
0x4737	CCIR656 CTRL7	0x00	RW	Bit[7:0]: Toggle data0[7:0]
0x4738	CCIR656 CTRL8	0x00	RW	Bit[7:0]: Toggle data1[7:0]
0x4740	POLARITY CTRL00	0x20	RW	Bit[5]: PCLK polarity 0: Active low 1: Active high Bit[3]: Gate PCLK under VSYNC Bit[2]: Gate PCLK under HREF Bit[1]: HREF polarity 0: Active low 1: Active high Bit[0]: VSYNC polarity 0: Active low 1: Active high
0x4741	TEST PATTERN	0x00	RW	Bit[2]: Test pattern enable Bit[1]: Test pattern select 0: Output test pattern 0 1: Output test pattern 1 Bit[0]: Test pattern 8-bit/10-bit 0: 10-bit test pattern 1: 8-bit test pattern
0x4745	DATA ORDER	0x00	RW	Bit[2:1]: DVP order option for debug 00: D[9:0] 10: {D[7:0], D[9:8]} x1: {D[1:0], D[9:2]} Bit[0]: Output data order 0: Normal output 1: Reverse output data bit order

6.6.2 DVP timing

figure 6-7 DVP timing diagram

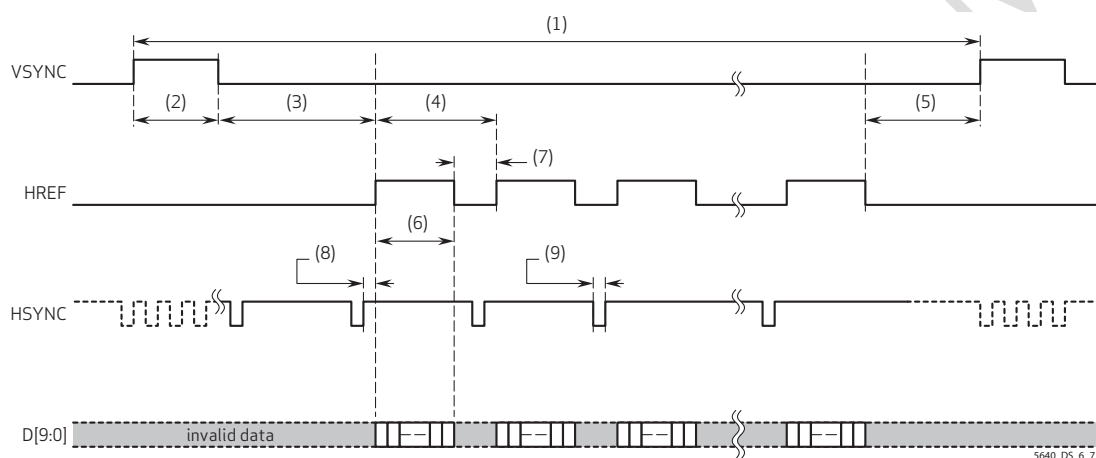


table 6-7 DVP timing specifications (sheet 1 of 2)

mode	timing
5 megapixel 2592x1944	(1) 5596992 tp (2) 5688 tp (3) 48276 tp (4) 2844 tp (5) 14544 tp (6) 2592 tp (7) 252 tp (8) 0 tp (9) 252 tp
1080p 1920x1080	(1) 5596992 tp (2) 5688 tp (3) 2506164 tp (4) 2844 tp (5) 14544 tp (6) 1920 tp (7) 924 tp (8) 0 tp (9) 924 tp
UXGA 1600x1200	(1) 5596992 tp (2) 5688 tp (3) 2165204 tp (4) 2844 tp (5) 14544 tp (6) 1600 tp (7) 1244 tp (8) 0 tp (9) 1244 tp

**note**

The timing values shown in **table 6-7** may vary depending upon register settings.

table 6-7 DVP timing specifications (sheet 2 of 2)

mode	timing
720p 1280x720	(1) 5596992 tp (2) 5688 tp (3) 3530644 tp (4) 2844 tp (5) 14544 tp (6) 1280 tp (7) 1564 tp (8) 0 tp (9) 1564 tp
XGA 1024x768	(1) 5596992 tp (2) 5688tp (3) 2825588 tp (4) 2844 tp (5) 583344tp (6) 1024 tp (7) 1820 tp (8) 0 tp (9) 1820 tp
VGA 640x480	(1) 5596992 tp (2) 5688 tp (3) 4213844 tp (4) 2844 tp (5) 14544 tp (6) 640 tp (7) 2204 tp (8) 0 tp (9) 2204 tp

6.7 mobile industry processor interface (MIPI)

MIPI provides a single uni-directional clock lane and two bi-directional data lane solution for communication links between components inside a mobile device. The two data lanes have full support for HS (uni-direction) and LP (bi-direction) data transfer mode. Contact your local OmniVision FAE for more details.

table 6-8 MIPI transmitter registers (sheet 1 of 3)

address	register name	default value	R/W	description
0x4800	MIPI CTRL 00	0x04	RW	MIPI Control 00
				Bit[5]: Clock lane gate enable 0: Clock lane is free running 1: Gate clock lane when no packet to transmit
				Bit[4]: Line sync enable 0: Do not send line short packet for each line 1: Send line short packet for each line
0x4801	MIPI CTRL 01	0x04	RW	Bit[3]: Lane select 0: Use lane1 as default data lane 1: Use lane2 as default data lane
				Bit[2]: Idle status 0: MIPI bus will be LP00 when no packet to transmit 1: MIPI bus will be LP11 when no packet to transmit
				MIPI Control 01
0x4805	MIPI CTRL 05	0x10	RW	Bit[4]: PH bit order for ECC 0: {DI[7:0],WC[7:0],WC[15:8]} 1: {DI[0:7],WC[0:7],WC[8:15]}
				Bit[3]: PH byte order for ECC 0: {DI,WC_l,WC_h} 1: {DI,WC_h,WC_l}
				Bit[2]: PH byte order2 for ECC 0: {DI,WC} 1: {WC,DI}
0x4805	MIPI CTRL 05	0x10	RW	Bit[7]: MIPI lane1 disable 1: Disable MIPI data lane1 Lane1 will be LP00
				Bit[6]: MIPI lane1 disable 1: Disable MIPI data lane1 Lane1 will be LP00
				Bit[5]: LPX Global timing select 0: Auto calculate t_lpx_o in pclk2x domain, unit clk2x 1: Use lp_p_min[7:0]

table 6-8 MIPI transmitter registers (sheet 2 of 3)

address	register name	default value	R/W	description
0x480A	MIPI DATA ORDER	0x00	RW	Bit[2]: Bit order reverse Bit[1:0]: Bit position adjust 01: {data[7:0],data[9:8]} 10: {data[1:0],data[9:2]}
0x4818	MIN HS ZERO H	0x00	RW	High Byte of Minimum Value of hs_zero Unit ns
0x4819	MIN HS ZERO L	0x96	RW	Low Byte of Minimum Value of hs_zero $hs_zero_real = hs_zero_min_o + Tui*ui_hs_zero_min_o$
0x481A	MIN MIPI HS TRAIL H	0x00	RW	High Byte of Minimum Value of hs_trail Unit ns
0x481B	MIN MIPI HS TRAIL L	0x3C	RW	Low Byte of Minimum Value of hs_trail $hs_trail_real = hs_trail_min_o + Tui*ui_hs_trail_min_o$
0x481C	MIN MIPI CLK ZERO H	0x01	RW	High Byte of Minimum Value of clk_zero
0x481D	MIN MIPI CLK ZERO L	0x86	RW	Low Byte of Minimum Value of clk_zero $clk_zero_real = clk_zero_min_o + Tui*ui_clk_zero_min_o$
0x481E	MIN MIPI CLK PREPARE H	0x00	RW	High Byte of Minimum Value of clk_prepare Unit ns
0x481F	MIN MIPI CLK PREPARE L	0x3C	RW	Low Byte of Minimum Value of clk_prepare $clk_prepare_real = clk_prepare_min_o + Tui*ui_clk_prepare_min_o$
0x4820	MIN CLK POST H	0x00	RW	High Byte of Minimum Value of clk_post Unit ns
0x4821	MIN CLK POST L	0x56	RW	Low Byte of Minimum Value of clk_post $clk_post_real = clk_post_min_o + Tui*ui_clk_post_min_o$
0x4822	MIN CLK TRAIL H	0x00	RW	High Byte of Minimum Value of clk_trail Unit ns
0x4823	MIN CLK TRAIL L	0x3C	RW	Low Byte of Minimum Value of clk_trail $clk_trail_real = clk_trail_min_o + Tui*ui_clk_trail_min_o$
0x4824	MIN LPX PCLK H	0x00	RW	High Byte of Minimum Value of lpx_p Unit ns
0x4825	MIN LPX PCLK L	0x32	RW	Low Byte of Minimum Value of lpx_p $lpx_p_real = lpx_p_min_o + Tui*ui_lpx_p_min_o$
0x4826	MIN HS PREPARE H	0x00	RW	High Byte of Minimum Value of hs_prepare Unit ns
0x4827	MIN HS PREPARE L	0x32	RW	Low Byte of Minimum Value of hs_prepare $hs_prepare_real = hs_prepare_min_o + Tui*ui_hs_prepare_min_o$

table 6-8 MIPI transmitter registers (sheet 3 of 3)

address	register name	default value	R/W	description
0x4828	MIN HS EXIT H	0x00	RW	High Byte of Minimum Value of hs_exit Unit ns
0x4829	MIN HS EXIT L	0x64	RW	Low Byte of Minimum Value of hs_exit $hs_exit_real = hs_exit_min_o + Tui * ui_hs_exit_min_o$
0x482A	MIN HS ZERO/UI	0x05	RW	Minimum UI Value of hs_zero Unit UI
0x482B	MIN HS TRAIL/UI	0x04	RW	Minimum UI Value of hs_trail Unit UI
0x482C	MIN CLK ZERO/UI	0x00	RW	Minimum UI Value of clk_zero Unit UI
0x482D	MIN CLK PREPARE/UI	0x00	RW	Minimum UI Value of clk_prepare Unit UI
0x482E	MIN CLK POST/UI	0x34	RW	Minimum UI Value of clk_post Unit UI
0x482F	MIN CLK TRAIL/UI	0x00	RW	Minimum UI Value of clk_trail Unit UI
0x4830	MIN LPX PCLK/UI	0x00	RW	Minimum UI Value of lpx_p(pclk2x domain) Unit UI
0x4831	MIN HS PREPARE/UI	0x04	RW	Minimum UI Value of hs_prepare Unit UI
0x4832	MIN HS EXIT/UI	0x00	RW	Minimum UI Value of hs_exit Unit UI
0x4837	PCLK PERIOD	0x10	RW	The period of pixel clock, pclk_div=1, and 1 bit decimal

7 register tables

The following tables provide descriptions of the device control registers contained in the OV5640. For all registers enable/disable bits, ENABLE = 1 and DISABLE = 0.

table 7-1 system and IO pad control registers (sheet 1 of 7)

address	register name	default value	R/W	description
0x3000	SYSTEM RESET00	0x30	RW	Reset for Individual Block (0: enable block; 1: reset block) Bit[7]: Reset BIST Bit[6]: Reset MCU program memory Bit[5]: Reset MCU Bit[4]: Reset OTP Bit[3]: Reset STB Bit[2]: Reset d5060 Bit[1]: Reset timing control Bit[0]: Reset array control
0x3001	SYSTEM RESET01	0x08	RW	Reset for Individual Block (0: enable block; 1: reset block) Bit[7]: Reset AWB registers Bit[6]: Reset AFC Bit[5]: Reset ISP Bit[4]: Reset FC Bit[3]: Reset S2P Bit[2]: Reset BLC Bit[1]: Reset AEC registers Bit[0]: Reset AEC
0x3002	SYSTEM RESET02	0x1C	RW	Reset for Individual Block (0: enable block; 1: reset block) Bit[7]: Reset VFIFO Bit[6]: Debug mode Bit[5]: Reset format Bit[4]: Reset JFIFO Bit[3]: Reset SFIFO Bit[2]: Reset JPG Bit[1]: Reset format MUX Bit[0]: Reset average
0x3003	SYSTEM RESET03	0x00	RW	Reset for Individual Block (0: enable block; 1: reset block) Bit[7:6]: Debug mode Bit[5]: Reset digital gain compensation Bit[4]: Reset SYNC FIFO Bit[3]: Reset PSRAM Bit[2]: Reset ISP FC Bit[1]: Reset MIPI Bit[0]: Reset DVP

table 7-1 system and IO pad control registers (sheet 2 of 7)

address	register name	default value	R/W	description
0x3004	CLOCK ENABLE00	0xCF	RW	Clock Enable Control (0: disable clock; 1: enable clock) Bit[7]: Enable BIST clock Bit[6]: Enable MCU program memory clock Bit[5]: Enable MCU clock Bit[4]: Enable OTP clock Bit[3]: Enable STROBE clock Bit[2]: Enable D5060 clock Bit[1]: Enable timing control clock Bit[0]: Enable array control clock
0x3005	CLOCK ENABLE01	0xF7	RW	Clock Enable Control (0: disable clock; 1: enable clock) Bit[7]: Enable AWB register clock Bit[6]: Enable AFC clock Bit[5]: Enable ISP clock Bit[4]: Enable FC clock Bit[3]: Enable S2P clock Bit[2]: Enable BLC clock Bit[1]: Enable AEC register clock Bit[0]: Enable AEC clock
0x3006	CLOCK ENABLE02	0xE3	RW	Clock Enable Control (0: disable clock; 1: enable clock) Bit[7]: Enable PSRAM clock Bit[6]: Enable FMT clock Bit[5]: Enable JPEG 2x clock Bit[3]: Enable JPEG clock Bit[2]: Debug mode Bit[1]: Enable format MUX clock Bit[0]: Enable average clock
0x3007	CLOCK ENABLE03	0xFF	RW	Clock Enable Control (0: disable clock; 1: enable clock) Bit[7]: Enable digital gain compensation clock Bit[6]: Enable SYNC FIFO clock Bit[5]: Enable ISPFC SCLK clock Bit[4]: Enable MIPI PCLK clock Bit[3]: Enable MIPI clock Bit[2]: Enable DVP PCLK clock Bit[1]: Enable VFIFO PCLK clock Bit[0]: Enable VFIFO SCLK clock
0x3008	SYSTEM CTROL0	0x02	RW	System Control Bit[7]: Software reset Bit[6]: Software power down Bit[5:0]: Debug mode
0x3009	DEBUG MODE	–	–	Debug Mode

table 7-1 system and IO pad control registers (sheet 3 of 7)

address	register name	default value	R/W	description
0x300A	CHIP ID HIGH BYTE	0x56	R	Chip ID High Byte
0x300B	CHIP ID LOW BYTE	0x40	R	Chip ID Low Byte
0x300C~ 0x300D	DEBUG MODE	–	–	Debug Mode
0x300E	MIPI CONTROL 00	0x58	RW	MIPI Control 00 Bit[7:5]: mipi_lane_mode 000: One lane mode 001: Two lane mode Others: Debug mode Bit[4]: MIPI TX PHY power down 0: Debug mode 1: Power down PHY HS TX Bit[3]: MIPI RX PHY power down 0: Debug mode 1: Power down PHY LP RX module Bit[2]: mipi_en 0: DVP enable 1: MIPI enable Bit[1:0]: Debug mode
0x300F~ 0x3015	DEBUG MODE	–	–	Debug Mode
0x3016	PAD OUTPUT ENABLE 00	0x00	RW	Input/Output Control (0: input; 1: output) Bit[7:2]: Debug mode Bit[1]: Strobe output enable Bit[0]: SIOD output enable
0x3017	PAD OUTPUT ENABLE 01	0x00	RW	Input/Output Control (0: input; 1: output) Bit[7]: FREX output enable Bit[6]: VSYNC output enable Bit[5]: HREF output enable Bit[4]: PCLK output enable Bit[3:0]: D[9:6] output enable
0x3018	PAD OUTPUT ENABLE 02	0x00	RW	Input/Output Control (0: input; 1: output) Bit[7:2]: D[5:0] output enable Bit[1]: GPIO1 output enable Bit[0]: GPIO0 output enable

table 7-1 system and IO pad control registers (sheet 4 of 7)

address	register name	default value	R/W	description
0x3019	PAD OUTPUT VALUE 00	0x00	RW	PAD Output Value Bit[7]: MIPI data lane option Bypass latch in MIPI PHY Bit[6]: MIPI lane2 state in sleep mode 0: LP00 1: LP11 Bit[5]: MIPI lane1 state in sleep mode 0: LP00 1: LP11 Bit[4]: MIPI CLK lane state in sleep mode 0: LP00 1: LP11 Bit[3:2]: Debug mode Bit[1]: Strobe Bit[0]: SIOD
0x301A	PAD OUTPUT VALUE 01	0x00	RW	GPIO Output Value 01 Bit[7]: FREX Bit[6]: VSYNC Bit[5]: HREF Bit[4]: PCLK Bit[3:0]: D[9:6]
0x301B	PAD OUTPUT VALUE 02	0x00	RW	GPIO Output Value 02 Bit[7:2]: D[5:0] Bit[1]: GPIO1 Bit[0]: GPIO0
0x301C	PAD SELECT 00	0x00	RW	Output Selection for GPIO Bit[7:2]: Debug mode Bit[1]: IO strobe select Bit[0]: IO SIOD select
0x301D	PAD SELECT 01	0x00	RW	Output Selection for GPIO Bit[7]: FREX select Bit[6]: VSYNC select Bit[5]: HREF select Bit[4]: PCLK select Bit[3:0]: IO D[9:6] select
0x301E	PAD SELECT 02	0x00	RW	Output Selection for GPIO Bit[7:2]: IO D[5:0] select Bit[1]: IO GPIO1 select Bit[0]: IO GPIO0 select
0x301F	DEBUG MODE	–	–	Debug Mode
0x302A	CHIP REVISION	0xB0	R	Bit[7:4]: Process 0xA: FSI 0xB: BSI Bit[3:0]: Chip revision

table 7-1 system and IO pad control registers (sheet 5 of 7)

address	register name	default value	R/W	description
0x302B	DEBUG MODE	–	–	Debug Mode
				Pad Control Bit[7:6]: Output drive capability 00: 1x 01: 2x 10: 3x 11: 4x
0x302C	PAD CONTROL 00	0x02	RW	Bit[5:2]: Debug mode Changing this value is not allowed Bit[1]: FREX enable Bit[0]: Debug mode Changing this value is not allowed
0x302D~ 0x302F	SYSTEM CONTROL	–	RW	System Control Registers Changing these values is not recommended
				PWC Control Bit[7:6]: Debug mode Changing this value is not allowed Bit[5]: bp_regulator Bit[4:0]: Debug mode Changing this value is not allowed
0x3030	SC A PWC PK O	0x0B	RW	
0x3031~ 0x3033	SYSTEM CONTROL	–	RW	System Control Registers Changing these values is not recommended
				Bit[7]: Debug mode Bit[6:4]: PLL charge pump control Bit[3:0]: MIPI bit mode 0x8: 8-bit mode 0xA: 10-bit mode Others: Debug mode
0x3034	SC PLL CONTRL0	0x1A	RW	
				Bit[7:4]: System clock divider Slow down all clocks Bit[3:0]: Scale divider for MIPI MIPI PCLK/SERCLK can be slow down
0x3035	SC PLL CONTRL1	0x11	RW	
				Bit[7:0]: PLL multiplier (4~252) Can be any integer from 4~127 and only even integers from 128~252
0x3036	SC PLL CONTRL2	0x69	RW	

table 7-1 system and IO pad control registers (sheet 6 of 7)

address	register name	default value	R/W	description
0x3037	SC PLL CONTRL3	0x03	RW	Bit[7:5]: Debug mode Bit[4]: PLL root divider 0: Bypass 1: Divided by 2 Bit[3:0]: PLL pre-divider 1,2,3,4,6,8
0x3038	SYSTEM CONTROL	–	RW	System Control Registers Changing these values is not recommended
0x3039	SC PLL CONTRL 5	0x00	RW	Bit[7]: PLL bypass Bit[6:0]: Debug mode
0x303A	SC PLLS CTRL0	0x00	RW	Bit[7]: PLLS bypass Bit[6:0]: Debug mode
0x303B	SC PLLS CTRL1	0x19	RW	Bit[7:5]: Debug mode Bit[4:0]: PLLS multiplier
0x303C	SC PLLS CTRL2	0x11	RW	Bit[7]: Debug mode Bit[6:4]: PLLS charge pump control Bit[3:0]: PLLS system divider
0x303D	SC PLLS CTRL3	0x30	RW	Bit[7:6]: Debug mode Bit[5:4]: PLLS pre-divider 00: /1 01: /1.5 10: /2 11: /3 Bit[3]: Debug mode Bit[2]: PLLS root divider 0: /1 1: /2 Bit[1:0]: PLLS seld5 00: /1 01: /1 10: /2 11: /2.5
0x303E~ 0x304F	SYSTEM CONTROL	–	RW	System Control Registers Changing these values is not recommended
0x3050	IO PAD VALUE	–	R	Read Pad Value Bit[7:5]: Debug mode Bit[4]: FREX Bit[3]: PWDN Bit[2]: Debug mode Bit[1]: SIOC Bit[0]: Debug mode

table 7-1 system and IO pad control registers (sheet 7 of 7)

address	register name	default value	R/W	description
0x3051	IO PAD VALUE	–	R	Read Pad Value Bit[7]: OTP memory out Bit[6]: VSYNC Bit[5]: HREF Bit[4]: PCLK Bit[3:0]: D[9:6]
0x3052	IO PAD VALUE	–	R	Pad Input Status Bit[7:2]: D[5:0] Bit[1]: GPIO1 Bit[0]: GPIO0

table 7-2 SCCB control registers (sheet 1 of 2)

address	register name	default value	R/W	description
0x3100	SCCB_ID	0x78	RW	SCCB Slave ID
0x3101	SCCB SYSTEM CTRL0	–	RW	SCCB Control Registers Changing these values is not allowed
0x3102	SCCB SYSTEM CTRL0	0x00	RW	Bit[7]: Debug mode Bit[6]: MIPI SC reset Bit[5]: SRB reset Bit[4]: SCCB slave reset Bit[3]: rst_pon_sccb Bit[2]: Debug mode Bit[1]: MIPI PHY reset Bit[0]: PLL reset
0x3103	SCCB SYSTEM CTRL1	0x00	RW	PLL Clock Select Bit[7:2]: Debug mode Changing this value is not allowed Bit[1]: Select system input clock 0: From pad clock 1: From PLL Bit[0]: Debug mode Changing this value is not allowed
0x3104~ 0x3107	SCCB SYSTEM CTRL0	–	RW	SCCB Control Registers Changing these values is not allowed

table 7-2 SCCB control registers (sheet 2 of 2)

address	register name	default value	R/W	description
0x3108	SYSTEM ROOT DIVIDER	0x16	RW	Pad Clock Divider for SCCB Clock Bit[7:6]: Debug mode Bit[5:4]: PCLK root divider 00: PCLK = pll_clki 01: PCLK = pll_clki/2 10: PCLK = pll_clki/4 11: PCLK = pll_clki/8 Bit[3:2]: sclk2x root divider 00: SCLK2x = pll_clki 01: SCLK2x = pll_clki/2 10: SCLK2x = pll_clki/4 11: SCLK2x = pll_clki/8 Bit[1:0]: SCLK root divider 00: SCLK = pll_clki 01: SCLK = pll_clki/2 10: SCLK = pll_clki/4 11: sclk = pll_clki/8

table 7-3 SRB control registers

address	register name	default value	R/W	description
0x3200	GROUP ADDR0	0x40	RW	SRAM Group Address0
0x3201	GROUP ADDR1	0x4A	RW	SRAM Group Address1
0x3202	GROUP ADDR2	0x54	RW	SRAM Group Address2
0x3203	GROUP ADDR3	0x5E	RW	SRAM Group Address3
0x3204~ 0x3211	GROUP WRITE CONTROL REGISTERS	—	RW	Group Write Registers Changing these values is not recommended
				SRM Group Access
				Bit[7]: Group launch enable
				Bit[6]: Test mode access group
				Bit[5]: Group launch
				Bit[4]: Group hold end
				Bit[3:0]: Group ID
0x3212	SRM GROUP ACCESS	—	W	00x: Group for register access 011: Group to hold register address of embedded line SOF 100: Group to hold register address of embedded line EOF 101: Test mode for store register value to memory 110: Test mode for restore register value from memory 111: Group for write mask address
				SRM Group Status
0x3213	SRM GROUP STATUS	—	R	Bit[7]: Store Bit[6]: Restore Bit[5]: Group hold Bit[4]: Group launch Bit[3]: Group write Bit[2:0]: Group select

table 7-4 AWB gain control registers

address	register name	default value	R/W	description
0x3400	AWB R GAIN	0x04	RW	Bit[3:0]: AWB R gain[11:8]
0x3401	AWB R GAIN	0x00	RW	Bit[7:0]: AWB R gain[7:0]
0x3402	AWB G GAIN	0x04	RW	Bit[3:0]: AWB G gain[11:8]
0x3403	AWB G GAIN	0x00	RW	Bit[7:0]: AWB G gain[7:0]
0x3404	AWB B GAIN	0x04	RW	Bit[3:0]: AWB B gain[11:8]
0x3405	AWB B GAIN	0x00	RW	Bit[7:0]: AWB B gain[7:0]
0x3406	AWB MANUAL CONTROL	0x00	RW	Bit[7:1]: Debug mode Bit[0]: AWB gain manual enable 0: Auto 1: Manual

table 7-5 AEC/AGC control functions

address	register name	default value	R/W	description
0x3500	AEC PK EXPOSURE	0x00	RW	Exposure Output Bit[7:4]: Debug mode Bit[3:0]: Exposure [19:16]
0x3501	AEC PK EXPOSURE	0x02	RW	Exposure Output Bit[7:0]: Exposure [15:8]
0x3502	AEC PK EXPOSURE	0x00	RW	Exposure Output Bit[7:0]: Exposure [7:0]
0x3503	AEC PK MANUAL	0x00	RW	AEC Manual Mode Control Bit[7:2]: Debug mode Bit[1]: AGC manual 0: Auto enable 1: Manual enable Bit[0]: AEC manual 0: Auto enable 1: Manual enable
0x350A	AEC PK REAL GAIN	0x00	RW	Real Gain Bit[7:2]: Debug mode Bit[1:0]: Real gain[9:8]
0x350B	AEC PK REAL GAIN	0x10	RW	Real Gain Bit[7:0]: Real gain[7:0]
0x350C	AEC PK VTS	0x00	RW	AEC VTS Output Bit[7:0]: VTS[15:8] high bits
0x350D	AEC PK VTS	0x00	RW	AEC VTS Output Bit[7:0]: VTS[7:0] low bits

table 7-6 VCM control registers

address	register name	default value	R/W	description
0x3600~0x3601	DEBUG MODE	–	–	Debug Mode
0x3602	VCM CONTROL 0	0x50	RW	VCM Control Bit[7:4]: VCM target value[3:0] Bit[3]: Slew rate control s3 Bit[2:0]: Slew rate control s2,s1,s0
0x3603	VCM CONTROL 1	0x01	RW	VCM Control Bit[7]: PWDN VCM Bit[6]: Debug mode Bit[5:0]: VCM target value[9:4]
0x3604	VCM CONTROL 2	0x05	RW	VCM Control Bit[7:0]: vcm_rdiv[7:0]
0x3605	VCM CONTROL 3	0x46	RW	VCM Control Bit[7:5]: Debug mode Bit[4]: VCM RIH Bit[3:0]: vcm_rdiv[11:8]
0x3606	VCM CONTROL 4	0x00	RW	VCM Control Bit[7:3]: Debug mode Bit[2:0]: ib_vcm

table 7-7 timing control registers (sheet 1 of 2)

address	register name	default value	R/W	description
0x3800	TIMING HS	0x00	RW	Bit[7:4]: Debug mode Bit[3:0]: X address start[11:8] high byte
0x3801	TIMING HS	0x00	RW	Bit[7:0]: X address start[7:0] low byte
0x3802	TIMING VS	0x00	RW	Bit[7:4]: Debug mode Bit[3:0]: Y address start[11:8] high byte
0x3803	TIMING VS	0x00	RW	Bit[7:0]: Y address start[7:0] low byte
0x3804	TIMING HW	0x0A	RW	Bit[7:4]: Debug mode Bit[3:0]: X address end[11:8] high byte
0x3805	TIMING HW	0x3F	RW	Bit[7:0]: X address end[7:0] low byte
0x3806	TIMING VH	0x07	RW	Bit[7:3]: Debug mode Bit[2:0]: Y address end[10:8] high byte
0x3807	TIMING VH	0x9F	RW	Bit[7:0]: Y address end[7:0] low byte
0x3808	TIMING DVPHO	0x0A	RW	Bit[7:4]: Debug mode Bit[3:0]: DVP output horizontal width[11:8] high byte
0x3809	TIMING DVPHO	0x20	RW	Bit[7:0]: DVP output horizontal width[7:0] low byte
0x380A	TIMING DVPVO	0x07	RW	Bit[7:3]: Debug mode Bit[2:0]: DVP output vertical height[10:8] high byte
0x380B	TIMING DVPVO	0x98	RW	Bit[7:0]: DVP output vertical height[7:0] low byte
0x380C	TIMING HTS	0x0B	RW	Bit[7:5]: Debug mode Bit[4:0]: Total horizontal size[12:8] high byte
0x380D	TIMING HTS	0x1C	RW	Bit[7:0]: Total horizontal size[7:0] low byte
0x380E	TIMING VTS	0x07	RW	Bit[7:0]: Total vertical size[15:8] high byte
0x380F	TIMING VTS	0xB0	RW	Bit[7:0]: Total vertical size[7:0] low byte
0x3810	TIMING HOFFSET	0x00	RW	Bit[7:4]: Debug mode Bit[3:0]: ISP horizontal offset[11:8] high byte
0x3811	TIMING_HOFFSET	0x10	RW	Bit[7:0]: Horizontal offset[7:0] low byte
0x3812	TIMING VOFFSET	0x00	RW	Bit[7:3]: Debug mode Bit[2:0]: Vertical offset[10:8] high byte
0x3813	TIMING VOFFSET	0x04	RW	Bit[7:0]: Vertical offset[7:0] low byte
0x3814	TIMING X INC	0x11	RW	Bit[7:4]: Horizontal odd subsample increment Bit[3:0]: Horizontal even subsample increment

table 7-7 timing control registers (sheet 2 of 2)

address	register name	default value	R/W	description
0x3815	TIMING Y INC	0x11	RW	Bit[7:4]: Vertical odd subsample increment Bit[3:0]: Vertical even subsample increment
0x3816	HSYNC START	0x00	RW	Bit[7:4]: Debug mode Bit[3:0]: HSYNC start point[11:8]
0x3817	HSYNC START	0x00	RW	Bit[7:0]: HSYNC start point[7:0]
0x3818	HSYNC WIDTH	0x00	RW	Bit[7:4]: Debug mode Bit[3:0]: HSYNC width[11:8]
0x3819	HSYNC WIDTH	0x00	RW	Bit[7:4]: Debug mode Bit[3:0]: HSYNC width[7:8]
0x3820	TIMING TC REG20	0x40	RW	Timing Control Bit[7:3]: Debug mode Bit[2]: ISP vflip Bit[1]: Sensor vflip
0x3821	TIMING TC REG21	0x00	RW	Timing Control Bit[7:6]: Debug mode Bit[5]: JPEG enable Bit[4:3]: Debug mode Bit[2]: ISP mirror Bit[1]: Sensor mirror Bit[0]: Horizontal binning enable

table 7-8 AEC/AGC power down domain control registers (sheet 1 of 4)

address	register name	default value	R/W	description
0x3A00	AEC CTRL00	0x78	RW	AEC System Control (0: disable; 1: enable) Bit[7]: Debug mode Bit[6]: Less one line enable Bit[5]: Band function enable Bit[4]: Less 1 band enable Bit[3]: Start selection Bit[2]: Night mode Bit[1]: New balance function Bit[0]: Freeze
0x3A01	AEC MIN EXPOSURE	0x01	RW	Minimum Exposure Output Limit Bit[7:0]: Minimum exposure
0x3A02	AEC MAX EXPO (60HZ)	0x3D	RW	60Hz Maximum Exposure Output Limit Bit[7:0]: Maximum exposure[15:8]
0x3A03	AEC MAX EXPO (60HZ)	0x80	RW	60Hz Maximum Exposure Output Limit Bit[7:0]: Maximum exposure[7:0]

table 7-8 AEC/AGC power down domain control registers (sheet 2 of 4)

address	register name	default value	R/W	description
0x3A04	DEBUG MODE	–	–	Debug Mode
0x3A05	AEC CTRL05	0x30	RW	AEC System Control 2 Bit[7]: Debug mode Bit[6]: frame insert 0: In night mode, insert frame disable 1: In night mode, insert frame enable Bit[5]: Step auto enable 0: Step manual mode 1: Step auto mode Bit[4:0]: Step auto ratio In step auto mode, step ratio setting to adjust speed
0x3A06	AEC CTRL06	0x10	RW	AEC System Control 3 Bit[7:5]: Debug mode Bit[4:0]: Step manual setting 1 Step manual Increase mode fast step
0x3A07	AEC CTRL07	0x18	RW	AEC Manual Step Register Bit[7:4]: Step manual setting 2 Step manual, slow step Bit[3:0]: Step manual setting 3 Step manual, decrease mode fast step
0x3A08	AEC B50 STEP	0x01	RW	50Hz Band Width Bit[7:2]: Debug mode Bit[1:0]: B50 step[9:8]
0x3A09	AEC B50 STEP	0x27	RW	50Hz Band Width Bit[7:0]: B50 step[7:0]
0x3A0A	AEC B60 STEP	0x00	RW	60Hz Band Width Bit[7:2]: Debug mode Bit[1:0]: B60 step[13:8]
0x3A0B	AEC B60 STEP	0xF6	RW	60Hz Band Width Bit[7:0]: B60 step[7:0]
0x3A0C	AEC CTRL0C	0xE4	RW	Bit[7:4]: E1 max Decimal line high limit zone Bit[3:0]: E1 min Decimal line low limit zone
0x3A0D	AEC CTRL0D	0x08	RW	60Hz Max Bands in One Frame Bit[7:6]: Debug mode Bit[5:0]: B60 max

table 7-8 AEC/AGC power down domain control registers (sheet 3 of 4)

address	register name	default value	R/W	description
0x3A0E	AEC CTRL0E	0x06	RW	50Hz Max Bands in One Frame Bit[7:6]: Debug mode Bit[5:0]: B50 max
0x3A0F	AEC CTRL0F	0x78	RW	Stable Range High Limit (Enter) Bit[7:0]: WPT
0x3A10	AEC CTRL10	0x68	RW	Stable Range Low Limit (Enter) Bit[7:0]: BPT
0x3A11	AEC CTRL11	0xD0	RW	Step Manual Mode, Fast Zone High Limit Bit[7:0]: VPT high
0x3A12	DEBUG MODE	–	–	Debug Mode
0x3A13	AEC CTRL13	0x40	RW	Bit[7]: Debug mode Bit[6]: Pre-gain enable Bit[5:0]: Pre-gain value 0x40 = 1x
0x3A14	AEC MAX EXPO (50HZ)	0x0E	RW	50Hz Maximum Exposure Output Limit Bit[7:4]: Debug mode Bit[3:0]: Max exposure[15:8]
0x3A15	AEC MAX EXPO (50HZ)	0x40	RW	50Hz Maximum Exposure Output Limit Bit[7:0]: Max exposure[7:0]
0x3A16	DEBUG MODE	–	–	Debug Mode
0x3A17	AEC CTRL17	0x01	RW	Gain Base When in Night Mode Bit[7:2]: Debug mode Bit[1:0]: Gain night threshold 00: 00 01: 10 10: 30 11: 70
0x3A18	AEC GAIN CEILING	0x03	RW	Gain Output Top Limit Bit[7:2]: Debug mode Bit[1:0]: AEC gain ceiling[9:8] Real gain format
0x3A19	AEC GAIN CEILING	0xE0	RW	Gain Output Top Limit Bit[7:0]: AEC gain ceiling[7:0] Real gain format
0x3A1A	AEC DIFF MIN	0x04	RW	Reserved Default Value for This Register Bit[7:0]: Difference minimal
0x3A1B	AEC CTRL1B	0x78	RW	Stable Range High Limit (Go Out) Bit[7:0]: WPT2
0x3A1C	LED ADD ROW	0x06	RW	Exposure Values Added When Strobe is On Bit[7:0]: AEC LED add row[15:8]

table 7-8 AEC/AGC power down domain control registers (sheet 4 of 4)

address	register name	default value	R/W	description
0x3A1D	LED ADD ROW	0x18	RW	Exposure Values Added When Strobe is On Bit[7:0]: AEC LED add row[7:0]
0x3A1E	AEC CTRL1E	0x68	RW	Stable Range Low Limit (Go Out) Bit[7:0]: BPT2
0x3A1F	AEC CTRL1F	0x40	RW	Step Manual Mode, Fast Zone Low Limit Bit[7:0]: VPT low
0x3A20	AEC CTRL20	0x20	RW	Bit[7:3]: Debug mode Bit[2]: Strobe option Bit[1:0]: Debug mode
0x3A21	AEC CTRL21	0x78	RW	Bit[7]: Debug mode Bit[6:4]: Insert frame number Bit[3:0]: Debug mode
0x3A22~ 0x3A24	DEBUG MODE	—	—	Debug Mode
0x3A25	AEC CTRL25	0x00	RW	Bit[7:5]: Debug mode Bit[4:2]: Freeze counter Bit[1:0]: Debug mode

table 7-9 STROBE registers (sheet 1 of 2)

address	register name	default value	R/W	description
0x3B00	STROBE CTRL	0x00	RW	Bit[7]: Strobe request on/off 0: Off 1: On Bit[6]: Strobe pulse reverse Bit[3:2]: width_in_xenon Bit[1:0]: Strobe mode 00: Xenon 01: LED1 10: LED2 11: LED3
0x3B01	FREX EXPOSURE 02	0x00	RW	Bit[7:0]: FREX exposure time[23:16]
0x3B02	FREX SHUTTER DELAY 01	0x08	RW	Bit[7:6]: Debug mode Bit[5:0]: Shutter delay time[12:8]
0x3B03	FREX SHUTTER DELAY 00	0x00	RW	Bit[7:0]: Shutter delay time[7:0] Unit: 64x SCLK cycle
0x3B04	FREX EXPOSURE 01	0x04	RW	Bit[7:0]: FREX exposure time[15:8]
0x3B05	FREX EXPOSURE 00	0x00	RW	Bit[7:0]: FREX exposure time[7:0] Unit: Tline

table 7-9 STROBE registers (sheet 2 of 2)

address	register name	default value	R/W	description
0x3B06	FREX CTRL 07	0x04	RW	Bit[7:4]: FREX frame delay Bit[3:0]: Strobe width[3:0]
0x3B07	FREX MODE	0x08	RW	FREX Mode Selection Bit[7:0]: FREX mode 00: FREX strobe mode0 01: FREX strobe mode1 1x: Rolling strobe
0x3B08	FREX REQUEST	0x00	RW	FREX Request
0x3B09	FREX HREF DELAY	0x02	RW	FREX HREF Delay
0x3B0A	FREX RST LENGTH	0x04	RW	Bit[7:3]: Debug mode Bit[2:0]: FREX precharge length 000: 1/16 Tline 001: 1/8 Tline 010: 1/4 Tline 011: 1/2 Tline 100: 1 Tline 101: 2 Tline 110: 4 Tline 111: 8 Tline
0x3B0B	STROBE WIDTH	0x00	RW	Bit[7:0]: Strobe width[19:12]
0x3B0C	STROBE WIDTH	0x3D	RW	Bit[7:0]: Strobe width[11:4]

table 7-10 5060HZ detector registers (sheet 1 of 3)

address	register name	default value	R/W	description
0x3C00	5060HZ CTRL00	0x00	RW	Bit[7:6]: Debug mode Bit[5]: Time counter threshold divisor enable Bit[4]: Low limit enable Bit[3]: Debug mode Bit[2]: Band50 default value Bit[1:0]: Time counter threshold 00: 1s 01: 2s 10: 4s 11: 8s
0x3C01	5060HZ CTRL01	0x00	RW	Bit[7]: Band manual enable Bit[6]: Band begin reset enable Bit[5]: Sum auto mode enable Bit[4]: Band counter enable Bit[3:0]: Band counter Counter threshold for band change

table 7-10 5060HZ detector registers (sheet 2 of 3)

address	register name	default value	R/W	description
0x3C02	5060HZ CTRL02	0x00	RW	Bit[7:6]: Debug mode Bit[5:0]: Low light threshold No detection under low light Bit[7:6]: Low light limit mode
0x3C03	5060HZ CTRL03	0x00	RW	Bit[7:0]: Counter threshold for low light
0x3C04	5060HZ CTRL04	0x20	RW	Bit[7:0]: Threshold for low sum
0x3C05	5060HZ CTRL05	0x70	RW	Bit[7:0]: Threshold for high sum
0x3C06	LIGHT METER1 THRESHOLD	0x00	RW	Bit[7:0]: Lightmeter1 threshold[15:8]
0x3C07	LIGHT METER1 THRESHOLD	0x00	RW	Bit[7:0]: Lightmeter1 threshold[7:0]
0x3C08	LIGHT METER2 THRESHOLD	0x01	RW	Bit[7:0]: Lightmeter2 threshold[15:8]
0x3C09	LIGHT METER2 THRESHOLD	0x2C	RW	Bit[7:0]: Lightmeter2 threshold[7:0]
0x3C0A	SAMPLE NUMBER	0x4E	RW	Bit[7:0]: Sample number[15:8]
0x3C0B	SAMPLE NUMBER	0x1F	RW	Bit[7:0]: Sample number[7:0]
0x3C0C	SIGMADELTA CTRL0C	—	R	Bit[7:4]: Band counter Bit[1]: Sign bit of sum50/60 Bit[0]: Band50/60 0: 60Hz light 1: 50Hz light
0x3C0D	SUM 50	—	R	Bit[7:5]: Debug mode Bit[4:0]: Sum50[28:24]
0x3C0E	SUM 50	—	R	Bit[7:0]: Sum50[23:16]
0x3C0F	SUM 50	—	R	Bit[7:0]: Sum50[15:8]
0x3C10	SUM 50	—	R	Bit[7:0]: Sum50[7:0]
0x3C11	SUM 60	—	R	Bit[7:5]: Debug mode Bit[4:0]: Sum60[28:24]
0x3C12	SUM 60	—	R	Bit[7:0]: Sum60[23:16]
0x3C13	SUM 60	—	R	Bit[7:0]: Sum60[15:8]
0x3C14	SUM 60	—	R	Bit[7:0]: Sum60[7:0]
0x3C15	SUM 50 60	—	R	Bit[7:0]: Sum50/60[15:8]
0x3C16	SUM 50 60	—	R	Bit[7:0]: Sum50/60[7:0]
0x3C17	BLOCK COUNTER	—	R	Bit[7:0]: Block counter[15:8]

table 7-10 5060HZ detector registers (sheet 3 of 3)

address	register name	default value	R/W	description
0x3C18	BLOCK COUNTER	–	R	Bit[7:0]: Block counter[7:0]
0x3C19	B6	–	R	Bit[7:0]: B6[15:8]
0x3C1A	B6	–	R	Bit[7:0]: B6[7:0]
0x3C1B	LIGHTMETER OUTPUT	–	R	Bit[7:4]: Debug mode Bit[3:0]: Light meter output[19:16]
0x3C1C	LIGHTMETER OUTPUT	–	R	Bit[7:0]: Light meter output[15:8]
0x3C1D	LIGHTMETER OUTPUT	–	R	Bit[7:0]: Light meter output[7:0]
0x3C1E	SUM THRESHOLD	–	R	Sum Threshold

table 7-11 OTP control functions (sheet 1 of 2)

address	register name	default value	R/W	description
0x3D00	OTP DATA00	0x00	RW	OTP Dump/Load Data00
0x3D01	OTP DATA01	0x00	RW	OTP Dump/Load Data01
0x3D02	OTP DATA02	0x00	RW	OTP Dump/Load Data02
0x3D03	OTP DATA03	0x00	RW	OTP Dump/Load Data03
0x3D04	OTP DATA04	0x00	RW	OTP Dump/Load Data04
0x3D05	OTP DATA05	0x00	RW	OTP Dump/Load Data05
0x3D06	OTP DATA06	0x00	RW	OTP Dump/Load Data06
0x3D07	OTP DATA07	0x00	RW	OTP Dump/Load Data07
0x3D08	OTP DATA08	0x00	RW	OTP Dump/Load Data08
0x3D09	OTP DATA09	0x00	RW	OTP Dump/Load Data09
0x3D0A	OTP DATA0A	0x00	RW	OTP Dump/Load Data0a
0x3D0B	OTP DATA0B	0x00	RW	OTP Dump/Load Data0b
0x3D0C	OTP DATA0C	0x00	RW	OTP Dump/Load Data0c
0x3D0D	OTP DATA0D	0x00	RW	OTP Dump/Load Data0d
0x3D0E	OTP DATA0E	0x00	RW	OTP Dump/Load Data0e
0x3D0F	OTP DATA0F	0x00	RW	OTP Dump/Load Data0f
0x3D10	OTP DATA10	0x00	RW	OTP Dump/Load Data10

table 7-11 OTP control functions (sheet 2 of 2)

address	register name	default value	R/W	description
0x3D11	OTP DATA11	0x00	RW	OTP Dump/Load Data11
0x3D12	OTP DATA12	0x00	RW	OTP Dump/Load Data12
0x3D13	OTP DATA13	0x00	RW	OTP Dump/Load Data13
0x3D14	OTP DATA14	0x00	RW	OTP Dump/Load Data14
0x3D15	OTP DATA15	0x00	RW	OTP Dump/Load Data15
0x3D16	OTP DATA16	0x00	RW	OTP Dump/Load Data16
0x3D17	OTP DATA17	0x00	RW	OTP Dump/Load Data17
0x3D18	OTP DATA18	0x00	RW	OTP Dump/Load Data18
0x3D19	OTP DATA19	0x00	RW	OTP Dump/Load Data19
0x3D1A	OTP DATA1A	0x00	RW	OTP Dump/Load Data1A
0x3D1B	OTP DATA1B	0x00	RW	OTP Dump/Load Data1B
0x3D1C	OTP DATA1C	0x00	RW	OTP Dump/Load Data1C
0x3D1D	OTP DATA1D	0x00	RW	OTP Dump/Load Data1D
0x3D1E	OTP DATA1E	0x00	RW	OTP Dump/Load Data1E
0x3D1F	OTP DATA1F	0x00	RW	OTP Dump/Load Data1F
0x3D20	OTP PROGRAM CTRL	0x00	RW	Bit[7]: OTP program busy Bit[6:2]: Debug mode Bit[1]: OTP program speed 0: Fast 1: Slow Bit[0]: OTP program enable
0x3D21	OTP READ CTRL	0x00	RW	Bit[7]: OTP read busy Bit[1]: OTP read speed 0: Fast 1: Slow Bit[0]: OTP read enable

table 7-12 BIST registers (sheet 1 of 3)

address	register name	default value	R/W	description
0x3E00	BIST_START_ADDRESS	0x00	RW	Bit[7:0]: Specify BIST start address[15:8]
0x3E01	BIST_START_ADDRESS	0x00	RW	Bit[7:0]: Specify BIST start address[7:0]
0x3E02	BIST_END_ADDRESS	0x0F	RW	Bit[7:0]: Specify BIST end address[15:8]

table 7-12 BIST registers (sheet 2 of 3)

address	register name	default value	R/W	description
0x3v03	BIST_END_ADDRESS	0xDB	RW	Bit[7:0]: Specify BIST end address[7:0]
0x3E04	BIST_R4	0x14	RW	BIST Option Counter Bit[7:5]: Debug mode Bit[4:0]: BIST OP counter Specify BIST operation number It can be settled from 0x02 to 0x14
0x3E05	BIST_R5	0x00	RW	BIST Special Data Bit[7:0]: Specify data written into memory in special mode
0x3E06	BIST_R6	0x03	RW	SRAM Select Specify SRAM Select
0x3E07	BIST_CTRL07	0x20	RW	Bit[7]: BIST start Specify BIST start It should first be high, then low Bit[6]: Specify BIST restart Bit[5]: BIST mode Specifies BIST test mode 0: Manual mode 1: Auto mode Bit[4]: Special BIST special mode Bit[3]: Specify read only mode Bit[2:0]: Debug mode
0x3E0C	BIST_CTRL12	0x00	RW	Bit[7:5]: Debug mode Bit[4]: BIST busy Specify BIST busy status Bit[2:0]: BIST error byte Specify BIST error type
0x3E0D	BIST_RESULT00	0x00	RW	BIST Test Result00 (0: BIST pass; 1: BIST error) Bit[7:2]: Debug mode Bit[1]: MCP RAM Bit[0]: SRM
0x3E0E	BIST_RESULT01	0x00	RW	BIST Test Result01 (0: BIST pass; 1: BIST error) Bit[7]: PFIFO2 Bit[6]: PFIFO1 Bit[5]: VFIFO Bit[4]: JFIFO Bit[3]: SFIFO Bit[2]: SCALE2 Bit[1]: SCALE1 Bit[0]: DPC4

table 7-12 BIST registers (sheet 3 of 3)

address	register name	default value	R/W	description
0x3E0F	BIST RESULT02	0x00	RW	BIST Test Result02 (0: BIST pass; 1: BIST error) Bit[7]: DPC3 Bit[6]: DPC2 Bit[5]: DPC1 Bit[4]: CIP3 Bit[3]: CIP2 Bit[2]: CIP1 Bit[1]: AWB Bit[0]: MCU IRAM

table 7-13 MC registers (sheet 1 of 3)

address	register name	default value	R/W	description
0x3F00	MC CTRL00	0x00	RW	Bit[7:5]: Debug mode Bit[4]: DW8051 manual reset enable Bit[3]: DW8051 manual reset Bit[2]: IRAM manual reset enable Bit[1]: IRAM manual reset Bit[0]: Soft reset MCU 0: Debug mode 1: Reset MCU
0x3F01	MC INTERRUPT MASK0	0x00	RW	Bit[7:0]: Mask0 for interrupt 0: Disable interrupt bit 1: Enable interrupt bit
0x3F02	MC INTERRUPT MASK1	0x00	RW	Bit[7:0]: Mask1 for interrupt 0: Disable interrupt bit 1: Enable interrupt bit
0x3F03	MC READ INTERRUPT ADDRESS	0x70	RW	Bit[7:0]: Set high byte for SCCB address that will trigger interrupt when read
0x3F04	MC READ INTERRUPT ADDRESS	0x00	RW	Bit[7:0]: Set low byte for SCCB address that will trigger interrupt when read
0x3F05	MC WRITE INTERRUPT ADDRESS	0x70	RW	Bit[7:0]: Set high byte for SCCB address that will trigger interrupt when written
0x3F06	MC WRITE INTERRUPT ADDRESS	0x04	RW	Bit[7:0]: Set low byte for SCCB address that will trigger interrupt when written

table 7-13 MC registers (sheet 2 of 3)

address	register name	default value	R/W	description
0x3F08	MC INTERRUPT SOURCE SELECTION1	0x00	RW	Bit[7:6]: Interrupt1[7] source selection 0x: AEC done 10: Debug mode 11: DVP HREF falling edge Bit[5:4]: Interrupt1[6] source selection 00: ISP average done 01: FREX rising edge 10: Debug mode 11: DVP VSYNC falling edge Bit[3:2]: Interrupt1[5] source selection 00: AEC trigger 01: FREX falling edge 10: MIPI frame end 11: DVP VSYNC rising edge Bit[1:0]: Interrupt1[4] source selection 0x: JPEG over size 10: MIPI line end 11: DVP HREF rising edge
0x3F09	MC INTERRUPT SOURCE SELECTION2	0x00	RW	Bit[7:6]: Interrupt1[3] source selection 0x: Debug mode 11: SRM operation start Bit[5:4]: Interrupt1[2] source selection 0x: Debug mode 11: SRM operation done Bit[3:2]: Interrupt1[1] source selection 0x: Debug mode 11: DVP frame counter change Bit[1:0]: Interrupt1[0] source selection 0x: BLC SOF 11: Debug mode
0x3F0A	MC INTERRUPT SOURCE SELECTION3	0x00	RW	Bit[7:6]: Interrupt0[7] source selection 00: JFIFO over flow 01: ISP end frame 10: SFIFO end of frame 11: JFIFO end frame Bit[5:4]: Interrupt0[6] source selection 0x: JFIFO end of image 10: F1 FIFO write 11: VFIFO ready Bit[3:2]: Interrupt0[5] source selection 00: ISP end of frame 01: SFIFO end of frame 10: JFIFO end of frame 11: VFIFO end of frame Bit[1:0]: Interrupt0[4] source selection 00: ISP start of frame 01: SFIFO start of frame 10: JFIFO start of frame 11: VFIFO start of frame

table 7-13 MC registers (sheet 3 of 3)

address	register name	default value	R/W	description
0x3F0B	MC INTERRUPT SOURCE SELECTION4	0x00	RW	Bit[7:6]: Interrupt0[3] source selection 0x: AFC done 10: HREF falling edge 11: BIST done Bit[5:4]: Interrupt0[2] source selection 00: AWB done 01: ISP start of frame 10: SFIFO start of frame 11: JFIFO start of frame Bit[3:2]: Interrupt0[1] source selection 00: VFIFO full 01: ISP FC SOF 10: f2_fifo_wr 11: Write a specific address Bit[1:0]: Interrupt0[0] source selection 00: VFIFO empty 01: ISP line 10: ISP end of frame 11: Read a specific address
0x3F0C	MC INTERRUPT0 STATUS	–	R	Bit[7:0]: Interrupt0 status indication
0x3F0D	MC INTERRUPT1 STATUS	–	R	Bit[7:0]: Interrupt1 status indication

table 7-14 BLC registers (sheet 1 of 3)

address	register name	default value	R/W	description
0x4000	BLC CTRL00	0x89	RW	BLC Control 00 (0: disable; 1: enable) Bit[7:3]: Debug mode Bit[2]: Apply2blackline Bit[1]: Black line average frame Bit[0]: BLC enable
0x4001	BLC CTRL01	0x00	RW	Bit[7:6]: Debug mode Bit[5:0]: BLC start line
0x4002	BLC CTRL02	0x45	RW	Bit[7]: Format change enable BLC update when format changes Bit[6]: BLC auto enable 0: Manual 1: Auto Bit[5:0]: Reset frame number Frame number BLC do after reset

table 7-14 BLC registers (sheet 2 of 3)

address	register name	default value	R/W	description
0x4003	BLC CTRL03	0x08	RW	Bit[7]: BLC redo enable Write 1 to thisbit will trigger a BLC redo N frames begin, where N is 0x4003[5:0] Bit[6]: BLC freeze Bit[5:0]: Manual frame number
0x4004	BLC CTRL04	0x08	RW	Bit[7:0]: BLC line number Specify the line number BLC process
0x4005	BLC CTRL05	0x18	RW	Bit[7:2]: Debug mode Bit[1]: BLC always update 0: Normal freeze 1: BLC always update Bit[0]: Debug mode
0x4006	DEBUG MODE	–	–	Debug Mode
0x4007	BLC CTRL07	0x00	RW	Bit[7:5]: Debug mode Bit[4:3]: Window selection 00: Full image 01: A windows not contain the first 16 pixels and the end 16 pixels 10: A windows not contain the first 1/16 image and the end 1/16 image 11: A windows not contain the first 1/8 image and the end 1/8 image Bit[2:0]: Debug mode
0x4008	DEBUG MODE	–	–	Debug Mode
0x4009	BLACK LEVEL	0x10	RW	Bit[7:0]: BLC black level target at 10-bit range
0x400C~0x402B	DEBUG MODE	–	–	Debug Mode
0x402C	BLACK LEVEL00	0x00	RW	Bit[7:0]: Blacklevel00[15:8] With 3 decimal
0x402D	BLACK LEVEL00	0x00	RW	Bit[7:0]: Blacklevel00[7:0] With 3 decimal
0x402E	BLACK LEVEL01	0x00	RW	Bit[7:0]: Blacklevel01[15:8] With 3 decimal
0x402F	BLACK LEVEL01	0x00	RW	Bit[7:0]: Blacklevel01[7:0] With 3 decimal
0x4030	BLACK LEVEL10	0x00	RW	Bit[7:0]: Blacklevel10[15:8] With 3 decimal

table 7-14 BLC registers (sheet 3 of 3)

address	register name	default value	R/W	description
0x4031	BLACK LEVEL10	0x00	RW	Bit[7:0]: Blacklevel10[7:0] With 3 decimal
0x4032	BLACK LEVEL11	0x00	RW	Bit[7:0]: Blacklevel11[15:8] With 3 decimal
0x4033	BLACK LEVEL11	0x00	RW	Bit[7:0]: Blacklevel11[7:0] With 3 decimal

table 7-15 frame control registers

address	register name	default value	R/W	description
0x4201	FRAME CTRL01	0x00	R/W	Control Passed Frame Number When both ON and OFF number set to 0x00, frame control is in bypass mode Bit[7:4]: Debug mode Bit[3:0]: Frame ON number
0x4202	FRAME CTRL02	0x00	R/W	Control Masked Frame Number When both ON and OFF number set to 0x00, frame control is in bypass mode Bit[7:4]: Debug mode BIT[3:0]: Frame OFF number

table 7-16 FORMAT control registers (sheet 1 of 5)

address	register name	default value	R/W	description
0x4300	FORMAT CONTROL 00	0xF8	RW	<p>Format Control 00</p> <p>Bit[7:4]: Output format of formatter module</p> <p>0x0: RAW</p> <p>Bit[3:0]: Output sequence</p> <p>0x0: BGBG... / GRGR...</p> <p>0x1: GBGB... / RGRG...</p> <p>0x2: GRGR... / BGBG...</p> <p>0x3: RGRG... / GBGB...</p> <p>0x4~0xF: Not allowed</p> <p>0x1: Y8</p> <p>Bit[3:0]: Does not matter</p> <p>0x2: YUV444/RGB888 (not available for full resolution)</p> <p>Bit[3:0]: Output sequence</p> <p>0x0: YUVYUV..., or GBRGBR...</p> <p>0x1: YVUYVU..., or GRBGRB...</p> <p>0x2: UYVUYV..., or BGRBGR...</p> <p>0x3: VYUYVU..., or RGBRGB...</p> <p>0x4: UVYUVY..., or BRBGRG...</p> <p>0x5: VUYVUY..., or RBGRBG...</p> <p>0x6~0xE: Not allowed</p> <p>0xF: UYVUYV..., or BGRBGR...</p> <p>0x3: YUV422</p> <p>Bit[3:0]: Output sequence</p> <p>0x0: YUYV...</p> <p>0x1: YVYU...</p> <p>0x2: UYVY...</p> <p>0x3: VYUY...</p> <p>0x4~0xE: Not allowed</p> <p>0xF: UYVY...</p> <p>0x4: YUV420</p> <p>Bit[3:0]: Output sequence</p> <p>0x0: YYYY... / YUYV...</p> <p>0x1: YYYY... / YVYU...</p> <p>0x2: YYYY... / UYVY...</p> <p>0x3: YYYY... / VYUY...</p> <p>0x4: YUYV... / YYYY...</p>

table 7-16 FORMAT control registers (sheet 2 of 5)

address	register name	default value	R/W	description
				0x5: YVYU... / YYYY...
				0x6: UYVY... / YYYY...
				0x7: VYUY... / YYYY...
				0x8~0xE: Not allowed
				0xF: YYYY... / UYVY...
				0x5: YUV420 (for MIPI only)
				Bit[3:0]: Output sequence
				0x0~0xD: Not allowed
				0xE: VYVYVY... / UYUYUY...
				0xF: UYUYUY... / VYVYVY...
				0x6: RGB565
				Bit[3:0]: Output sequence
				0x0: {b[4:0],g[5:3]}, {g[2:0],r[4:0]}
				0x1: {r[4:0],g[5:3]}, {g[2:0],b[4:0]}
				0x2: {g[4:0],r[5:3]}, {r[2:0],b[4:0]}
				0x3: {b[4:0],r[5:3]}, {r[2:0],g[4:0]}
				0x4: {g[4:0],b[5:3]}, {b[2:0],r[4:0]}
				0x5: {r[4:0],b[5:3]}, {b[2:0],g[4:0]}
				0x6~0xE: Not allowed
				0xF: {g[2:0],b[4:0]}, {r[4:0],g[5:3]}
				0x7: RGB555 format 1
				Bit[3:0]: Output sequence
				0x0: {b[4:0],g[4:2]}, {g[1:0],1'b0,r[4:0]}
				0x1: {r[4:0],g[4:2]}, {g[1:0],1'b0,b[4:0]}
				0x2: {g[4:0],r[4:2]}, {r[1:0],1'b0,b[4:0]}
				0x3: {b[4:0],r[4:2]}, {r[1:0],1'b0,g[4:0]}
				0x4: {r[4:0],b[4:2]}, {b[1:0],1'b0,g[4:0]}
				0x5: {g[4:0],b[4:2]}, {b[1:0],1'b0,r[4:0]}
				0x6~0xE: Not allowed
				0xF: {g[1:0],1'b0,b[4:0]}, {r[4:0],g[4:2]}
				0x8: RGB555 format 2
				Bit[3:0]: Output sequence
				0x0: {1'b0,b[4:0],g[4:3]}, {g[2:0],r[4:0]}

table 7-16 FORMAT control registers (sheet 3 of 5)

address	register name	default value	R/W	description
				0x1: {1'b0,r[4:0],g[4:2]}, {g[2:0],b[4:0]}
				0x2: {1'b0,g[4:0],r[4:2]}, {r[2:0],b[4:0]}
				0x3: {1'b0,b[4:0],r[4:2]}, {r[2:0],g[4:0]}
				0x4: {1'b0,r[4:0],b[4:2]}, {b[2:0],g[4:0]}
				0x5: {1'b0,g[4:0],b[4:2]}, {b[2:0],r[4:0]}
				0x6: {b[4:0],1'b0,g[4:3]}, {g[2:0],r[4:0]}
				0x7: {r[4:0],1'b0,g[4:2]}, {g[2:0],b[4:0]}
				0x8: {g[4:0],1'b0,r[4:2]}, {r[2:0],b[4:0]}
				0x9: {b[4:0],1'b0,r[4:2]}, {r[2:0],g[4:0]}
				0xA: {r[4:0],1'b0,b[4:2]}, {b[2:0],g[4:0]}
				0xB: {g[4:0],1'b0,b[4:2]}, {b[2:0],r[4:0]}
				0xC~0xF: Not allowed
				0x9: RGB444 format 1
				Bit[3:0]: Output sequence
				0x0: {1'b0,b[3:0],2'h0,g[3]}, {g[2:0],1'b0,r[3:0]}
				0x1: {1'b0,r[3:0],2'h0,g[3]}, {g[2:0],1'b0,b[3:0]}
				0x2: {1'b0,g[3:0],2'h0,r[3]}, {r[2:0],1'b0,b[3:0]}
				0x3: {1'b0,b[3:0],2'h0,r[3]}, {r[2:0],1'b0,g[3:0]}
				0x4: {1'b0,r[3:0],2'h0,b[3]}, {b[2:0],1'b0,g[3:0]}
				0x5: {1'b0,g[3:0],2'h0,b[3]}, {b[2:0],1'h0,r[3:0]}
				0x6: {b[3:0],1'b0,g[3:1]}, {g[0],2'h0,r[3:0],1'b0}
				0x7: {r[3:0],1'b0,g[3:1]}, {g[0],2'h0,b[3:0],1'b0}
				0x8: {g[3:0],1'b0,r[3:1]}, {r[0],2'h0,b[3:0],1'b0}
				0x9: {b[3:0],1'b0,r[3:1]}, {r[0],2'h0,g[3:0],1'b0}
				0xA: {r[3:0],1'b0,b[3:1]}, {b[0],2'h0,g[3:0],1'b0}
				0xB: {g[3:0],1'b0,b[3:1]}, {b[0],2'h0,r[3:0],1'b0}
				0xC~0xE: Not allowed

table 7-16 FORMAT control registers (sheet 4 of 5)

address	register name	default value	R/W	description
				0xF: {g[0],2'h2,b[3:0],1'b1}, {r[3:0],1'b1,g[3:1]}
				0xA: RGB444 format 2
				Bit[3:0]: Output sequence
				0x0: {4'b0,b[3:0]}, {g[3:0],r[3:0]}
				0x1: {4'b0,r[3:0]}, {g[3:0],b[3:0]}
				0x2: {4'b0,b[3:0]}, {r[3:0],g[3:0]}
				0x3: {4'b0,r[3:0]}, {b[3:0],g[3:0]}
				0x4: {4'b0,g[3:0]}, {b[3:0],r[3:0]}
				0x5: {4'b0,g[3:0]}, {r[3:0],b[3:0]}
				0x6: {b[3:0],g[3:0],2'h0}, {r[3:0],b[3:0],2'h0,g[3:0],r[3:0],2'h0}
				0x7: {r[3:0],g[3:0],2'h0}, {b[3:0],r[3:0],2'h0,g[3:0],b[3:0],2'h0}
				0x8: {b[3:0],r[3:0],2'h0}, {g[3:0],b[3:0],2'h0,r[3:0],g[3:0],2'h0}
				0x9: {r[3:0],b[3:0],2'h0}, {g[3:0],r[3:0],2'h0,b[3:0],g[3:0],2'h0}
				0xA: {g[3:0],b[3:0],2'h0}, {r[3:0],g[3:0],2'h0,b[3:0],r[3:0],2'h0}
				0xB: {g[3:0],r[3:0],2'h0}, {b[3:0],g[3:0],2'h0,r[3:0],b[3:0],2'h0}
				0xC~0xF: Not allowed
				0xB~0xE: Not allowed
				0xF: Bypass formatter module (not recommended)
				Bit[3:0]: Output format
				0x8: Raw
				0x9: YUV422
				0xA: YUV444
				0xE: VYYYVYYY.../UYUYUY
				0xF: UYYUYUY.../VYYYVYYY

table 7-16 FORMAT control registers (sheet 5 of 5)

address	register name	default value	R/W	description
0x4301	FORMAT CONTROL 01	0x00	RW	Format Control 01 Bit[1:0]: YUV422 UV control 00: U/V generated from average 01: U/V generated from first pixel 10: Not valid 11: U/V generated from second pixel
0x4302	YMAX VALUE	0x03	RW	Bit[7:2]: Debug mode Bit[1:0]: Y max clip value[9:8]
0x4303	YMAX VALUE	0xFF	RW	Bit[7:0]: Y max clip value[7:0]
0x4304	YMIN VALUE	0x00	RW	Bit[7:2]: Debug mode Bit[1:0]: Y min clip value[9:8]
0x4305	YMIN VALUE	0x00	RW	Bit[7:0]: Y min clip value[7:0]
0x4306	UMAX VALUE	0x03	RW	Bit[7:2]: Debug mode Bit[1:0]: U max clip value[9:8]
0x4307	UMAX VALUE	0xFF	RW	Bit[7:0]: U max clip value[7:0]
0x4308	UMIN VALUE	0x00	RW	Bit[7:2]: Debug mode Bit[1:0]: U min clip value[9:8]
0x4309	UMIN VALUE	0x00	RW	Bit[7:0]: U min clip value[7:0]
0x430A	VMAX VALUE	0x03	RW	Bit[7:2]: Debug mode Bit[1:0]: V max clip value[9:8]
0x430B	VMAX VALUE	0xFF	RW	Bit[7:0]: V max clip value[7:0]
0x430C	VMIN VALUE	0x00	RW	Bit[7:2]: Debug mode Bit[1:0]: V min clip value[9:8]
0x430D	VMIN VALUE	0x00	RW	Bit[7:0]: V min clip value[7:0]

table 7-17 JPEG control registers (sheet 1 of 3)

address	register name	default value	R/W	description
0x4400	JPEG CTRL00	0x81	RW	Bit[7]: input_format 0: YUV420 1: YUV422 Bit[6:0]: JFIFO read speed control

table 7-17 JPEG control registers (sheet 2 of 3)

address	register name	default value	R/W	description
0x4401	JPEG CTRL01	0x01	RW	Bit[7:4]: SFIFO output buffer speed control Bit[3]: Read SRAM enable when blanking 0: Disable 1: Enable Bit[2]: Read SRAM at first blanking 0: Disable 1: Enable Bit[1:0]: SFIFO read speed control
0x4402	JPEG_CTRL02	0x10	RW	Bit[7]: SFIFO output control mode 0: Control by HREF and valid which before scale down 1: Control by input HREF and valid Bit[6:4]: SOF control 001: Start at the first valid HREF 010: Start at the eighth valid HREF Bit[3:0]: SFIFO output buffer speed control at last stripe
0x4403	JPEG CTRL03	0x33	RW	Bit[7]: Memory select 0: Select ROM QT 1: Select SRAM QT Bit[6]: MPEG enable Bit[5]: Enable zero stuff Bit[4]: Enable Huffman table output Bit[3]: Rounding enable for C Bit[2]: Rounding enable for Y Bit[1]: Input shift 128 select for C Bit[0]: Input shift 128 select for Y
0x4404	JPEG CTRL04	0x24	RW	Bit[7]: jfifo_pwrn Bit[6]: SFIFO PWRDN Bit[5]: Header output enable Bit[4]: Enable gated clock 0: Disable gated clock 1: Enable gated clock Bit[3]: Substitute 0xFF to 0xFE in QT Bit[2:0]: Quantization rounding bias: Set value = Bias/8
0x4405	JPEG CTRL05	0x40	RW	Bit[7:0]: QZ out truncate for Y
0x4406	JPEG CTRL06	0x40	RW	Bit[7:0]: QZ out truncate for C
0x4407	JPEG CTRL07	0x0C	RW	Bit[7]: Enable read QTA auto increment Bit[5:0]: QS Quantization scale

table 7-17 JPEG control registers (sheet 3 of 3)

address	register name	default value	R/W	description
0x4408	JPEG ISI CTRL	0x00	RW	Bit[7]: Scalado mode enable 0: Normal 1: Insert 0xFF after EOB Bit[6]: JPEG size manual enable Bit[5:4]: Debug mode Bit[3]: Replace 0xFF to 0xFE in comment data Bit[2]: Cut 0xD9 at the end of frame Bit[1]: EOI generation enable Bit[0]: ISI insert
0x4409	JPEG CTRL09	0x00	RW	Bit[7:0]: D9 data
0x440A	JPEG CTRL0A	0x4E	RW	Bit[7:0]: JFIFO output delay
0x440B	JPEG CTRL0B	0x16	RW	Bit[5]: Dummy read speed manual mode Bit[4:0]: SFIFO SOF delay
0x440C	JPEG CTRL0C	0x00	RW	Bit[7:0]: Dummy read speed
0x440D~ 0x440F	DEBUG MODE	–	–	Debug Mode
0x4410	JPEG QT DATA	0x00	RW	Bit[7:0]: QT data
0x4411	JPEG QT ADDR	0x00	RW	Bit[7:0]: QT address
0x4412	JPEG ISI DATA	0x00	RW	Bit[7:0]: ISI data
0x4413	JPEG ISI CTRL	–	RO	Bit[7:4]: Debug mode Bit[3]: D9 odd (read only) Bit[2]: Reset counter write 0: Debug mode 1: Reset counter Bit[1]: ISO EOF
0x4414	JPEG LENGTH	–	RO	Bit[7:0]: JPEG length[23:16]
0x4415	JPEG LENGTH	–	RO	Bit[7:0]: JPEG length[15:8]
0x4416	JPEG LENGTH	–	RO	Bit[7:0]: JPEG length[7:0]
0x4417	JFIFO OVERFLOW	–	RO	Bit[7:1]: Debug mode Bit[0]: JFIFO overflow indicator
0x4418~ 0x4419	DEBUG MODE	–	–	Debug Mode
0x4420~ 0x442F	JPEG COMMENT	0x00	RW	JPEG Comment Data Embedded in JPEG Data
0x4430	JPEG COMMENT	0x00	RW	Comment Length Two bytes align
0x4431	JPEG COMMENT	0xFE	RW	Comment Data Marker

table 7-18 VFIFO registers

address	register name	default value	R/W	description
0x4600	VFIFO CTRL00	0x80	RW	VFIFO Control 00 Bit[7:6]: Reserved Bit[5]: Compression output fixed height enable 0: In compression mode2, compression height is different in each frame 1: In compression mode2, compression height is fixed in each frame
0x4601	DEBUG MODE	–	–	Debug Mode
0x4602	VFIFO HSIZE	0x04	RW	Compression Output Width High Byte
0x4603	VFIFO HSIZE	0x00	RW	Compression Output Width Low Byte
0x4604	VFIFO VSIZE	0x03	RW	Compression Output Height High Byte
0x4605	VFIFO HSIZE	0x00	RW	Compression Output Height Low Byte
0x4606~0x460B	DEBUG MODE	–	–	Debug Mode
0x460C	VFIFO CTRL0C	0x20	RW	Bit[7:4]: JPEG dummy data pad speed Bit[2]: Footer disable JPEG footer disable 0: In jpg_mode2 footer will be added in the last six bytes of each frame 1: Disable footer Bit[1]: PCLK manual enable 0: DVP PCLK divider control by auto mode 1: DVP PCLK divider control by 0x3824[4:0]
0x460D	VFIFO CTRL0D	0x00	RW	Dummy Data

table 7-19 DVP control registers (sheet 1 of 3)

address	register name	default value	R/W	description
0x4709	DVP VYSNC WIDTH0	0x02	RW	VSYNC Width Line Unit
0x470A	DVP VYSNC WIDTH1	0x00	RW	Bit[7:0]: VSYNC width PCLK unit[15:8]
0x470B	DVP VYSNC WIDTH2	0x01	RW	Bit[7:0]: VSYNC width PCLK unit[7:0]
0x470C~ 0x4710	DEBUG MODE	–	–	Debug Mode
0x4711	PAD LEFT CTRL	0x00	RW	HSYNC Mode Left Padding Pixel Counter Add padding data at start of a line
0x4712	PAD RIGHT CTRL	0x00	RW	HSYNC Mode Right Padding Pixel Counter Add padding data at end of a line
0x4713	JPG MODE SELECT	0x02	RW	Bit[7:3]: Debug mode Bit[2:0]: JPEG mode select 001: JPEG mode 1 010: JPEG mode 2 011: JPEG mode 3 100: JPEG mode 4 101: JPEG mode 5 110: JPEG mode 6
0x4715	656 DUMMY LINE	0x00	RW	Bit[7:4]: Debug mode Bit[3:0]: CCIR656 dummy line number Control dummy line number at beginning of the frame
0x4719	CCIR656 CTRL	0x00	RW	Bit[7:2]: Debug mode Bit[1:0]: CCIR656 EAV/SAV option
0x471B	HSYNC CTRL00	0x02	RW	Bit[7:1]: Debug mode Bit[0]: HSYNC mode enable
0x471D	DVP VSYNC CTRL	0x01	RW	Bit[7:2]: Debug mode Bit[1:0]: vsync_mode 00: VSYNC positive edge trigger by end of field, negative edge trigger by start of frame 01: VSYNC positive edge trigger by end of frame, the width define by register 10: VSYNC positive edge trigger by start of field, the width define by register

table 7-19 DVP control registers (sheet 2 of 3)

address	register name	default value	R/W	description
0x471F	DVP HREF CTRL	0x40	RW	HREF Minimum Blanking in JPEG Mode23
0x4721	VERTICAL START OFFSET	0x00	RW	Bit[7:4]: Debug mode Bit[3:0]: Vertical start delay between video output and video input
0x4722	VERTICAL END OFFSET	0x00	RW	Bit[7:4]: Debug mode Bit[3:0]: Vertical end delay between video output and video input
0x4723	DVP CTRL23	0x00	RW	DVP JPEG Mode456 Skip Line Number
0x4730	CCIR656 CTRL00	0x00	RW	Bit[7]: SYNC code selection 0: Auto generate sync code 1: Sync code from register setting 0x4732~4735 Bit[6]: f value in CCIR656 SYNC code when fixed f value Bit[5]: Fixed f value Bit[4:3]: Blank toggle data options 00: Toggle data is 1'h040/1'h200 01: Use register setting 0x4736~0x4738 10: Blanking data always keep 0 Bit[1]: Clip data disable Bit[0]: CCIR656 mode enable
0x4731	CCIR656 CTRL01	0x00	RW	Bit[7:1]: Debug mode Bit[0]: Blanking toggle data order option
0x4732	CCIR656 FS	0x01	RW	CCIR656 SYNC Code Frame Start
0x4733	CCIR656 FE	0x0F	RW	CCIR656 SYNC Code Frame End
0x4734	CCIR656 LS	0x00	RW	CCIR656 SYNC Code Line Start
0x4735	CCIR656 LE	0x00	RW	CCIR656 SYNC Code Line End
0x4736	CCIR656 CTRL6	0x00	RW	Bit[7:4]: Debug mode Bit[3:2]: Toggle data0[9:8] Bit[1:0]: Toggle data1[9:8]
0x4737	CCIR656 CTRL7	0x00	RW	Bit[7:0]: Toggle data0[7:0]
0x4738	CCIR656 CTRL8	0x00	RW	Bit[7:0]: Toggle data1[7:0]

table 7-19 DVP control registers (sheet 3 of 3)

address	register name	default value	R/W	description
0x4740	POLARITY CTRL00	0x20	RW	Bit[7:6]: Debug mode Bit[5]: PCLK polarity 0: Active low 1: Active high Bit[3]: Gate PCLK under VSYNC Bit[2]: Gate PCLK under HREF Bit[1]: HREF polarity 0: Active low 1: Active high Bit[0]: VSYNC polarity 0: Active low 1: Active high
0x4741	TEST PATTERN	0x00	RW	Bit[7:3]: Debug mode Bit[2]: Test pattern enable Bit[1]: Test pattern select 0: Output test pattern 0 1: Output test pattern 1 Bit[0]: Test pattern 8-bit/10-bit 0: 10-bit test pattern 1: 8-bit test pattern
0x4742~ 0x4744	DEBUG MODE	—	—	Debug Mode
0x4745	DATA ORDER	0x00	RW	Bit[7:3]: Debug mode Bit[2:1]: DVP order option for debug 00: Data[9:0] 10: {data[7:0],data[9:8]} x1: {data[1:0],data[9:2]} Bit[0]: Output data order 0: Normal output 1: Reverse output data bit order

table 7-20 MIPI transmitter registers (sheet 1 of 3)

address	register name	default value	R/W	description
0x4800	MIPI CTRL 00	0x04	RW	MIPI Control 00 Bit[7:6]: Debug mode Bit[5]: Clock lane gate enable 0: Clock lane is free running 1: Gate clock lane when no packet to transmit Bit[4]: Line sync enable 0: Do not send line short packet for each line 1: Send line short packet for each line Bit[3]: Lane select 0: Use lane1 as default data lane 1: Use lane2 as default data lane Bit[2]: Idle status 0: MIPI bus will be LP00 when no packet to transmit 1: MIPI bus will be LP11 when no packet to transmit Bit[1:0]: Debug mode
0x4801	MIPI CTRL 01	0x04	RW	MIPI Control 01 Bit[7:5]: Debug mode Bit[4]: PH bit order for ECC 0: {DI[7:0],WC[7:0],WC[15:8]} 1: {DI[0:7],WC[0:7],WC[8:15]} Bit[3]: PH byte order for ECC 0: {DI,WC_l,WC_h} 1: {DI,WC_h,WC_l} Bit[2]: PH byte order2 for ECC 0: {DI,WC} 1: {WC,DI} Bit[1:0]: Debug mode
0x4802~0x4804	DEBUG MODE	—	—	Debug Mode
0x4805	MIPI CTRL 05	0x10	RW	Bit[7]: MIPI lane1 disable 1: Disable MIPI data lane1 Lane1 will be LP00 Bit[6]: MIPI lane1 disable 1: Disable MIPI data lane1 Lane1 will be LP00 Bit[5]: LPX Global timing select 0: Auto calculate t_lpx_o in pclk2x domain, unit clk2x 1: Use lp_p_min[7:0] Bit[6:0]: Debug mode
0x4806~0x4809	DEBUG MODE	—	—	Debug Mode

table 7-20 MIPI transmitter registers (sheet 2 of 3)

address	register name	default value	R/W	description
0x480A	MIPI DATA ORDER	0x00	RW	Bit[7:3]: Debug mode Bit[2]: Bit order reverse Bit[1:0]: Bit position adjust 01: {data[7:0],data[9:8]} 10: {data[1:0],data[9:2]}
0x480B~ 0x4817	DEBUG MODE	–	–	Debug Mode
0x4818	MIN HS ZERO H	0x00	RW	High Byte of Minimum Value of hs_zero Unit ns
0x4819	MIN HS ZERO L	0x96	RW	Low Byte of Minimum Value of hs_zero $hs_zero_real = hs_zero_min_o + Tui*ui_hs_zero_min_o$
0x481A	MIN MIPI HS TRAIL H	0x00	RW	High Byte of Minimum Value of hs_trail Unit ns
0x481B	MIN MIPI HS TRAIL L	0x3C	RW	Low Byte of Minimum Value of hs_trail $hs_trail_real = hs_trail_min_o + Tui*ui_hs_trail_min_o$
0x481C	MIN MIPI CLK ZERO H	0x01	RW	High Byte of Minimum Value of clk_zero
0x481D	MIN MIPI CLK ZERO L	0x86	RW	Low Byte of Minimum Value of clk_zero $clk_zero_real = clk_zero_min_o + Tui*ui_clk_zero_min_o$
0x481E	MIN MIPI CLK PREPARE H	0x00	RW	High Byte of Minimum Value of clk_prepare Unit ns
0x481F	MIN MIPI CLK PREPARE L	0x3C	RW	Low Byte of Minimum Value of clk_prepare $clk_prepare_real = clk_prepare_min_o + Tui*ui_clk_prepare_min_o$
0x4820	MIN CLK POST H	0x00	RW	High Byte of Minimum Value of clk_post Unit ns
0x4821	MIN CLK POST L	0x56	RW	Low Byte of Minimum Value of clk_post $clk_post_real = clk_post_min_o + Tui*ui_clk_post_min_o$
0x4822	MIN CLK TRAIL H	0x00	RW	High Byte of Minimum Value of clk_trail Unit ns
0x4823	MIN CLK TRAIL L	0x3C	RW	Low Byte of Minimum Value of clk_trail $clk_trail_real = clk_trail_min_o + Tui*ui_clk_trail_min_o$
0x4824	MIN LPX PCLK H	0x00	RW	High Byte of Minimum Value of lpx_p Unit ns
0x4825	MIN LPX PCLK L	0x32	RW	Low Byte of Minimum Value of lpx_p $lpx_p_real = lpx_p_min_o + Tui*ui_lpx_p_min_o$
0x4826	MIN HS PREPARE H	0x00	RW	High Byte of Minimum Value of hs_prepare Unit ns

table 7-20 MIPI transmitter registers (sheet 3 of 3)

address	register name	default value	R/W	description
0x4827	MIN HS PREPARE L	0x32	RW	Low Byte of Minimum Value of hs_prepare $hs_prepare_real = hs_prepare_min_o + Tui*ui_hs_prepare_min_o$
0x4828	MIN HS EXIT H	0x00	RW	High Byte of Minimum Value of hs_exit Unit ns
0x4829	MIN HS EXIT L	0x64	RW	Low Byte of Minimum Value of hs_exit $hs_exit_real = hs_exit_min_o + Tui*ui_hs_exit_min_o$
0x482A	MIN HS ZERO/UI	0x05	RW	Minimum UI Value of hs_zero Unit UI
0x482B	MIN HS TRAIL/UI	0x04	RW	Minimum UI Value of hs_trail Unit UI
0x482C	MIN CLK ZERO/UI	0x00	RW	Minimum UI Value of clk_zero Unit UI
0x482D	MIN CLK PREPARE/UI	0x00	RW	Minimum UI Value of clk_prepare Unit UI
0x482E	MIN CLK POST/UI	0x34	RW	Minimum UI Value of clk_post Unit UI
0x482F	MIN CLK TRAIL/UI	0x00	RW	Minimum UI Value of clk_trail Unit UI
0x4830	MIN LPX PCLK/UI	0x00	RW	Minimum UI Value of lpx_p(pclk2x domain) Unit UI
0x4831	MIN HS PREPARE/UI	0x04	RW	Minimum UI Value of hs_prepare Unit UI
0x4832	MIN HS EXIT/UI	0x00	RW	Minimum UI Value of hs_exit Unit UI
0x4833~ 0x4836	DEBUG MODE	–	–	Debug Mode
0x4837	PCLK PERIOD	0x10	RW	Period of pixel clock, pclk_div=1, and 1-bit decimal

table 7-21 ISP frame control registers

address	register name	default value	R/W	description
0x4901	FRAME CTRL01	0x00	RW	Control Passed Frame Number When both ON and OFF number set to 0x00, frame control is in bypass mode Bit[7:4]: Debug mode Bit[3:0]: Frame ON number
0x4902	FRAME CTRL02	0x00	RW	Control Masked Frame Number When both ON and OFF number set to 0x00, frame control is in bypass mode Bit[7:4]: Debug mode Bit[3:0]: Frame OFF number

table 7-22 ISP top control registers (sheet 1 of 5)

address	register name	default value	R/W	description
0x5000	ISP CONTROL 00	0x06	RW	Bit[7]: LENC correction enable 0: Disable 1: Enable Bit[6]: Debug mode Bit[5]: RAW GMA enable 0: Disable 1: Enable Bit[4:3]: Debug mode Bit[2]: Black pixel cancellation enable 0: Disable 1: Enable Bit[1]: White pixel cancellation enable 0: Disable 1: Enable Bit[0]: Color interpolation enable 0: Disable 1: Enable

table 7-22 ISP top control registers (sheet 2 of 5)

address	register name	default value	R/W	description
0x5001	ISP CONTROL 01	01	RW	Bit[7]: Special digital effect enable 0: Disable 1: Enable Bit[6]: Debug mode Bit[5]: Scale enable 0: Disable 1: Enable Bit[4:3]: Debug mode Bit[2]: UV average enable 0: Disable 1: Enable Bit[1]: Color matrix enable 0: Disable 1: Enable Bit[0]: Auto white balance enable 0: Disable 1: Enable
0x5002	DEBUG MODE	–	–	Debug Mode
0x5003	ISP CONTROL 03	08	RW	Bit[7:3]: Debug mode Bit[2]: Bin enable 0: Disable 1: Enable Bit[1]: Draw window for AFC enable 0: Disable 1: Enable Bit[0]: Solarize enable 0: Disable 1: Enable
0x5004	DEBUG MODE	–	–	Debug Mode

table 7-22 ISP top control registers (sheet 3 of 5)

address	register name	default value	R/W	description
0x5005	ISP CONTROL 05	0x36	RW	Bit[7]: Debug mode Bit[6]: AWB bias manual enable 0: Disable 1: Enable Bit[5]: AWB bias ON enable 0: Disable 1: Enable Bit[4]: AWB bias plus enable 0: Disable 1: Enable Bit[3]: Debug mode Bit[2]: LENC bias ON enable 0: Disable 1: Enable Bit[1]: GMA bias ON enable 0: Disable 1: Enable Bit[0]: LENC bias manual enable 0: Disable 1: Enable
0x5006~ 0x501C	DEBUG MODE	—	—	Debug Mode
0x501D	ISP MISC	0x00	RW	Bit[7]: Debug mode Bit[6]: SDE AVG manual enable Bit[5]: AWB YUV2CBCR enable Bit[4]: Average size manual enable Bit[3:0]: Debug mode
0x501E	ISP MISC	0x00	RW	Bit[7]: Debug mode Bit[6]: Scale ratio manual enable Bit[5:0]: Debug mode
0x501F	FORMAT MUX CONTROL	0x00	RW	Format MUX Control Bit[7:4]: Debug mode Bit[3]: Fmt vfirst Bit[2:0]: Format select 000: ISP YUV422 001: ISP RGB 010: ISP dither 011: ISP RAW (DPC) 100: SNR RAW 101: ISP RAW (CIP)
0x5020	DITHER CTRL 0	0x00	RW	Bit[7]: Debug mode Bit[6]: Dither MUX Bit[5:4]: R dithering Bit[3:2]: G dithering Bit[1:0]: B dithering

table 7-22 ISP top control registers (sheet 4 of 5)

address	register name	default value	R/W	description
0x5021~0x5026	DEBUG MODE	–	–	Debug Mode
0x5027	DRAW WINDOW CONTROL 00	0x02	RW	Bit[7:1]: Debug mode Bit[0]: Draw window control 0: No fixed Y 1: Fixed Y
0x5028	DRAW WINDOW LEFT POSITION CONTROL	0x04	RW	Bit[7:4]: Debug mode Bit[3:0]: Draw window left[11:8]
0x5029	DRAW WINDOW LEFT POSITION CONTROL	0x90	RW	Bit[7:0]: Draw window left[7:0]
0x502A	DRAW WINDOW RIGHT POSITION CONTROL	0x05	RW	Bit[7:4]: Debug mode Bit[3:0]: Draw window right[11:8]
0x502B	DRAW WINDOW RIGHT POSITION CONTROL	0x90	RW	Bit[7:0]: Draw window right[7:0]
0x502C	DRAW WINDOW TOP POSITION CONTROL	0x03	RW	Bit[7:3]: Debug mode Bit[2:0]: Draw window top[10:8]
0x502D	DRAW WINDOW TOP POSITION CONTROL	0x6C	RW	Bit[7:0]: Draw window top[7:0]
0x502E	DRAW WINDOW BOTTOM POSITION CONTROL	0x04	RW	Bit[7:3]: Debug mode Bit[2:0]: Draw window bottom[10:8]
0x502F	DRAW WINDOW BOTTOM POSITION CONTROL	0x2C	RW	Bit[7:0]: Draw window bottom[7:0]
0x5030	DRAW WINDOW HORIZONTAL BOUNDARY WIDTH CONTROL	0x00	RW	Bit[7:4]: Debug mode Bit[3:0]: Draw window horizontal boundary width[11:8]
0x5031	DRAW WINDOW HORIZONTAL BOUNDARY WIDTH CONTROL	0x14	RW	Bit[7:0]: Draw window horizontal boundary width[7:0]
0x5032	DRAW WINDOW VERTICAL BOUNDARY WIDTH CONTROL	0x00	RW	Bit[7:3]: Debug mode Bit[2:0]: Draw window vertical boundary width[10:8]

table 7-22 ISP top control registers (sheet 5 of 5)

address	register name	default value	R/W	description
0x5033	DRAW WINDOW VERTICAL BOUNDARY WIDTH CONTROL	0x14	RW	Bit[7:0]: Draw window vertical boundary width[7:0]
0x5034	DRAW WINDOW Y CONTROL	0x80	RW	Bit[7:0]: Fixed Y for draw window
0x5035	DRAW WINDOW U CONTROL	0x2A	RW	Bit[7:0]: Fixed U for draw window
0x5036	DRAW WINDOW V CONTROL	0x14	RW	Bit[7:0]: Fixed V for draw window
0x5037~ 0x503C	DEBUG MODE	—	—	Debug Mode
0x503D	PRE ISP TEST SETTING 1	0x00	RW	Bit[7]: Pre ISP test enable 0: Test disable 1: Color bar enable Bit[6]: Rolling Bit[5]: Transparent Bit[4]: Square BW Bit[3:2]: Pre ISP bar style 00: Standard 8 color bar 01: Gradual change at vertical mode 1 10: Gradual change at horizontal 11: Gradual change at vertical mode 2 Bit[1:0]: Test select 00: Color bar 01: Random data 10: Square data 11: Black image
0x503E~ 0x5060	DEBUG MODE	—	—	Debug Mode
0x5061	ISP SENSOR BIAS I	—	R	ISP Sensor Bias I
0x5062	ISP SENSOR GAIN I	—	R	ISP Sensor Gain I
0x5063	ISP SENSOR GAIN I	—	R	ISP Sensor Gain I

table 7-23 AWB registers (sheet 1 of 2)

address	register name	default value	R/W	description
0x5180	AWB CONTROL 00	0xFF	RW	Bit[7:0]: AWB B block
0x5181	AWB CONTROL 01	0x58	RW	Bit[7:6]: Step local Bit[5:4]: Step fast Bit[3]: Slop 8x Bit[2]: Slop 4x Bit[1]: One zone Bit[0]: AVG all
0x5182	AWB CONTROL 02	0x11	RW	Bit[7:4]: Max local counter Bit[3:0]: Max fast counter
0x5183	AWB CONTROL 03	0x90	RW	Bit[7]: AWB simple enable 0: AWB advance 1: AWB simple Bit[6]: AWB advance 0: YUV enable 1: Simple YUV enable Bit[5]: AWB preset Bit[4]: AWB SIMF Bit[3:2]: AWB win Bit[0]: Debug mode
0x5184	AWB CONTROL 04	0x25	RW	Bit[7:6]: Count area selection Bit[5]: G enable Bit[4:2]: Count limit control Bit[1:0]: Counter threshold
0x5185	AWB CONTROL 05	0x24	RW	Bit[7:4]: Stable range unstable Threshold for unstable to stable change Bit[3:0]: Stable range stable Threshold for stable to unstable change
0x5186~ 0x5190	AWB CONTROL	–	–	Advanced AWB Control Registers
0x5191	AWB CONTROL 17	0xFF	RW	Bit[7:0]: AWB top limit
0x5192	AWB CONTROL 18	0x00	RW	Bit[7:0]: AWB bottom limit
0x5193	AWB CONTROL 19	0xF0	RW	Bit[7:0]: Red limit
0x5194	AWB CONTROL 20	0xF0	RW	Bit[7:0]: Green limit
0x5195	AWB CONTROL 21	0xF0	RW	Bit[7:0]: Blue limit

table 7-23 AWB registers (sheet 2 of 2)

address	register name	default value	R/W	description
0x5196	AWB CONTROL 22	0x03	RW	Bit[7:6]: Debug mode Bit[5]: AWB freeze Bit[4]: Debug mode Bit[3:2]: AWB simple selection 00: AWB simple from after AWB gain 01: AWB simple from after RAW GMA 10: AWB simple from after RAW GMA 11: AWB simple from after AWB gain Bit[1]: Fast enable Bit[0]: AWB bias stat
0x5197	AWB CONTROL 23	0x02	RW	Bit[7:0]: Local limit
0x5198~ 0x519D	DEBUG MODE	—	—	Debug Mode
0x519E	AWB CONTROL 30	0x00	RW	Bit[7:4]: Debug mode Bit[3]: Local limit select Bit[2]: Simple stable select Bit[1:0]: Debug mode
0x519F	AWB CURRENT R GAIN	—	R	Bit[7:4]: Debug mode Bit[3:0]: Current R setting[11:8]
0x51A0	AWB CURRENT R GAIN	—	R	Bit[7:0]: Current R setting[7:0]
0x51A1	AWB CURRENT G GAIN	—	R	Bit[7:4]: Debug mode Bit[3:0]: Current G setting[11:8]
0x51A2	AWB CURRENT G GAIN	—	R	Bit[7:0]: Current G setting[7:0]
0x51A3	AWB CURRENT B GAIN	—	R	Bit[7:4]: Debug mode Bit[3:0]: Current B setting[11:8]
0x51A4	AWB CURRENT B GAIN	—	R	Bit[7:0]: Current B setting[7:0]
0x51A5	AWB AVERAGE B	—	R	Bit[7:0]: Average R[9:2]
0x51A6	AWB AVERAGE B	—	R	Bit[7:0]: Average G[9:2]
0x51A7	AWB AVERAGE B	—	R	Bit[7:0]: Average B[9:2]
0x51D0	AWB CONTROL74	—	R	Bit[7:6]: Debug mode Bit[5]: R large Bit[4]: G large Bit[3]: B large Bit[2:1]: Current type Bit[0]: Debug mode

table 7-24 CIP control registers

address	register name	default value	R/W	description
0x5300	CIP SHARPENMT THRESHOLD 1	0x08	RW	Color Interpolation Sharpen MT Threshold 1
0x5301	CIP SHARPENMT THRESHOLD 2	0x48	RW	Color Interpolation Sharpen MT Threshold 2
0x5302	CIP SHARPENMT OFFSET1	0x18	RW	CIP Sharpen MT Offset1 (Y edge.mt manual setting when 0x5308[6]=1)
0x5303	CIP SHARPENMT OFFSET2	0x0E	RW	CIP Sharpen MT Offset2
0x5304	CIP DNS THRESHOLD 1	0x08	RW	CIP DNS Threshold 1
0x5305	CIP DNS THRESHOLD 2	0x48	RW	CIP DNS Threshold 2
0x5306	CIP DNS OFFSET1	0x09	RW	CIP DNS Offset1 (DNS threshold manual setting when 0x5308[4]=1)
0x5307	CIP DNS OFFSET2	0x16	RW	CIP DNS Offset2
0x5308	CIP CTRL	0x25	RW	Bit[7]: Debug mode Bit[6]: CIP edge MT manual enable Bit[4]: CIP DNS manual enable Bit[2:0]: CIP threshold for BR sharpen
0x5309	CIP SHARPENTH THRESHOLD 1	0x08	RW	CIP Sharpen TH Threshold 1
0x530A	CIP SHARPENTH THRESHOLD 2	0x48	RW	CIP Sharpen TH Threshold 2
0x530B	CIP SHARPENTH OFFSET1	0x04	RW	CIP Sharpen TH Offset1 (Sharpen threshold manual setting when 0x5308[6]=1)
0x530C	CIP SHARPENTH OFFSET2	0x06	RW	CIP Sharpen TH Offset2
0x530D	CIP EDGE MT AUTO	–	R	CIP Edge MT Auto Read
0x530E	CIP DNS THRESHOLD AUTO	–	R	CIP DNS Threshold Auto Read
0x530F	CIP SHARPEN THRESHOLD AUTO	–	R	CIP Sharpen Threshold Auto Read

table 7-25 CMX control registers

address	register name	default value	R/W	description
0x5381	CMX1	0x20	RW	Bit[7:2]: Debug mode Bit[1]: Color matrix enable 0: Disable 1: Enable Bit[0]: Debug mode
0x5382	CMX2	0x64	RW	Bit[7:0]: CMX2 for Y
0x5383	CMX3	0x08	RW	Bit[7:0]: CMX3 for Y
0x5384	CMX4	0x30	RW	Bit[7:0]: CMX4 for U
0x5385	CMX5	0x90	RW	Bit[7:0]: CMX5 for U
0x5386	CMX6	0xC0	RW	Bit[7:0]: CMX6 for U
0x5387	CMX7	0xA0	RW	Bit[7:0]: CMX7 for V
0x5388	CMX8	0x98	RW	Bit[7:0]: CMX8 for V
0x5389	CMX9	0x08	RW	Bit[7:0]: CMX9 for V
0x538A	CMXSIGN	0x01	RW	Cmxsign Bit[7:1]: Debug mode Bit[0]: CMX9 sign
0x538B	CMXSIGN	0x98	RW	Cmxsign Bit[7]: CMX8 sign Bit[6]: CMX7 sign Bit[5]: CMX6 sign Bit[4]: CMX5 sign Bit[3]: CMX4 sign Bit[2]: CMX3 sign Bit[1]: CMX2 sign Bit[0]: CMX1 sign

table 7-26 gamma control registers

address	register name	default value	R/W	description
0x5480	GAMMA CONTROL00	0x00	RW	Bit[7:2]: Debug mode Bit[1]: YSLP15 manual enable Bit[0]: BIAS plus on
0x5481	GAMMA YST00	0x26	RW	Bit[7:0]: Y yst 00
0x5482	GAMMA YST01	0x35	RW	Bit[7:0]: Y yst 01
0x5483	GAMMA YST02	0x48	RW	Bit[7:0]: Y yst 02
0x5484	GAMMA YST03	0x57	RW	Bit[7:0]: Y yst 03
0x5485	GAMMA YST04	0x63	RW	Bit[7:0]: Y yst 04
0x5486	GAMMA YST05	0x6E	RW	Bit[7:0]: Y yst 05
0x5487	GAMMA YST06	0x77	RW	Bit[7:0]: Y yst 06
0x5488	GAMMA YST07	0x80	RW	Bit[7:0]: Y yst 07
0x5489	GAMMA YST08	0x88	RW	Bit[7:0]: Y yst 08
0x548A	GAMMA YST09	0x96	RW	Bit[7:0]: Y yst 09
0x548B	GAMMA YST0A	0xA3	RW	Bit[7:0]: Y yst 0A
0x548C	GAMMA YST0B	0xAF	RW	Bit[7:0]: Y yst 0B
0x548D	GAMMA YST0C	0xC5	RW	Bit[7:0]: Y yst 0C
0x548E	GAMMA YST0D	0xD7	RW	Bit[7:0]: Y yst 0D
0x548F	GAMMA YST0E	0xE8	RW	Bit[7:0]: Y yst 0E
0x5490	GAMMA YST0F	0x0F	RW	Bit[7:0]: Y yst 0F

table 7-27 SDE control registers (sheet 1 of 2)

address	register name	default value	R/W	description	
0x5580	SDE CTRL0	0x00	RW	Bit[7]:	Fixed Y enable 0: Disable 1: Enable
				Bit[6]:	Negative enable 0: Disable 1: Enable
				Bit[5]:	Gray enable 0: Disable 1: Enable
				Bit[4]:	Fixed V enable 0: Disable 1: Enable
				Bit[3]:	Fixed U enable 0: Disable 1: Enable
				Bit[2]:	Contrast enable 0: Disable 1: Enable
				Bit[1]:	Saturation enable 0: Disable 1: Enable
				Bit[0]:	Hue enable 0: Disable 1: Enable
0x5581	SDE CTRL1	0x80	RW	Bit[7:0]:	Hue cos coefficient
0x5582	SDE CTRL2	0x00	RW	Bit[7:0]:	Hue sin coefficient
0x5583	SDE CTRL3	0x40	RW	Bit[7:0]:	Saturation U when 0x5580[1]=1 and 0x5588[6]=1, max value for UV adjust when 0x5580[1]=1 and 0x5588[6]=0 or fixed U when 0x5580[3]=1
0x5584	SDE CTRL4	0x40	RW	Bit[7:0]:	Saturation V when 0x5580[1]=1 and 0x5588[6]=1, min value for UV adjust when 0x5580[1]=1 and 0x5588[6]=0 or Vreg when 0x5580[4]=1
0x5585	SDE CTRL5	0x00	RW	Bit[7:0]:	Y offset for contrast when 0x5044[3]=1; or fixed Y when 0x5580[7]=1
0x5586	SDE CTRL6	0x20	RW	Bit[7:0]:	Y gain for contrast
0x5587	SDE CTRL7	0x00	RW	Bit[7:0]:	Y bright for contrast

table 7-27 SDE control registers (sheet 2 of 2)

address	register name	default value	R/W	description
0x5588	SDE CTRL8	0x01	RW	Bit[7]: Debug mode Bit[5]: Sign5 for hue V, cos Bit[4]: Sign4 for hue U, cos Bit[3]: Sign3 Y bright sign for contrast 0: Keep Y bright sign 1: Negative Y bright sign Bit[2]: Sign2 Y offset sign for contrast when 0x5044[3]=1 0: Keep Y offset sign 1: Negative Y offset sign Bit[1]: Sign1 for hue V, sin Bit[0]: Sign0 for hue U, sin
0x5589	SDE CTRL9	0x01	RW	Bit[7:0]: UV adjust threshold 1 Valid when 0x5580[1]=1
0x558A	SDE CTRL10	0x01	RW	Bit[7:1]: Debug mode Bit[0]: UV adjust threshold 2[8] Valid when 0x5580[1]=1
0x558B	SDE CTRL11	0xFF	RW	Bit[7:0]: UV adjust threshold 2[7:0] Valid when 0x5580[1]=1
0x558C	SDE CTRL12	—	R	Bit[7:0]: UV adjust value read out

table 7-28 SCALE registers

address	register name	default value	R/W	description
0x5600	SCALE CTRL 0	0x10	RW	Bit[7:6]: Debug mode Bit[5]: UV drop YUV444 to 422 drop mode versus AVG mode selection 0: AVG mode 1: Drop mode Bit[4]: Debug mode Bit[3]: Hround DCW hrounding 0: No horizontal rounding 1: Horizontal rounding Bit[2]: Hdrop DCW drop mode 0: Horizontal average mode 1: Horizontal drop mode Bit[1]: Vround DCW vrounding 0: No vertical rounding 1: Vertical rounding Bit[0]: Vdrop DCW drop mode 0: Vertical average mode 1: Vertical drop mode
0x5601	SCALE CTRL 1	0x00	RW	Bit[7]: Debug mode Bit[6:4]: HDIV RW DCW scale times 000: DCW 1 time 001: DCW 2 time 010: DCW 4 time 011: DCW 8 time 1xx: DCW 16 time Bit[2:0]: VDIV RW DCW scale times 000: DCW 1 time 001: DCW 2 time 010: DCW 4 time 011: DCW 8 time 1xx: DCW 16 time
0x5602	SCALE CTRL 2	0x02	RW	Bit[7:0]: XSC[15:8]
0x5603	SCALE CTRL 3	0x00	RW	Bit[7:0]: XSC[7:0]
0x5604	SCALE CTRL 4	0x02	RW	Bit[7:0]: YSC[15:8]
0x5605	SCALE CTRL 5	0x00	RW	Bit[7:0]: YSC[7:0]
0x5606	SCALE CTRL 6	0x00	RW	Bit[7:4]: Debug mode Bit[3:0]: Voffset

table 7-29 AVG registers (sheet 1 of 2)

address	register name	default value	R/W	description
0x5680	X START	0x00	RW	Bit[7:4]: Debug mode Bit[3:0]: x start[11:8] Horizontal start position for average window high byte, valid when 0x501D[4]=1
0x5681	X START	0x00	RW	Bit[7:0]: x start[7:0] Horizontal start position for average window low byte, valid when 0x501D[4]=1
0x5682	Y START	0x00	RW	Bit[7:3]: Debug mode Bit[2:0]: y start[10:8] Vertical start position for average window low byte, valid when 0x501D[4]=1
0x5683	Y START	0x00	RW	Bit[7:0]: y start[7:0] Vertical start position for average window low byte, valid when 0x501D[4]=1
0x5684	X WINDOW	0x10	RW	Bit[7:4]: Debug mode Bit[3:0]: Window X[11:8] Horizontal end position for average window high byte, valid when 0x501D[4]=1
0x5685	X WINDOW	0xA0	RW	Bit[7:0]: Window X[7:0] Horizontal end position for average window low byte, valid when 0x501D[4]=1
0x5686	Y WINDOW	0x0C	RW	Bit[7:3]: Debug mode Bit[2:0]: Window Y[10:8] Vertical end position for average window high byte, valid when 0x501D[4]=1
0x5687	Y WINDOW	0x78	RW	Bit[7:0]: Window Y[7:0] Vertical end position for average window low byte, valid when 0x501D[4]=1
0x5688	WEIGHT00	0x11	RW	Bit[7:4]: Window 01 weight Bit[3:0]: Window 00 weight
0x5689	WEIGHT01	0x11	RW	Bit[7:4]: Window 03 weight Bit[3:0]: Window 02 weight
0x568A	WEIGHT02	0x11	RW	Bit[7:4]: Window 11 weight Bit[3:0]: Window 10 weight
0x568B	WEIGHT03	0x11	RW	Bit[7:4]: Window 13 weight Bit[3:0]: Window 12 weight
0x568C	WEIGHT04	0x11	RW	Bit[7:4]: Window 21 weight Bit[3:0]: Window 20 weight
0x568D	WEIGHT05	0x11	RW	Bit[7:4]: Window 23 weight Bit[3:0]: Window 22 weight

table 7-29 AVG registers (sheet 2 of 2)

address	register name	default value	R/W	description
0x568E	WEIGHT06	0x11	RW	Bit[7:4]: Window 31 weight Bit[3:0]: Window 30 weight
0x568F	WEIGHT07	0x11	RW	Bit[7:4]: Window 33 weight Bit[3:0]: Window 32 weight
0x5690	AVG CTRL10	0x01	RW	Bit[7:1]: Debug mode Bit[0]: AVG option 0: $\text{Sum}=(4*B+9*G*2+10*R)/8$ 1: $\text{Sum}=(B+G*2+R)$
0x5691	AVG WIN 00	–	R	Bit[7:0]: Average of win 00
0x5692	AVG WIN 01	–	R	Bit[7:0]: Average of win 01
0x5693	AVG WIN 02	–	R	Bit[7:0]: Average of win 02
0x5694	AVG WIN 03	–	R	Bit[7:0]: Average of win 03
0x5695	AVG WIN 10	–	R	Bit[7:0]: Average of win 10
0x5696	AVG WIN 11	–	R	Bit[7:0]: Average of win 11
0x5697	AVG WIN 12	–	R	Bit[7:0]: Average of win 12
0x5698	AVG WIN 13	–	R	Bit[7:0]: Average of win 13
0x5699	AVG WIN 20	–	R	Bit[7:0]: Average of win 20
0x569A	AVG WIN 21	–	R	Bit[7:0]: Average of win 21
0x569B	AVG WIN 22	–	R	Bit[7:0]: Average of win 22
0x569C	AVG WIN 23	–	R	Bit[7:0]: Average of win 23
0x569D	AVG WIN 30	–	R	Bit[7:0]: Average of win 30
0x569E	AVG WIN 31	–	R	Bit[7:0]: Average of win 31
0x569F	AVG WIN 32	–	R	Bit[7:0]: Average of win 32
0x56A0	AVG WIN 33	–	R	Bit[7:0]: Average of win 33
0x56A1	AVG READOUT	–	R	Bit[7:0]: High 8 bits of average value
0x56A2	AVG WEIGHT SUM	–	R	Bit[7:0]: Average weight sum

table 7-30 LENC control registers (sheet 1 of 5)

address	register name	default value	R/W	description
0x5800	GMTRX00	0x10	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 00
0x5801	GMTRX01	0x10	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 01
0x5802	GMTRX02	0x10	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 02
0x5803	GMTRX03	0x10	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 03
0x5804	GMTRX04	0x10	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 04
0x5805	GMTRX05	0x10	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 05
0x5806	GMTRX10	0x10	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 06
0x5807	GMTRX11	0x08	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 07
0x5808	GMTRX12	0x08	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 08
0x5809	GMTRX13	0x08	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 09
0x580A	GMTRX14	0x08	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 0A
0x580B	GMTRX15	0x10	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 0B
0x580C	GMTRX20	0x10	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 0C
0x580D	GMTRX21	0x08	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 0D
0x580E	GMTRX22	0x00	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 0E
0x580F	GMTRX23	0x00	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 0F
0x5810	GMTRX24	0x08	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 10
0x5811	GMTRX25	0x10	RW	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 11

table 7-30 LENC control registers (sheet 2 of 5)

address	register name	default value	R/W	description
0x5812	GMTRX30	0x10	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 12
0x5813	GMTRX31	0x08	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 13
0x5814	GMTRX32	0x00	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 14
0x5815	GMTRX33	0x00	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 15
0x5816	GMTRX34	0x08	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 16
0x5817	GMTRX35	0x10	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 17
0x5818	GMTRX40	0x10	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 18
0x5819	GMTRX41	0x08	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 19
0x581A	GMTRX42	0x08	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 1A
0x581B	GMTRX43	0x08	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 1B
0x581C	GMTRX44	0x08	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 1C
0x581E	GMTRX45	0x10	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 1D
0x581E	GMTRX50	0x10	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 1E
0x581F	GMTRX51	0x10	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 1F
0x5820	GMTRX52	0x10	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 20
0x5821	GMTRX53	0x10	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 21
0x5822	GMTRX54	0x10	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 22
0x5823	GMTRX55	0x10	R/W	Bit[7:6]: Debug mode Bit[5:0]: Green matrix 23
0x5824	BRMATRX00	0xAA	R/W	Bit[7:4]: Blue matrix 00 Bit[3:0]: Red matrix 00

table 7-30 LENC control registers (sheet 3 of 5)

address	register name	default value	R/W	description
0x5825	BRMATRX01	0xAA	RW	Bit[7:4]: Blue matrix 01 Bit[3:0]: Red matrix 01
0x5826	BRMATRX02	0xAA	RW	Bit[7:4]: Blue matrix 02 Bit[3:0]: Red matrix 02
0x5827	BRMATRX03	0xAA	RW	Bit[7:4]: Blue matrix 03 Bit[3:0]: Red matrix 03
0x5828	BRMATRX04	0xAA	RW	Bit[7:4]: Blue matrix 04 Bit[3:0]: Red matrix 04
0x5829	BRMATRX05	0xAA	RW	Bit[7:4]: Blue matrix 05 Bit[3:0]: Red matrix 05
0x582A	BRMATRX06	0x99	RW	Bit[7:4]: Blue matrix 06 Bit[3:0]: Red matrix 06
0x582B	BRMATRX07	0x99	RW	Bit[7:4]: Blue matrix 07 Bit[3:0]: Red matrix 07
0x582C	BRMATRX08	0x99	RW	Bit[7:4]: Blue matrix 08 Bit[3:0]: Red matrix 08
0x582D	BRMATRX09	0xAA	RW	Bit[7:4]: Blue matrix 09 Bit[3:0]: Red matrix 09
0x582E	BRMATRX20	0xAA	RW	Bit[7:4]: Blue matrix 20 Bit[3:0]: Red matrix 20
0x582F	BRMATRX21	0x99	RW	Bit[7:4]: Blue matrix 21 Bit[3:0]: Red matrix 21
0x5830	BRMATRX22	0x88	RW	Bit[7:4]: Blue matrix 22 Bit[3:0]: Red matrix 22
0x5831	BRMATRX23	0x99	RW	Bit[7:4]: Blue matrix 23 Bit[3:0]: Red matrix 23
0x5832	BRMATRX24	0xAA	RW	Bit[7:4]: Blue matrix 24 Bit[3:0]: Red matrix 24
0x5833	BRMATRX30	0xAA	RW	Bit[7:4]: Blue matrix 30 Bit[3:0]: Red matrix 30
0x5834	BRMATRX31	0x99	RW	Bit[7:4]: Blue matrix 31 Bit[3:0]: Red matrix 31
0x5835	BRMATRX32	0x99	RW	Bit[7:4]: Blue matrix 32 Bit[3:0]: Red matrix 32
0x5836	BRMATRX33	0x99	RW	Bit[7:4]: Blue matrix 33 Bit[3:0]: Red matrix 33
0x5837	BRMATRX34	0xAA	RW	Bit[7:4]: Blue matrix 34 Bit[3:0]: Red matrix 34

table 7-30 LENC control registers (sheet 4 of 5)

address	register name	default value	R/W	description
0x5838	BRMATRX40	0xAA	R/W	Bit[7:4]: Blue matrix 40 Bit[3:0]: Red matrix 40
0x5839	BRMATRX41	0xAA	R/W	Bit[7:4]: Blue matrix 41 Bit[3:0]: Red matrix 41
0x583A	BRMATRX42	0xAA	R/W	Bit[7:4]: Blue matrix 42 Bit[3:0]: Red matrix 42
0x583B	BRMATRX43	0xAA	R/W	Bit[7:4]: Blue matrix 43 Bit[3:0]: Red matrix 43
0x583C	BRMATRX44	0xAA	R/W	Bit[7:4]: Blue matrix 44 Bit[3:0]: Red matrix 44
0x583D	LENC BR OFFSET	0x88	R/W	Bit[7:4]: LENC b offset Bit[3:0]: LENC r offset
0x583E	MAX GAIN	0x40	R/W	Bit[7:0]: Maximum gain
0x583F	MIN GAIN	0x20	R/W	Bit[7:0]: Minimum gain
0x5840	MIN Q	0x18	R/W	Bit[7]: Debug mode Bit[6:0]: Minimum Q
0x5841	LENC CTRL59	0x0D	R/W	Bit[7:4]: Debug mode Bit[3]: Add BLC enable 0: Disable BLC add back function 1: Enable BLC add back function Bit[2]: BLC enable 0: Disable BLC function 1: Enable BLC function Bit[1]: Gain manual enable Bit[0]: Auto Q enable 0: Used constant Q (0x40) 1: Used calculated Q
0x5842	BR HSCALE	0x01	RW	Bit[7:3]: Debug mode Bit[2:0]: br h scale[10:8] Reciprocal of horizontal step for BR channel. BR channel in whole image is divided into 5x5 blocks. The step is used to point to the border of the adjacent block
0x5843	BR HSCAL	0x2B	RW	Bit[7:0]: br h scale[7:0] Reciprocal of horizontal step for BR channel. BR channel in whole image is divided into 5x5 blocks. The step is used to point to the border of the adjacent block

table 7-30 LENC control registers (sheet 5 of 5)

address	register name	default value	R/W	description
0x5844	BR VSCALE	0x01	RW	Bit[7:3]: Debug mode Bit[2:0]: br v scale[10:8] Reciprocal of vertical step for BR channel. BR channel in whole image is divided into 5x5 blocks. The step is used to point to the border of the adjacent block
0x5845	BR VSCALE	0x8D	RW	Bit[7:0]: br v scale[7:0] Reciprocal of vertical step for BR channel. BR channel in whole image is divided into 5x5 blocks. The step is used to point to the border of the adjacent block
0x5846	G HSCALE	0x01	RW	Bit[7:3]: Debug mode Bit[2:0]: g h scale[10:8] Reciprocal of horizontal step for G channel. G channel in whole image is divided into 6x6 blocks. The step is used to point to the border of the adjacent block
0x5847	G HSCALE	0x8F	RW	Bit[7:0]: g h scale[7:0] Reciprocal of horizontal step for G channel. G channel in whole image is divided into 6x6 blocks. The step is used to point to the border of the adjacent block
0x5848	G VSCALE	0x01	RW	Bit[7:3]: Debug mode Bit[2:0]: g v scale[10:8] Reciprocal of vertical step for G channel. G channel in whole image is divided into 6x6 blocks. The step is used to point to the border of the adjacent block
0x5849	G VSCALE	0x09	RW	Bit[7:0]: g v scale[7:0] Reciprocal of vertical step for G channel. G channel in whole image is divided into 6x6 blocks. The step is used to point to the border of the adjacent block

table 7-31 AFC control registers (sheet 1 of 5)

address	register name	default value	R/W	description
0x6000	AFC CTRL00	0xFF	RW	AFC Control 00 Bit[7:5]: Debug mode Bit[4]: Edge filter enable 0: afc_edge module will not update 1: afc_edge module will update Bit[3]: Edge filter b select Edge b filters select 0: Edge selects b2 1: Edge selects b1 Bit[2:0]: Edge filter a select Edge a filters select 001: Edge selects a1 010: Edge selects a2 100: Edge selects a4 101: Edge selects a5
0x6001	AFC CTRL01	0xFF	RW	AFC Control 01 Bit[7:0]: Edge window0 left This window coordinate Others: Edge selects a1
0x6002	AFC CTRL02	0xFF	RW	AFC Control 02 Bit[7:0]: Edge window0 top This window coordinate
0x6003	AFC CTRL03	0xFF	RW	AFC Control 03 Bit[7:0]: Edge window0 right This window coordinate
0x6004	AFC CTRL04	0xFF	RW	AFC Control 04 Bit[7:0]: Edge window0 bottom This window coordinate This bottom must be larger than any other
0x6005	AFC CTRL05	0xFF	RW	AFC Control 05 Bit[7:0]: Edge window1 left This window coordinate
0x6006	AFC CTRL06	0xFF	RW	AFC Control 06 Bit[7:0]: Edge window1 top This window coordinate
0x6007	AFC CTRL07	0xFF	RW	AFC Control 07 Bit[7:0]: Edge window1 right This window coordinate
0x6008	AFC CTRL08	0xFF	RW	AFC Control 08 Bit[7:0]: Edge window1 bottom This window coordinate

table 7-31 AFC control registers (sheet 2 of 5)

address	register name	default value	R/W	description
0x6009	AFC CTRL09	0xFF	RW	AFC Control 09 Bit[7:0]: Edge window2 left This window coordinate
0x600A	AFC CTRL10	0xFF	RW	AFC Control 10 Bit[7:0]: Edge window2 top This window coordinate
0x600B	AFC CTRL11	0xFF	RW	AFC Control 11 Bit[7:0]: Edge window2 right This window coordinate
0x600C	AFC CTRL12	0xFF	RW	AFC Control 12 Bit[7:0]: Edge window2 bottom This window coordinate
0x600D	AFC CTRL13	0xFF	RW	AFC Control 13 Bit[7:0]: Edge window3 left This window coordinate
0x600E	AFC CTRL14	0xFF	RW	AFC Control 14 Bit[7:0]: edge window3 top This window coordinate
0x600F	AFC CTRL15	0xFF	RW	AFC Control 15 Bit[7:0]: Edge window3 right This window coordinate
0x6010	AFC CTRL16	0xFF	RW	AFC Control 16 Bit[7:0]: Edge window3 bottom This window coordinate
0x6011	AFC CTRL17	0xFF	RW	AFC Control 17 Bit[7:0]: Edge window4 left This window coordinate
0x6012	AFC CTRL18	0xFF	RW	AFC Control 18 Bit[7:0]: Edge window4 top This window coordinate
0x6013	AFC CTRL19	0xFF	RW	AFC Control 19 Bit[7:0]: Edge window4 right This window coordinate
0x6014	AFC CTRL20	0xFF	RW	AFC Control 20 Bit[7:0]: Edge window4 bottom This window coordinate
0x6015	AFC CTRL21	–	R	AFC Control 21 Bit[7:6]: Debug mode Bit[5:0]: Window0 filter a[29:24]
0x6016	AFC CTRL22	–	R	AFC Control 22 Bit[7:0]: Window0 filter a[23:16]

table 7-31 AFC control registers (sheet 3 of 5)

address	register name	default value	R/W	description
0x6017	AFC CTRL23	–	R	AFC Control 23 Bit[7:0]: Window0 filter a[15:8]
0x6018	AFC CTRL24	–	R	AFC Control 24 Bit[7:0]: Window0 filter a[7:0]
0x6019	AFC CTRL25	–	R	AFC Control 25 Bit[7:6]: Debug mode Bit[5:0]: Window0 filter b[29:24]
0x601A	AFC CTRL26	–	R	AFC Control 26 Bit[7:0]: Window0 filter b[23:16]
0x601B	AFC CTRL27	–	R	AFC Control 27 Bit[7:0]: Window0 filter b[15:8]
0x601C	AFC CTRL28	–	R	AFC Control 28 Bit[7:0]: Window0 filter b[7:0]
0x601D	AFC CTRL29	–	R	AFC Control 29 Bit[7:6]: Debug mode Bit[5:0]: Window1 filter a[29:24]
0x601E	AFC CTRL30	–	R	AFC Control 30 Bit[7:0]: Window1 filter a[23:16]
0x601F	AFC CTRL31	–	R	AFC Control 31 Bit[7:0]: Window1 filter a[15:8]
0x6020	AFC CTRL32	–	R	AFC Control 32 Bit[7:0]: Window1 filter a[7:0]
0x6021	AFC CTRL33	–	R	AFC Control 33 Bit[7:6]: Debug mode Bit[5:0]: Window1 filter b[29:24]
0x6022	AFC CTRL34	–	R	AFC Control 34 Bit[7:0]: Window1 filter b[23:16]
0x6023	AFC CTRL35	–	R	AFC Control 35 Bit[7:0]: Window1 filter b[15:8]
0x6024	AFC CTRL36	–	R	AFC Control 36 Bit[7:0]: Window1 filter b[7:0]
0x6025	AFC CTRL37	–	R	AFC Control 37 Bit[7:6]: Debug mode Bit[5:0]: Window2 filter a[29:24]
0x6026	AFC CTRL38	–	R	AFC Control 38 Bit[7:0]: Window2 filter a[23:16]
0x6027	AFC CTRL39	–	R	AFC Control 39 Bit[7:0]: Window2 filter a[15:8]

table 7-31 AFC control registers (sheet 4 of 5)

address	register name	default value	R/W	description
0x6028	AFC CTRL40	–	R	AFC Control 40 Bit[7:0]: Window2 filter a[7:0]
0x6029	AFC CTRL41	–	R	AFC Control 41 Bit[7:6]: Debug mode Bit[5:0]: Window2 filter b[29:24]
0x602A	AFC CTRL42	–	R	AFC Control 42 Bit[7:0]: Window2 filter b[23:16]
0x602B	AFC CTRL43	–	R	AFC Control 43 Bit[7:0]: Window2 filter b[15:8]
0x602C	AFC CTRL44	–	R	AFC Control 44 Bit[7:0]: Window2 filter b[7:0]
0x602D	AFC CTRL45	–	R	AFC Control 45 Bit[7:6]: Debug mode Bit[5:0]: Window3 filter a[29:24]
0x602E	AFC CTRL46	–	R	AFC Control 46 Bit[7:0]: Window3 filter a[23:16]
0x602F	AFC CTRL47	–	R	AFC Control 47 Bit[7:0]: Window3 filter a[15:8]
0x6030	AFC CTRL48	–	R	AFC Control 48 Bit[7:0]: Window3 filter a[7:0]
0x6031	AFC CTRL49	–	R	AFC Control 49 Bit[7:6]: Debug mode Bit[5:0]: Window3 filter b[29:24]
0x6032	AFC CTRL50	–	R	AFC Control 50 Bit[7:0]: Window3 filter b[23:16]
0x6033	AFC CTRL51	–	R	AFC Control 51 Bit[7:0]: Window3 filter b[15:8]
0x6034	AFC CTRL52	–	R	AFC Control 52 Bit[7:0]: Window3 filter b[7:0]
0x6035	AFC CTRL53	–	R	AFC Control 53 Bit[7:6]: Debug mode Bit[5:0]: Window4 filter a[29:24]
0x6036	AFC CTRL54	–	R	AFC Control 54 Bit[7:0]: Window4 filter a[23:16]
0x6037	AFC CTRL55	–	R	AFC Control 55 Bit[7:0]: Window4 filter a[15:8]
0x6038	AFC CTRL56	–	R	AFC Control 56 Bit[7:0]: Window4 filter a[7:0]

table 7-31 AFC control registers (sheet 5 of 5)

address	register name	default value	R/W	description
0x6039	AFC CTRL57	–	R	AFC Control 57 Bit[7:6]: Debug mode Bit[5:0]: Window4 filter b[29:24]
0x603A	AFC CTRL58	–	R	AFC Control 58 Bit[7:0]: Window4 filter b[23:16]
0x603B	AFC CTRL59	–	R	AFC Control 59 Bit[7:0]: Window4 filter b[15:8]
0x603C	AFC CTRL60	–	R	AFC Control 60 Bit[7:0]: Window4 filter b[7:0]
0x603D	AFC READ58	–	R	AFC READ 58 Bit[7:0]: Window4 filter b[23:16]
0x603R	AFC READ59	–	R	AFC READ 59 Bit[7:0]: Window4 filter b[15:8]
0x603F	AFC READ60	–	R	AFC READ 60 Bit[7:0]: Window4 filter b[7:0]

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8 operating specifications

8.1 absolute maximum ratings

table 8-1 absolute maximum ratings

parameter		absolute maximum rating ^a
ambient storage temperature		-40°C to +95°C
supply voltage (with respect to ground) ^b	V _{DD-A}	4.5V
	V _{DD-D}	3V
	V _{DD-IO}	4.5V
electro-static discharge (ESD)	human body model	2000V
	machine model	200V
all input/output voltages (with respect to ground)		-0.3V to V _{DD-IO} + 1V
I/O current on any input or output pin		±200 mA
peak solder temperature (10 second dwell time)		245°C

a. exceeding the absolute maximum ratings shown above invalidates all AC and DC electrical specifications and may result in permanent damage to the device. Exposure to absolute maximum rated conditions for extended periods may affect device reliability.

b. for negative voltage with respect to ground, V_{DD-A} (-4.5V), V_{DD-C} (-3V), V_{DD-IO} (-4.5V)

8.2 functional temperature

table 8-2 functional temperature

parameter	range
operating temperature range ^a	-20°C to +70°C
stable image temperature range ^b	0°C to +50°C

a. sensor functions but image quality may be noticeably different at temperatures outside of stable image range

b. image quality remains stable throughout this temperature range

8.3 DC characteristics

table 8-3 DC characteristics ($-20^{\circ}\text{C} < T_A < 70^{\circ}\text{C}$) (sheet 1 of 2)

symbol	parameter	min	typ	max	unit
power supply					
V _{DD-A}	supply voltage (analog)	2.6	2.8	3.0	V
V _{DD-D} ^a	supply voltage (digital core)	1.425	1.5	1.575	V
V _{DD-IO}	supply voltage (digital I/O)	1.71	1.8	3.0	V
internal DVDD, DOVDD=1.8V					
I _{DD-A}	active (operating) current	TBD	TBD	TBD	mA
I _{DD-IO} ^{b, c}		TBD	TBD	TBD	mA
I _{DDS-SCCB} ^d	standby current	TBD	TBD	TBD	μA
I _{DDS-PWDN} ^d		TBD	TBD	TBD	μA
P _O	active (operating) power consumption	TBD	TBD	TBD	mW
P _{DDS-SCCB}	standby power consumption	TBD	TBD	TBD	μW
P _{DDS-PWDN}		TBD	TBD	TBD	μW
external DVDD, DOVDD=2.8V					
I _{DD-A}	active (operating) current	TBD	TBD	TBD	mA
I _{DD-D} ^{b, c}		TBD	TBD	TBD	mA
I _{DD-IO}	standby current	TBD	TBD	TBD	mA
I _{DDS-SCCB}		TBD	TBD	TBD	μA
I _{DDS-PWDN}	standby current	TBD	TBD	TBD	μA
P _O		TBD	TBD	TBD	mW
P _{DDS-SCCB}	standby power consumption	TBD	TBD	TBD	μW
P _{DDS-PWDN}		TBD	TBD	TBD	μW
external DVDD, DOVDD=1.8V					
I _{DD-A}	active (operating) current	TBD	TBD	TBD	mA
I _{DD-D} ^{b, c}		TBD	TBD	TBD	mA
I _{DD-IO}	standby current	TBD	TBD	TBD	mA
I _{DDS-SCCB}		TBD	TBD	TBD	μA
I _{DDS-PWDN}	standby current	TBD	TBD	TBD	μA
P _O		TBD	TBD	TBD	mW
P _{DDS-SCCB}	standby power consumption	TBD	TBD	TBD	μW
P _{DDS-PWDN}		TBD	TBD	TBD	μW

table 8-3 DC characteristics ($-20^{\circ}\text{C} < T_A < 70^{\circ}\text{C}$) (sheet 2 of 2)

symbol	parameter	min	typ	max	unit
digital inputs (typical conditions: AVDD = 2.8V, DVDD = 1.5V, DOVDD = 1.8V)					
V_{IL}	input voltage LOW			0.54	V
V_{IH}	input voltage HIGH	1.26			V
C_{IN}	input capacitor			10	pF
digital outputs (standard loading 25 pF)					
V_{OH}	output voltage HIGH	1.62			V
V_{OL}	output voltage LOW			0.18	V
serial interface inputs ^e					
V_{IL}	SIOC and SIOD	-0.5	0	0.54	V
V_{IH}	SIOC and SIOD	1.26	1.8	3.0	V

- a. using the internal DVDD regulator is strongly recommended for minimum power down current
- b. active current is based on sensor resolution at full size and at full speed in compression format. For smaller sizes such as 720p or below preview, the total active current will be about half.
- c. DOVDD active current is based on loading of 10pF and typical compression format output PCLK (48MHz). For YUV output with higher PCLK, or higher loading, DOVDD current can go up.
- d. at room temperature and typical supply voltages
- e. based on DOVDD = 1.8V.

8.4 AC characteristics

table 8-4 AC characteristics ($T_A = 25^\circ\text{C}$, $V_{DD-A} = 2.8\text{V}$)

symbol	parameter	min	typ	max	unit
ADC parameters					
B	analog bandwidth		30		MHz
DLE	DC differential linearity error		0.5		LSB
ILE	DC integral linearity error		1		LSB
	settling time for hardware reset			<1	ms
	settling time for software reset			<1	ms
	settling time for resolution mode change			<1	ms
	settling time for register setting			<300	ms

table 8-5 timing characteristics

symbol	parameter	min	typ	max	unit
oscillator and clock input					
f_{OSC}	frequency (XVCLK) ^a	6	24	54	MHz
t_r, t_f	clock input rise/fall time ^b			5 (10 ^c)	ns
f_{PCLK}	parallel port output pixel clock		48 ^d	96 ^e	MHz

a. for input clock range 6~27MHz, the OV5640 can tolerate input clock jitter up to 1ns, for input clock range to 54MHz, the OV5640 can tolerate input clock jitter up to 500ps

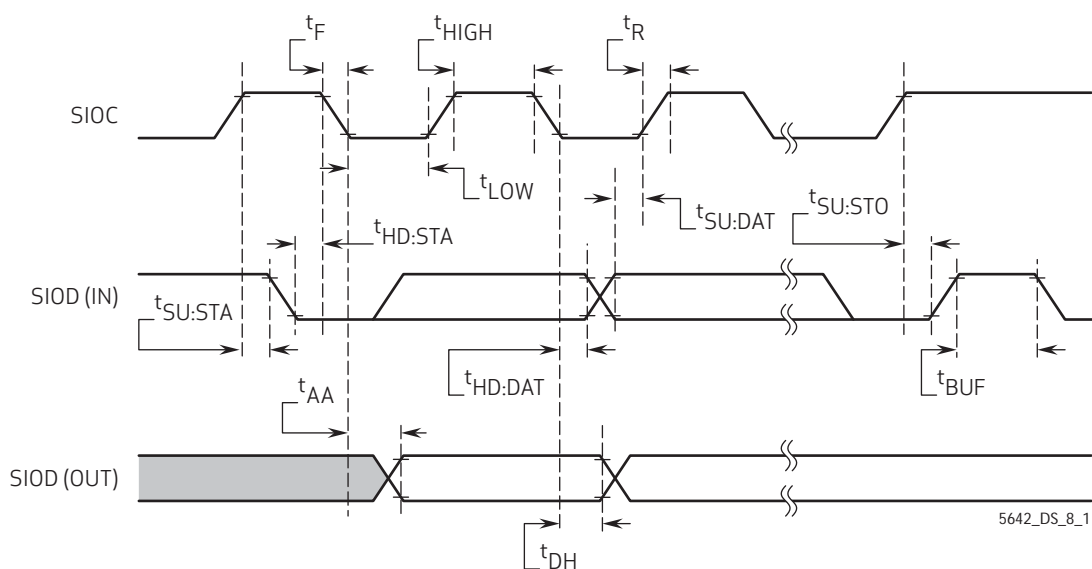
b. if the PLL is bypassed, the delay from input clock to output clock is approximately 4~5ns

c. if using the internal PLL

d. typical PCLK is 48 MHz when sensor output is smaller size (VGA YUV or below) or full size compression

e. 96 MHz is for sensor RAW data output at 15fps or YUV output at 7.5fps. For higher speeds such as 5 megapixel YUV @ 15fps, OmniVision recommends using the MIPI two-lane interface.

figure 8-1 SCCB interface timing

table 8-6 SCCB interface timing specifications^a

symbol	parameter	min	typ	max	unit
f_{SIOC}	clock frequency			400 ^b	KHz
t_{LOW}	clock low period	1.3			μs
t_{HIGH}	clock high period	0.6			μs
t_{AA}	SIOC low to data out valid	0.1		0.9	μs
t_{BUF}	bus free time before new start	1.3			μs
$t_{HD:STA}$	start condition hold time	0.6			μs
$t_{SU:STA}$	start condition setup time	1.85			μs
$t_{HD:DAT}$	data in hold time	0			μs
$t_{SU:DAT}$	data in setup time	0.1			μs
$t_{SU:STO}$	stop condition setup time	0.6			μs
t_R, t_F	SCCB rise/fall times			0.3	μs
t_{DH}	data out hold time	0.05			μs

a. SCCB timing is based on 400KHz mode

b. SCCB maximum speed is 400KHz when sensor master input clock (XVCLK) is greater than or equal to 13MHz. When XVCLK is less than 13MHz, the maximum SCCB speed is less than 400KHz (approximately XVCLK/32.5)

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9 mechanical specifications

9.1 physical specifications

figure 9-1 package specifications

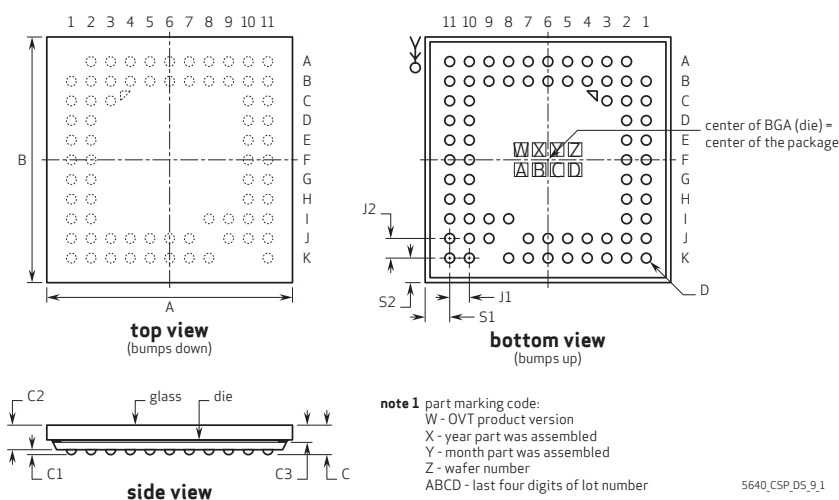


table 9-1 package dimensions

parameter	symbol	min	typ	max	unit
package body dimension x	A	5960	5985	6010	μm
package body dimension y	B	5810	5835	5860	μm
package height	C	690	750	810	μm
ball height	C1	100	130	160	μm
package body thickness	C2	575	620	665	μm
cover glass thickness	C3	425	445	465	μm
ball diameter	D	220	250	280	μm
total pin count	N		71 (13 NC)		
pin count x-axis	N1		11		
pin count y-axis	N2		11		
pins pitch x-axis	J1		500		μm
pins pitch y-axis	J2		500		μm
edge-to-pin center distance analog x	S1	463	493	523	μm
edge-to-pin center distance analog y	S2	388	418	448	μm

9.2 IR reflow specifications

figure 9-2 IR reflow ramp rate requirements

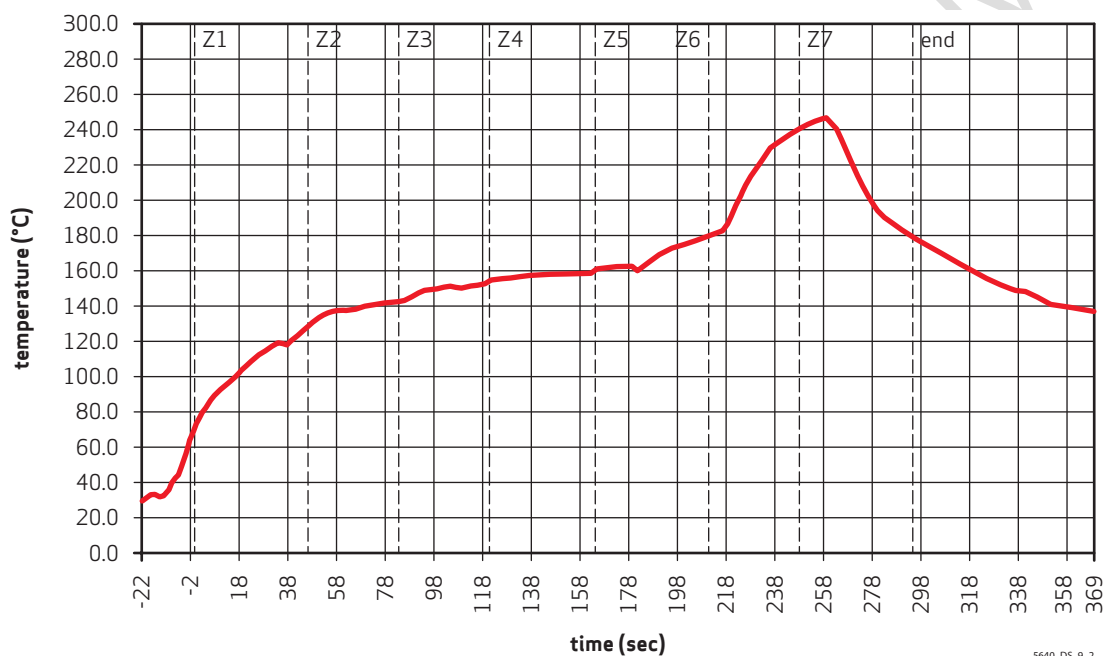


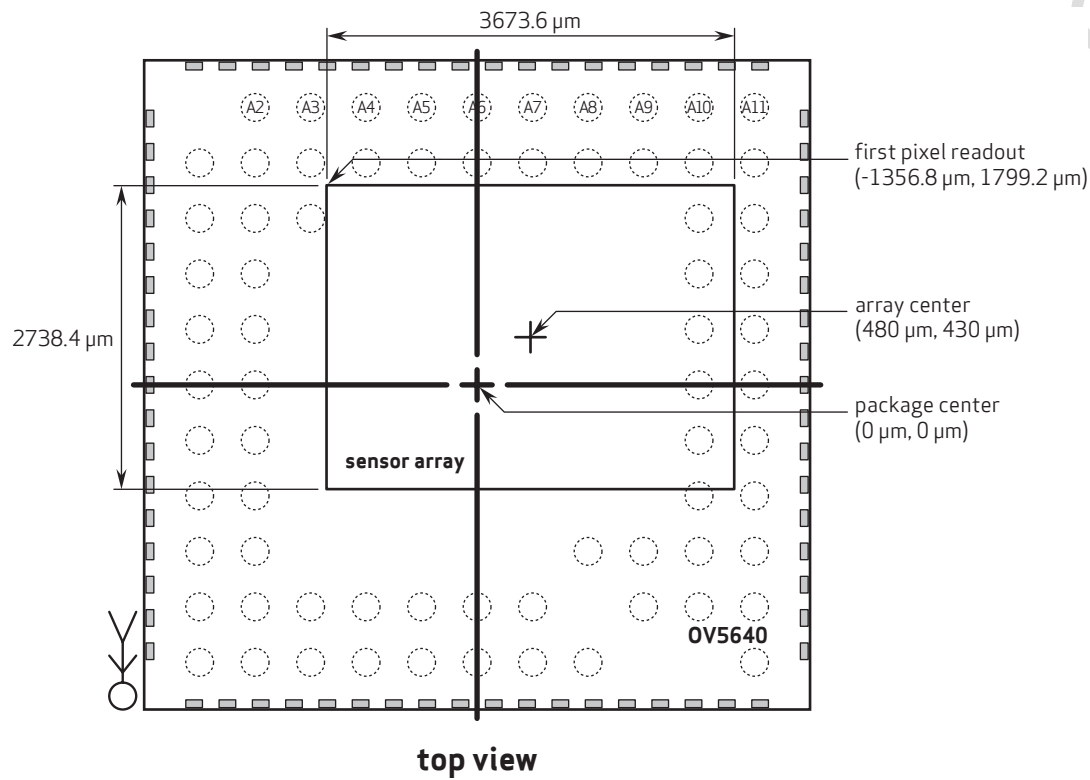
table 9-2 reflow conditions

condition	exposure
average ramp-up rate (30°C to 217°C)	less than 3°C per second
> 100°C	between 330 - 600 seconds
> 150°C	at least 210 seconds
> 217°C	at least 30 seconds (30 ~ 120 seconds)
peak temperature	245°C
cool-down rate (peak to 50°C)	less than 6°C per second
time from 30°C to 245°C	no greater than 390 seconds

10 optical specifications

10.1 sensor array center

figure 10-1 sensor array center



note 1 this drawing is not to scale and is for reference only.

note 2 as most optical assemblies invert and mirror the image, the chip is typically mounted with pins A2 to A11 oriented down on the PCB.

5640_CSP_DS_10_1

10.2 lens chief ray angle (CRA)

figure 10-2 chief ray angle (CRA)

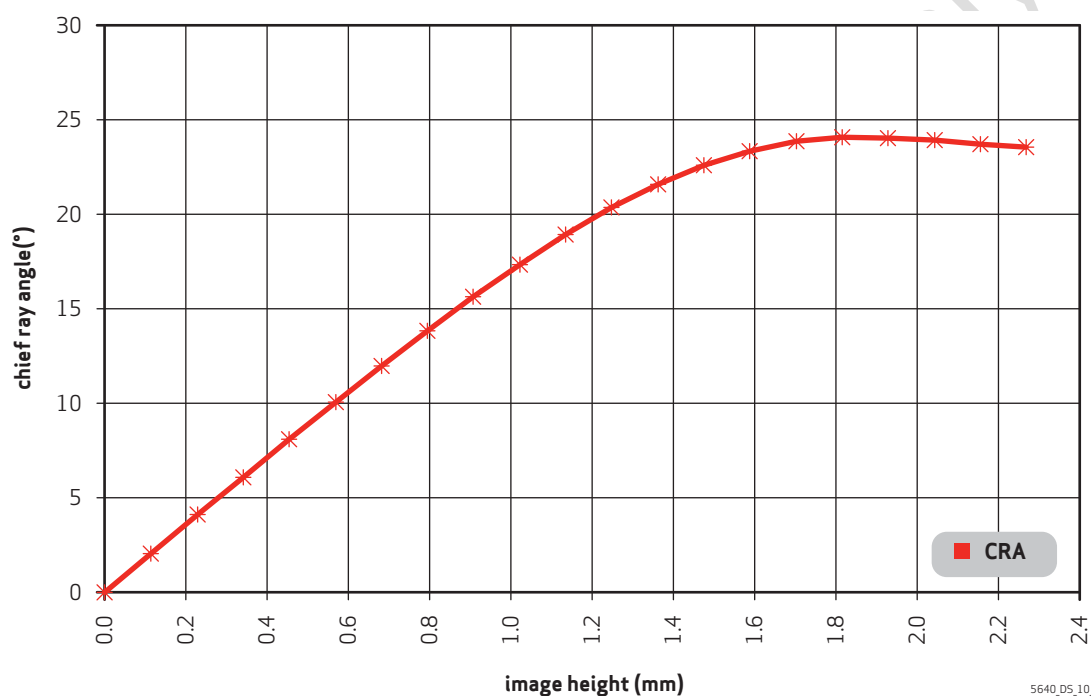


table 10-1 CRA versus image height plot (sheet 1 of 2)

field (%)	image height (mm)	CRA (degrees)
0	0	0
0.05	0.114	2.0
0.1	0.227	4.1
0.15	0.341	6.1
0.2	0.454	8.1
0.25	0.568	10.1
0.3	0.681	12.0
0.35	0.795	13.8
0.4	0.908	15.6
0.45	1.022	17.3

table 10-1 CRA versus image height plot (sheet 2 of 2)

field (%)	image height (mm)	CRA (degrees)
0.5	1.135	18.9
0.55	1.249	20.4
0.6	1.362	21.6
0.65	1.476	22.6
0.7	1.589	23.4
0.75	1.703	23.9
0.8	1.816	24.1
0.85	1.930	24.1
0.9	2.043	23.9
0.95	2.157	23.7
1	2.270	23.6

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the clear advantage™

OmniVision Technologies, Inc.

UNITED STATES

4275 Burton Drive
Santa Clara, CA 95054

tel: + 1 408 567 3000

fax: + 1 408 567 3001

email: salesamerican@ovt.com

UNITED KINGDOM

Hampshire + 44 1256 744 610

FINLAND

Mouhijärvi + 358 3 341 1898

GERMANY

Munich +49 89 63 81 99 88

CHINA

Beijing + 86 10 6580 1690

Shanghai + 86 21 6105 5100

Shenzhen + 86 755 8384 9733

Hong Kong + 852 2403 4011

JAPAN

Tokyo + 81 3 5765 6321

KOREA

Seoul + 82 2 3478 2812

SINGAPORE + 65 6562 8250

TAIWAN

Taipei + 886 2 2657 9800 -
ext.#100